2021 Index IEEE/ASME Transactions on Mechatronics Vol. 26

This index covers all technical items—papers, correspondence, reviews, etc.—that appeared in this periodical during 2021, and items from previous years that were commented upon or corrected in 2021. Departments and other items may also be covered if they have been judged to have archival value.

The Author Index contains the primary entry for each item, listed under the first author's name. The primary entry includes the coauthors' names, the title of the paper or other item, and its location, specified by the publication abbreviation, year, month, and inclusive pagination. The Subject Index contains entries describing the item under all appropriate subject headings, plus the first author's name, the publication abbreviation, month, and year, and inclusive pages. Note that the item title is found only under the primary entry in the Author Index.

Author Index

Α

- Abete, J.M., see Olaizola, J., TMECH Oct. 2021 2418-2428
- Abirami B, S., Sundarsingh, E.F., and Ramalingam, V.S., On-Body RF Sensor Toward Tremor Detection in Parkinson's Disease; *TMECH Oct. 2021 2814-*2817
- Abooee, A., see Sedghi, F., TMECH Oct. 2021 2517-2527
- Acharya, P., Nguyen, K., La, H.M., Liu, D., and Chen, I., Nonprehensile Manipulation: A Trajectory-Planning Perspective; *TMECH Feb. 2021 527-538*
- Afzal, M.R., see Haghjoo, M.R., TMECH Feb. 2021 13-23
- Agnus, J., see Tiwari, B., TMECH Aug. 2021 1837-1845
- Ahlers, D., Wasserfall, F., Hendrich, N., Bungener, A.N., Butt, J., and Zhang, J., Automated *In Situ* Placing of Metal Components Into 3-D Printed FFF Objects; *TMECH Aug. 2021 1886-1894*
- Ahmadabadi, M.N., see Sharbafi, M.A., TMECH Feb. 2021 335-346
- Ahn, C.K., see Wang, N., TMECH Dec. 2021 3198-3210
- Akhrif, O., see Khaled, T.A., TMECH June 2021 1646-1656
- Akiyama, T., see Shimonomura, S., TMECH Aug. 2021 2163-2173
- Al-Bahadly, I., see Rehan, M., TMECH Aug. 2021 1803-1811
- Alambeigi, F., see Sefati, S., TMECH Feb. 2021 369-380
- Alambeigi, F., see Ebrahimi, A., TMECH June 2021 1512-1523
- Alici, G., see Tawk, C., TMECH April 2021 876-887
- Angelico, B.A., see Toriumi, F.Y., TMECH Oct. 2021 2285-2293
- Antonelli, G., see He, W., TMECH April 2021 595-599
- Antonelli, G., see Simetti, E., TMECH June 2021 1635-1645
- Aphale, S.S., see Li, L., TMECH Feb. 2021 24-32
- Aphale, S.S., see Li, L., TMECH June 2021 1700
- Arefi, M.M., see Sedghi, F., TMECH Oct. 2021 2517-2527
- Argandona, E.S.d., see Olaizola, J., TMECH Oct. 2021 2418-2428
- Armand, M., see Sefati, S., TMECH Feb. 2021 369-380
- Asada, H.H., see Liu, S., TMECH Oct. 2021 2747-2757
- Asama, H., see Kasahara, J.Y.L., TMECH Dec. 2021 2826-2834
- Atienza, D., Bielza, C., Diaz-Rozo, J., and Larranaga, P., Efficient Anomaly Detection in a Laser-Surface Heat-Treatment Process via Laser-Spot Tracking; *TMECH Feb. 2021 405-415*
- Au, K.W.S., see Wang, Y., TMECH Aug. 2021 1858-1866
- Aukes, D.M., see Sharifzadeh, M., TMECH Feb. 2021 503-514
- Avci, E., see Rehan, M., TMECH Aug. 2021 1803-1811
- Axinte, D., see Ba, W., TMECH Dec. 2021 3010-3021
- Aydemir, G., see Demircali, A.A., TMECH Dec. 2021 2956-2966

B

- Ba, W., Dong, X., Mohammad, A., Wang, M., Axinte, D., and Norton, A., Design and Validation of a Novel Fuzzy-Logic-Based Static Feedback Controller for Tendon-Driven Continuum Robots; *TMECH Dec.* 2021 3010-3021
- Bai, M., see Li, Y., TMECH Dec. 2021 2977-2985
- Balbola, A.A., Kayed, M.O., Lou, E., and Moussa, W.A., Testing of a Strained Silicon Based 3-D Stress Sensor for Out-of-Plane Stress Measurements; *TMECH April 2021 1076-1083*
- Baldi, S., see Roy, S., TMECH Dec. 2021 3064-3075
- Bao, J., Wang, H., and Liu, P.X., Finite-Time Synchronization Control for Bilateral Teleoperation Systems With Asymmetric Time-Varying Delay and Input Dead Zone; *TMECH June 2021 1570-1580*
- Basin, M.V., see Wang, G., TMECH April 2021 789-797
- Beidl, C., see Vadamalu, R.S., TMECH Feb. 2021 381-392
- Ben-Tzvi, P., see Njaka, T., TMECH Oct. 2021 2339-2349
- Bergmann, L., see Liu, L., TMECH Aug. 2021 2080-2091
- Bernat, J., Kolota, J., and Rosset, S., Identification of a Nonlinear Dielectric Elastomer Actuator Based on the Harmonic Balance Method; *TMECH Oct.* 2021 2664-2675
- Bhushan, B.M., Yoon, J.Y., Griffith, L.G., and Trumper, D.L., Flux-Biased, Energy-Efficient Electromagnetic Micropumps Utilizing Bistable Magnetic Latching and Energy-Storage Springs; *TMECH Oct.* 2021 2362-2372
- Biagiotti, L., and Melchiorri, C., Optimization of Generalized S-Curve Trajectories for Residual Vibration Suppression and Compliance With Kinematic Bounds; *TMECH Oct. 2021 2724-2734*
- Bianchi, R.A.d.C., see Venancio, M.M., TMECH June 2021 1433-1444
- Bicchi, A., see Mengacci, R., TMECH Dec. 2021 3186-3197
- Bielza, C., see Atienza, D., TMECH Feb. 2021 405-415
- Birla, M., Duan, X., Li, H., Lee, M., Li, G., Wang, T.D., and Oldham, K.R., Image Processing Metrics for Phase Identification of a Multiaxis MEMS Scanner Used in Single Pixel Imaging; *TMECH June 2021 1445-1454*
- Blot, M., see Tiwari, B., TMECH Aug. 2021 1837-1845
- Bock, T., see Cheah, C.C., TMECH Dec. 2021 2819-2825
- Bonev, I.A., see Khaled, T.A., TMECH June 2021 1646-1656
- Bonfe, M., see Ferraguti, F., TMECH Feb. 2021 276-287
- Bortoluzzi, D., see Zanoni, C., TMECH Dec. 2021 3022-3030
- Bosso, A., Conficoni, C., Raggini, D., and Tilli, A., A Computational-Effective Field-Oriented Control Strategy for Accurate and Efficient Electric Propulsion of Unmanned Aerial Vehicles; *TMECH June 2021 1501-1511*
- Boulon, L., see Ivanov, V., TMECH June 2021 1195-1200
- Bracale, U., see Liu, H., TMECH Feb. 2021 393-404
- Brizzolara, S., see Njaka, T., TMECH Oct. 2021 2339-2349
- Bu, F., Xuan, F., Yang, Z., Gao, Y., Pan, Z., Degano, M., and Gerada, C., Rotor Position Tracking Control for Low Speed Operation of Direct-Drive PMSM Servo System ; *TMECH April 2021 1129-1139*
- Buchanan, S., and Sergi, F., Dynamic Modeling and State Estimation of Cable-Conduit Actuation During Interaction With Nonpassive Environments; *TMECH Oct. 2021 2462-2471*
- Bui, M.P., see Le, T., TMECH Feb. 2021 551-562
- Bungener, A.N., see Ahlers, D., TMECH Aug. 2021 1886-1894
- Burdette, E.C., see Li, G., TMECH Feb. 2021 255-266
- Butt, J., see Ahlers, D., TMECH Aug. 2021 1886-1894

С

Cai, C.J., Xiao, X., Kalairaj, M.S., Lee, I.J.J., Mugilvannan, A.K., Yeow, B.S., Tan, J.H., Huang, H., and Ren, H., Diversified and Untethered Motion Generation Via Crease Patterning from Magnetically Actuated Caterpillar-Inspired Origami Robot ; *TMECH June 2021 1678-1688*

- Cai, M., and Liao, W., Design, Modeling, and Experiments of Electromagnetic Energy Harvester Embedded in Smart Watch and Wristband as Power Source; *TMECH Aug. 2021 2104-2114*
- Campos, R., see Simetti, E., TMECH June 2021 1635-1645
- Cao, C., Chen, L., Duan, W., Hill, T.L., Li, B., Chen, G., Li, H., Li, Y., Wang, L., and Gao, X., On the Mechanical Power Output Comparisons of Cone Dielectric Elastomer Actuators; *TMECH Dec.* 2021 3151-3162
- Cao, D., see Sun, C., TMECH April 2021 600-610
- Cao, D., see Meng, Q., TMECH June 2021 1307-1317
- Cao, D., see Zeng, R., TMECH June 2021 1581-1590
- Cao, J., see Liu, W., TMECH Aug. 2021 1846-1857
- Cao, J., see Cheah, C.C., TMECH Dec. 2021 2819-2825
- Cao, K., see Li, D., TMECH April 2021 709-718
- Cao, L., Huang, T., Zhang, X., and Ding, H., Generative Adversarial Network for Prediction of Workpiece Surface Topography in Machining Stage; *TMECH Feb. 2021 480-490*
- Cao, Y., Huang, J., Ru, H., Chen, W., and Xiong, C., A Visual Servo-Based Predictive Control With Echo State Gaussian Process for Soft Bending Actuator ; *TMECH Feb. 2021 574-585*
- Cao, Y., and Dong, J., Self-Sensing and Control of Soft Electrothermal Actuator; TMECH April 2021 854-863
- Cao, Z., see Chen, S., TMECH Aug. 2021 1745-1753
- Carbone, G., see Orozco-Magdaleno, E.C., TMECH June 2021 1657-1667
- Carrera Akutain, X., see Lazcano, A.M., TMECH June 2021 1201-1211
- Caspers, L.W., see Shanbhag, V.V., TMECH Dec. 2021 3087-3103
- Castillo-Castaneda, E., see Orozco-Magdaleno, E.C., TMECH June 2021 1657-1667
- Catalano, M.G., see Mengacci, R., TMECH Dec. 2021 3186-3197
- Cenev, Z., Harischandra, P.A.D., Nurmi, S., Latikka, M., Hynninen, V., Ras, R., Timonen, J., and Zhou, Q., Ferrofluidic Manipulator: Automatic Manipulation of Nonmagnetic Microparticles at the Air–Ferrofluid Interface; *TMECH Aug. 2021 1932-1940*
- Cha, K., Chin, J., Park, S., Jung, Y., Lee, E., and Lim, M., Design Method for Reducing AC Resistance of Traction Motor Using High Fill Factor Coil to Improve the Fuel Economy of eBus; *TMECH June 2021 1260-1270*

Cha, Y., see Kim, H., TMECH Oct. 2021 2538-2547

- Chadli, M., see Wang, G., TMECH April 2021 789-797
- Chae, H., Park, G., Lee, J., Kim, K., Kim, T., Kim, H.S., and Seo, T., Façade Cleaning Robot With Manipulating and Sensing Devices Equipped on a Gondola; *TMECH Aug. 2021 1719-1727*
- Chai, L., see Lei, Z., TMECH Dec. 2021 3221-3231
- Chakrabarty, A., see Jeon, W., TMECH Aug. 2021 1941-1950
- Chan, J.L., see Lee, D., TMECH Aug. 2021 1923-1931
- Chao, Y., see Li, C.G., TMECH Oct. 2021 2263-2273
- Chatraei, A., see Shojaei, K., TMECH June 2021 1689-1699
- Che, Y., see Deng, Z., TMECH June 2021 1295-1306
- Cheah, C.C., see Muhammad, I., TMECH Dec. 2021 2845-2856
- Cheah, C.C., Bock, T., Cao, J., Linner, T., Liu, Y., Yamashita, A., and Yang, L., Guest Editorial Introduction to the Focused Section on Mechatronics and Automation for Constructions; *TMECH Dec.* 2021 2819-2825
- Chemori, A., see Tijjani, A.S., TMECH April 2021 897-907
- Chen, B., see Oncken, J., TMECH June 2021 1248-1259
- Chen, C.L.P., see Liu, Y., TMECH Feb. 2021 168-178
- Chen, D., see Guan, Y., TMECH April 2021 864-875
- Chen, F., see Chen, S., TMECH Aug. 2021 1745-1753
- Chen, F., Liu, K., Pan, Q., Chen, S., and Zhu, X., An Integrated Design and Fabrication Strategy for Planar Soft Dielectric Elastomer Actuators; *TMECH* Oct. 2021 2629-2640
- Chen, G., Dong, W., Sheng, X., Zhu, X., and Ding, H., An Active Sense and Avoid System for Flying Robots in Dynamic Environments; *TMECH April* 2021 668-678
- Chen, G., Hou, J., Dong, J., Li, Z., Gu, S., Zhang, B., Yu, J., and Knoll, A., Multiobjective Scheduling Strategy With Genetic Algorithm and Time-Enhanced A* Planning for Autonomous Parking Robotics in High-Density Unmanned Parking Lots; *TMECH June 2021 1547-1557*

Chen, G., see Cao, C., TMECH Dec. 2021 3151-3162

- Chen, H., Nie, R., Gu, J., Yan, S., and Zhao, R., Efficiency Optimization Strategy for Switched Reluctance Generator System With Position Sensorless Control; *TMECH Feb. 2021 469-479*
- Chen, H., see Meng, Q., TMECH June 2021 1307-1317
- Chen, H., see Gong, X., TMECH June 2021 1271-1282
- Chen, I., see Acharya, P., TMECH Feb. 2021 527-538
- Chen, I., see Dong, H., TMECH Aug. 2021 2215-2225
- Chen, J., Xu, K., and Ding, X., Roller-Skating of Mammalian Quadrupedal Robot With Passive Wheels Inspired by Human; *TMECH June 2021 1624-1634*
- Chen, J., see Du, H., TMECH June 2021 1455-1466
- Chen, J., Wu, C., Yu, G., Narang, D., and Wang, Y., Path Following of Wheeled Mobile Robots Using Online-Optimization-Based Guidance Vector Field; *TMECH Aug. 2021 1737-1744*
- Chen, J., Wang, J., Zhu, J., Lee, T.H., and de Silva, C.W., Unsupervised Cross-Domain Fault Diagnosis Using Feature Representation Alignment Networks for Rotating Machinery; *TMECH Oct. 2021 2770-2781*
- Chen, K., see Jin, L., TMECH Feb. 2021 90-101
- Chen, L., Zhu, Y., Ling, J., and Feng, Z., Development and Test of a Two-Dimensional Stacked Terfenol-D Actuator With High Bandwidth and Large Stroke; *TMECH Aug. 2021 1951-1959*
- Chen, L., see Zhou, W., TMECH Aug. 2021 1773-1781
- Chen, L., see Cao, C., TMECH Dec. 2021 3151-3162
- Chen, L., Huang, P., Li, Y., and Meng, Z., Edge-Dependent Efficient Grasp Rectangle Search in Robotic Grasp Detection; *TMECH Dec. 2021 2922-2931*
- Chen, M., see Shao, S., TMECH April 2021 689-699
- Chen, Q., see Zhou, W., TMECH Aug. 2021 1773-1781
- Chen, Q., see Zhang, C., TMECH Aug. 2021 2226-2236
- Chen, S., see Zeng, R., TMECH June 2021 1581-1590
- Chen, S., Stevenson, D.T., Yu, S., Mioskowska, M., Yi, J., Su, H., and Trkov, M., Wearable Knee Assistive Devices for Kneeling Tasks in Construction ; *TMECH Aug. 2021 1989-1996*
- Chen, S., Chen, F., Cao, Z., Wang, Y., Miao, Y., Gu, G., and Zhu, X., Topology Optimization of Skeleton-Reinforced Soft Pneumatic Actuators for Desired Motions; *TMECH Aug. 2021 1745-1753*
- Chen, S., see Chen, F., TMECH Oct. 2021 2629-2640
- Chen, S., Lin, F., Liang, C., and Liao, C., Development of FW and MTPV Control for SynRM via Feedforward Voltage Angle Control; *TMECH Dec.* 2021 3254-3264
- Chen, S., see Huo, X., TMECH Dec. 2021 2899-2909
- Chen, S., see Zhang, Z., TMECH Dec. 2021 3232-3242
- Chen, W., see Cao, Y., TMECH Feb. 2021 574-585
- Chen, W., see Liu, X., TMECH April 2021 1178-1182
- Chen, W., see Zhao, H., TMECH April 2021 645-656
- Chen, W., see Zhou, S., TMECH June 2021 1467-1478
- Chen, W., see Han, L., TMECH Aug. 2021 2016-2026
- Chen, W., see Huo, X., TMECH Dec. 2021 2899-2909
- Chen, X., see Tang, H., TMECH Feb. 2021 323-334
- Chen, X., see Li, Q., TMECH April 2021 679-688
- Chen, X., and Vanderborght, B., Focused Section on the Second Edition of TMECH/AIM Emerging Topics; *TMECH Aug. 2021 1705-1707*
- Chen, X., see Fu, Z., TMECH Oct. 2021 2688-2699
- Chen, X., see Lei, Z., TMECH Dec. 2021 3221-3231
- Chen, X., see Lei, Z., TMECH Dec. 2021 3221-3231
- Chen, Y., see Huang, Y., TMECH Feb. 2021 33-44
- Chen, Y., see Gan, C., TMECH April 2021 1118-1128
- Chen, Y., see Huang, Y., TMECH Aug. 2021 2174-2185
- Chen, Y., Paez-Granados, D.F., Leme, B., and Suzuki, K., Virtual Landmark-Based Control of Docking Support for Assistive Mobility Devices; *TMECH Aug. 2021 2007-2015*
- Chen, Y., see Li, Y., TMECH Dec. 2021 2977-2985
- Chen, Z., see Zhao, J., TMECH Feb. 2021 3-12
- Chen, Z., see Lin, Y., TMECH Aug. 2021 1905-1913
- Chen, Z., see Helian, B., TMECH Oct. 2021 2593-2603
- Cheng, B., see Zhang, H., TMECH Oct. 2021 2316-2326
- Cheng, L., see Li, H., TMECH April 2021 841-853

- Cheng, L.K., see Hashem, R., TMECH Oct. 2021 2327-2338
- Cheng, M., see Tsai, W., TMECH Feb. 2021 179-190
- Cheng, M., see Ding, R., TMECH Oct. 2021 2558-2569
- Cheng, P., see Long, F., TMECH Oct. 2021 2408-2417 Cheng, S., see Liao, H., TMECH April 2021 1172-1177
- Chin, J., see Hwang, S., TMECH April 2021 11/2-11/7 Chin, J., see Hwang, S., TMECH April 2021 1033-1042
- Chin, J., see Cha, K., *TMECH June 2021 1260-1270*
- Chiong, E., see Xiao, X., TMECH Oct. 2021 2483-2494
- Chiu, P.W.Y., see Du, X., TMECH June 2021 1524-1535
- Cho, B., see Oh, J., TMECH Feb. 2021 102-112
- Cho, J., see Lee, M., TMECH Feb. 2021 191-202
- Cho, K., see Kim, B., TMECH Dec. 2021 2932-2943
- Choi, B., see Lee, M., TMECH Feb. 2021 191-202
- Choi, H., see Lee, M., TMECH Feb. 2021 191-202
- Choi, H.R., see Song, S.H., TMECH Feb. 2021 267-275
- Choi, H.R., see Jung, H.S., TMECH April 2021 1002-1012
- Choi, H.R., see Phung, H., TMECH Oct. 2021 2495-2505
- Choi, M., see Seo, M., TMECH Aug. 2021 1812-1819
- Choi, Y., see Jamil, B., TMECH Dec. 2021 3243-3253
- Chun, P., and Hayashi, S., Development of a Concrete Floating and Delamination Detection System Using Infrared Thermography; *TMECH Dec. 2021* 2835-2844
- Chung, F., see Liu, C., TMECH Aug. 2021 1828-1836
- Chwa, D., see Jeong, S., TMECH April 2021 741-752
- Cibicik, A., see Tysse, G.O., TMECH Feb. 2021 416-426
- Clayton, G.M., see Mitrovic, A., TMECH June 2021 1412-1421
- Clevy, C., see Tiwari, B., TMECH Aug. 2021 1837-1845
- **Cocquempot, V.,** see Ma, Y., *TMECH April 2021 1161-1171*
- Cole, D., see Lazcano, A.M., *TMECH June 2021 1201-1211*
- Concari, C., see Dalboni, M., TMECH June 2021 1212-1224
- Conficoni, C., see Bosso, A., TMECH June 2021 1501-1511
- Cong, S., see Zhang, B., TMECH Oct. 2021 2396-2407
- Creuze, V., see Tijjani, A.S., TMECH April 2021 897-907
- Crispel, S., Garcia, P.L., Saerens, E., Varadharajan, A., Verstraten, T., Vanderborght, B., and Lefeber, D., A Novel Wolfrom-Based Gearbox for Robotic Actuators; *TMECH Aug. 2021 1980-1988*
- Cruz-Villar, C.A., see Mendoza-Trejo, O., TMECH Feb. 2021 347-357
- Csencsics, E., and Schitter, G., Exploring the Pareto Fronts of Actuation Technologies for High Performance Mechatronic Systems; *TMECH April 2021* 1053-1063
- Cui, C., see Tang, H., TMECH Feb. 2021 323-334

D

- Dai, H., see Yang, W., TMECH Feb. 2021 246-254
- Dai, J.S., see Fu, Z., TMECH Oct. 2021 2688-2699
- Dai, M., see Wu, J., TMECH June 2021 1369-1379
- Dai, X., see Gao, S., TMECH Feb. 2021 448-457
- Dalboni, M., Tavernini, D., Montanaro, U., Soldati, A., Concari, C., Dhaens, M., and Sorniotti, A., Nonlinear Model Predictive Control for Integrated Energy-Efficient Torque-Vectoring and Anti-Roll Moment Distribution ; *TMECH June 2021 1212-1224*
- Dambach, G., see Pozzato, G., TMECH April 2021 830-840
- de Silva, C.W., see Falch, L., TMECH Feb. 2021 124-133
- de Silva, C.W., see Chen, J., TMECH Oct. 2021 2770-2781
- Degano, M., see Bu, F., TMECH April 2021 1129-1139
- DeGroot, C.T., see Edmonds, B.P.R., TMECH April 2021 966-977
- Demircali, A.A., Varol, R., Aydemir, G., Saruhan, E.N., Erkan, K., and Uvet, H., Longitudinal Motion Modeling and Experimental Verification of a Microrobot Subject to Liquid Laminar Flow; *TMECH Dec. 2021 2956-2966*
- Deng, H., see Xiong, J., TMECH Dec. 2021 3211-3220
- Deng, J., Liu, Y., Zhang, S., and Li, J., Development of a Nanopositioning Platform With Large Travel Range Based on Bionic Quadruped Piezoelectric Actuator; *TMECH Aug. 2021 2059-2070*
- Deng, W., and Yao, J., Asymptotic Tracking Control of Mechanical Servosystems With Mismatched Uncertainties; *TMECH Aug. 2021 2204-2214* Deng, X., and Theore, T., TMECH Deng, 2021 2224-2214
- Deng, X., see Zhang, Z., TMECH Dec. 2021 3232-3242

- Deng, Z., see Sun, C., TMECH April 2021 600-610
- Deng, Z., see Wang, C., TMECH April 2021 908-917
- Deng, Z., Hu, X., Lin, X., Xu, L., Che, Y., and Hu, L., General Discharge Voltage Information Enabled Health Evaluation for Lithium-Ion Batteries; *TMECH June 2021 1295-1306*
- Dhaens, M., see Dalboni, M., TMECH June 2021 1212-1224
- Diaz-Rozo, J., see Atienza, D., TMECH Feb. 2021 405-415
- Diller, E., see Shokrollahi, P., TMECH Oct. 2021 2616-2628
- Ding, C., and Lu, L., A Tilting-Rotor Unmanned Aerial Vehicle for Enhanced Aerial Locomotion and Manipulation Capabilities: Design, Control, and Applications ; *TMECH Aug*, 2021 2237-2248
- Ding, H., see Cao, L., TMECH Feb. 2021 480-490
- Ding, H., see Xie, H., TMECH Feb. 2021 515-526
- Ding, H., see Chen, G., TMECH April 2021 668-678
- Ding, H., see Zhang, Y., TMECH April 2021 990-1001
- Ding, J., see Zhao, J., TMECH Aug. 2021 2038-2047
- Ding, R., Cheng, M., Zheng, S., and Xu, B., Sensor-Fault-Tolerant Operation for the Independent Metering Control System; *TMECH Oct. 2021 2558-2569*
- Ding, X., see Chen, J., TMECH June 2021 1624-1634
- Dinh, T.Q., see Nguyen, A., TMECH June 2021 1328-1338
- Divekar, N., see Zhu, H., TMECH Dec. 2021 3104-3115
- Dong, H., see Wang, Y., TMECH June 2021 1318-1327
- Dong, H., Weng, C., Guo, C., Yu, H., and Chen, I., Real-Time Avoidance Strategy of Dynamic Obstacles via Half Model-Free Detection and Tracking With 2D Lidar for Mobile Robots; *TMECH Aug. 2021 2215-2225*
- Dong, J., see Cao, Y., TMECH April 2021 854-863
- Dong, J., see Chen, G., TMECH June 2021 1547-1557
- Dong, M., see Tu, L., TMECH Feb. 2021 156-167
- Dong, M., Fan, W., Li, J., Zhou, X., Rong, X., Kong, Y., and Zhou, Y., A New Ankle Robotic System Enabling Whole-Stage Compliance Rehabilitation Training; *TMECH June 2021 1490-1500*
- Dong, W., see Chen, G., TMECH April 2021 668-678
- Dong, X., Song, P., Wang, X., Fan, Q., and Liu, X., Robotic Prototyping of Paper-Based Field-Effect Transistors With Rolled-Up Semiconductor Microtubes; *TMECH Feb. 2021 427-436*
- Dong, X., see Ba, W., TMECH Dec. 2021 3010-3021
- Dong, X., see Shi, C., TMECH Dec. 2021 3076-3086
- Du, H., see Tu, L., TMECH Feb. 2021 156-167
- Du, H., Wang, L., Chen, J., Huang, H., and Feng, X., Integral Sliding-Mode Tracking Control for Heavy Vehicle Electrohydraulic Power Steering System; *TMECH June 2021 1455-1466*
- Du, L., see Liu, X., TMECH April 2021 1178-1182
- Du, R., see Zhong, Y., TMECH Dec. 2021 2998-3009
- Du, X., Zhang, M., Yu, J., Yang, L., Chiu, P.W.Y., and Zhang, L., Design and Real-Time Optimization for a Magnetic Actuation System With Enhanced Flexibility; *TMECH June 2021 1524-1535*
- Du, Z., see Wang, H., TMECH April 2021 1022-1032
- Duan, H., and Zhang, D., A Binary Tree Based Coordination Scheme for Target Enclosing With Micro Aerial Vehicles; *TMECH Feb. 2021 458-468*
- Duan, W., see Cao, C., TMECH Dec. 2021 3151-3162
- Duan, X., see Birla, M., TMECH June 2021 1445-1454
- Dumanli, A., and Sencer, B., Data-Driven Iterative Trajectory Shaping for Precision Control of Flexible Feed Drives; *TMECH Oct. 2021 2735-2746*

E

- Ebrahimi, A., Alambeigi, F., Sefati, S., Patel, N., He, C., Gehlbach, P., and Iordachita, I., Stochastic Force-Based Insertion Depth and Tip Position Estimations of Flexible FBG-Equipped Instruments in Robotic Retinal Surgery; *TMECH June 2021 1512-1523*
- Edmonds, B.P.R., DeGroot, C.T., and Trejos, A.L., Thermal Modeling and Characterization of Twisted Coiled Actuators for Upper Limb Wearable Devices; *TMECH April 2021 966-977*
- Egeland, O., see Tysse, G.O., TMECH Feb. 2021 416-426
- Eizad, A., see Haghjoo, M.R., TMECH Feb. 2021 13-23
- Endo, H., see Tanabe, T., TMECH Feb. 2021 203-213

Erkan, K., see Demircali, A.A., TMECH Dec. 2021 2956-2966

- Escalante, F.M., Jutinico, A.L., Jaimes, J.C., Terra, M.H., and Siqueira, A.A.G., Markovian Robust Filtering and Control Applied to Rehabilitation Robotics ; *TMECH Feb. 2021 491-502*
- Eshghi, A.T., see Jung, H.J., TMECH Aug. 2021 1708-1718
- Esteban, E., see Olaizola, J., TMECH Oct. 2021 2418-2428
- Eun, Y., see Jeon, H., TMECH June 2021 1401-1411

F

- Falch, L., and de Silva, C.W., Incorporating the Qualitative Variable Comfort Into the Design of a Wearable Body Sensor System; *TMECH Feb. 2021 124-133*
- Fallaha, C., Saad, M., Ghommam, J., and Kali, Y., Sliding Mode Control With Model-Based Switching Functions Applied on a 7-DOF Exoskeleton Arm; *TMECH Feb. 2021 539-550*
- Fan, Q., see Dong, X., TMECH Feb. 2021 427-436
- Fan, R., and Li, Y., An Adaptive Fuzzy Trajectory Tracking Control via Improved Cerebellar Model Articulation Controller for Electro-Hydraulic Shovel; *TMECH Dec. 2021 2870-2880*

Fan, W., see Dong, M., TMECH June 2021 1490-1500

- Fang, G., see Scharff, R.B.N., TMECH Aug. 2021 1877-1885
- Fang, J., see Shimonomura, S., TMECH Aug. 2021 2163-2173
- Fang, Z., see Liu, S., TMECH Oct. 2021 2747-2757
- Fantuzzi, C., see Ferraguti, F., TMECH Feb. 2021 276-287
- Farivar, F., Haghighi, M.S., Jolfaei, A., and Wen, S., Covert Attacks Through Adversarial Learning: Study of Lane Keeping Attacks on the Safety of Autonomous Vehicles; *TMECH June 2021 1350-1357*
- Fei, R., see Xie, G., TMECH April 2021 633-644
- Feng, X., see Du, H., TMECH June 2021 1455-1466
- Feng, Z., see Chen, L., TMECH Aug. 2021 1951-1959
- Ferraguti, F., Bonfe, M., Fantuzzi, C., and Secchi, C., Optimized Power Modulation in Wave-Based Bilateral Teleoperation; *TMECH Feb. 2021 276-287*
- Ferrentino, P., see Liu, H., TMECH Feb. 2021 393-404
- Ficuciello, F., see Liu, H., TMECH Feb. 2021 393-404
- Fischer, G.S., see Li, G., TMECH Feb. 2021 255-266
- Foong, S., see Lee, D., TMECH Aug. 2021 1923-1931
- Fouka, M., Sentouh, C., and Popieul, J., Quasi-LPV Interconnected Observer Design for Full Vehicle Dynamics Estimation With Hardware Experiments; *TMECH Aug. 2021 1763-1772*
- Frazelle, C.G., see Wang, C., TMECH April 2021 777-788
- Fu, M., see Wang, C., TMECH April 2021 908-917
- Fu, Z., Pan, J., Spyrakos-Papastavridis, E., Lin, Y., Zhou, X., Chen, X., and Dai, J.S., A Lie-Theory-Based Dynamic Parameter Identification Methodology for Serial Manipulators; *TMECH Oct.* 2021 2688-2699
- Fujie, M.G., see Miura, S., TMECH April 2021 1013-1021
- Fujii, H., see Kasahara, J.Y.L., TMECH Dec. 2021 2826-2834
- Fukuda, T., see He, W., TMECH April 2021 595-599

G

- G. Zhu, G., see Pal, A., TMECH Dec. 2021 3116-3127
- Galdos, L., see Olaizola, J., TMECH Oct. 2021 2418-2428
- Gan, C., Chen, Y., Sun, Q., Si, J., Wu, J., and Hu, Y., A Position Sensorless Torque Control Strategy for Switched Reluctance Machines With Fewer Current Sensors; *TMECH April 2021 1118-1128*
- Gangireddy, R., see Megalingam, R.K., TMECH Feb. 2021 288-299
- Gao, H., see Kuang, Z., TMECH Feb. 2021 358-368
- Gao, J., Zhang, Z., and Yan, G., Locomotion Analysis of a Clamper-Based Capsule Robot in a Compliant Tube; *TMECH Feb. 2021 55-65*
- Gao, J., see Tang, H., TMECH Feb. 2021 323-334
- Gao, S., Tian, G., Dai, X., Zhang, Q., Wang, Z., Yang, X., Wang, Q., and Jia, N., A Lightweight Wireless Overpressure Node Based Efficient Monitoring for Shock Waves; *TMECH Feb. 2021 448-457*
- Gao, S., Mai, J., Zhu, J., and Wang, Q., Mechanism and Controller Design of a Transfemoral Prosthesis With Electrohydraulic Knee and Motor-Driven Ankle; *TMECH Oct. 2021 2429-2439*

- Gao, X., see Cao, C., TMECH Dec. 2021 3151-3162
- Gao, Y., see Bu, F., TMECH April 2021 1129-1139
- Gao, Y., Zhang, X., Zhu, C., and Guo, B., Global Parameter Sensitivity Analysis of Electrochemical Model for Lithium-Ion Batteries Considering Aging; *TMECH June 2021 1283-1294*
- Garabini, M., see Mengacci, R., TMECH Dec. 2021 3186-3197
- Garcia, P.L., see Crispel, S., TMECH Aug. 2021 1980-1988
- Garcia, R., see Simetti, E., TMECH June 2021 1635-1645
- Garratt, M.A., see Tran, V.P., TMECH Oct. 2021 2306-2315
- Ge, S.S., see Liu, X., TMECH Dec. 2021 2888-2898
- Gehlbach, P., see Ebrahimi, A., TMECH June 2021 1512-1523
- Gerada, C., see Bu, F., TMECH April 2021 1129-1139
- Geraedts, J.M.P., see Scharff, R.B.N., TMECH Aug. 2021 1877-1885
- Gerber, M.J., Hubschman, J., and Tsao, T., Automated Retinal Vein Cannulation on Silicone Phantoms Using Optical-Coherence-Tomography-Guided Robotic Manipulations; *TMECH Oct. 2021 2758-2769*
- Ghaffari, A., Analytical Design and Experimental Verification of Geofencing Control for Aerial Applications; *TMECH April 2021 1106-1117*
- Ghanta, S., see Megalingam, R.K., TMECH Feb. 2021 288-299
- Ghommam, J., see Fallaha, C., TMECH Feb. 2021 539-550
- Giudice, G.D., Orekhov, A.L., Shen, J., Joos, K.M., and Simaan, N., Investigation of Micromotion Kinematics of Continuum Robots for Volumetric OCT and OCT-Guided Visual Servoing; *TMECH Oct. 2021 2604-2615*
- Goldfarb, M., see Vailati, L.G., TMECH Feb. 2021 235-245
- Gomez-Bravo, F., see Orozco-Magdaleno, E.C., TMECH June 2021 1657-1667
- Gonalves, R.S., see Venancio, M.M., TMECH June 2021 1433-1444
- Gong, J., see Li, Z., TMECH June 2021 1339-1349
- Gong, X., Wang, J., Ma, B., Lu, L., Hu, Y., and Chen, H., Real-Time Integrated Power and Thermal Management of Connected HEVs Based on Hierarchical Model Predictive Control; *TMECH June 2021 1271-1282*
- Gregg, R.D., see Zhu, H., TMECH Dec. 2021 3104-3115
- Griffith, L.G., see Bhushan, B.M., TMECH Oct. 2021 2362-2372
- Grioli, G., see Mengacci, R., TMECH Dec. 2021 3186-3197
- Gu, D., see Wong, C., TMECH Oct. 2021 2294-2305
- Gu, G., see Chen, S., TMECH Aug. 2021 1745-1753
- Gu, G., see Huang, X., TMECH Dec. 2021 3175-3185
- Gu, J., see Chen, H., TMECH Feb. 2021 469-479
- Gu, S., see Chen, G., TMECH June 2021 1547-1557
- Gu, S., see Zhu, H., TMECH Oct. 2021 2712-2723
- Gu, X., see Xiao, X., TMECH Oct. 2021 2483-2494
- Guan, Y., Zeng, Z., Chen, D., Zhang, T., Zhu, H., and He, L., Kinematic Modeling, Analysis, and Verification of an Essboard-Like Robot; *TMECH April* 2021 864-875
- Guan, Y., see Zhu, H., TMECH Oct. 2021 2712-2723
- Guerra, T., see Nguyen, A., TMECH June 2021 1328-1338
- Gundelsweiler, B., see Raab, M., TMECH June 2021 1380-1391
- Guo, B., see Gao, Y., TMECH June 2021 1283-1294
- Guo, C., see Dong, H., TMECH Aug. 2021 2215-2225
- Guo, H., see Meng, Q., TMECH June 2021 1307-1317
- Guo, J., Wang, J., Luo, Y., and Li, K., Takagi–Sugeno Fuzzy-Based Robust *H*∞ Integrated Lane-Keeping and Direct Yaw Moment Controller of Unmanned Electric Vehicles; *TMECH Aug. 2021 2151-2162*
- Guo, K., see Xu, Y., TMECH Aug. 2021 2249-2260
- Guo, P., see Zhong, Y., TMECH Dec. 2021 2998-3009
- Guo, Q., Li, X., Zuo, Z., Shi, Y., and Jiang, D., Quasi-Synchronization Control of Multiple Electrohydraulic Actuators With Load Disturbance and Uncertain Parameters; *TMECH Aug. 2021 2048-2058*
- Guo, S., see Zhou, Q., TMECH June 2021 1225-1235
- Guo, X., see Zhou, Q., TMECH June 2021 1225-1235

H

- Haghighi, M.S., see Farivar, F., TMECH June 2021 1350-1357
- Haghjoo, M.R., Lee, H., Afzal, M.R., Eizad, A., and Yoon, J., Mech-Walker:A Novel Single-DOF Linkage Device With Movable Frame for Gait Rehabilitation; *TMECH Feb. 2021 13-23*
- Han, D., see Wang, T., TMECH April 2021 1183-1188

- Han, L., Wang, H., Liu, Z., Chen, W., and Zhang, X., Vision-Based Cutting Control of Deformable Objects With Surface Tracking; *TMECH Aug. 2021* 2016-2026
- Han, Q., see Wang, J., TMECH Feb. 2021 311-322
- Handroos, H., see Malysheva, J., TMECH Oct. 2021 2385-2395
- Hang, P., see Huang, C., TMECH April 2021 611-620
- Hangai, S., see Sariyildiz, E., TMECH Aug. 2021 2139-2150
- Harada, N., see Shen, Y., TMECH Oct. 2021 2350-2361
- Harischandra, P.A.D., see Cenev, Z., TMECH Aug. 2021 1932-1940
- Hashem, R., Stommel, M., Cheng, L.K., and Xu, W., Design and Characterization of a Bellows-Driven Soft Pneumatic Actuator; *TMECH Oct. 2021* 2327-2338
- Hata, N., see Kato, T., TMECH Oct. 2021 2451-2461
- Hayashi, S., see Chun, P., TMECH Dec. 2021 2835-2844
- He, C., see Ebrahimi, A., TMECH June 2021 1512-1523
- He, G., see Li, J., TMECH June 2021 1591-1601
- He, J., see Zhou, W., TMECH Aug. 2021 1773-1781
- He, L., see Wang, Y., TMECH April 2021 719-729
- He, L., see Guan, Y., TMECH April 2021 864-875
- He, S., see Tang, H., TMECH Feb. 2021 323-334
- He, W., Li, Z., Meurer, T., Antonelli, G., Kaynak, O., and Fukuda, T., Guest Editorial Focused Section on Mechatronics in Unmanned Systems; *TMECH April 2021 595-599*
- Hegeman, R., see Sefati, S., TMECH Feb. 2021 369-380
- Hei, X., see Xie, G., TMECH April 2021 633-644
- Helian, B., Chen, Z., Yao, B., Lyu, L., and Li, C., Accurate Motion Control of a Direct-Drive Hydraulic System With an Adaptive Nonlinear Pump Flow Compensation; *TMECH Oct.* 2021 2593-2603
- Hendrich, N., see Ahlers, D., TMECH Aug. 2021 1886-1894
- Hill, T.L., see Cao, C., TMECH Dec. 2021 3151-3162
- Hithiksha, K., see Vikrant, K.S., TMECH April 2021 798-806
- Ho, Y., see Liu, C., TMECH Aug. 2021 1828-1836
- Hoang, P.T., see Phung, H., TMECH Oct. 2021 2495-2505
- Holley, J., see Thomas, G.C., TMECH Feb. 2021 586-591
- Hong, S., Jang, K., Kim, S., and Park, J., Regularized Hierarchical Quadratic Program for Real-Time Whole-Body Motion Generation; *TMECH Aug.* 2021 2115-2126
- Hong, Z., see Liu, L., TMECH Aug. 2021 2080-2091
- Hori, M., see Takeyama, T., TMECH Dec. 2021 2881-2887
- Hossain, N.A., Yamomo, G.G., Willing, R., and Towfighian, S., Characterization of a Packaged Triboelectric Harvester Under Simulated Gait Loading for Total Knee Replacement; *TMECH Dec.* 2021 2967-2976
- Hosseinabadi, A.H.H., and Salcudean, S.E., UltraLow Noise, High Bandwidth, Low Latency, No Overload 6-Axis Optical Force Sensor; *TMECH Oct. 2021* 2581-2592
- Hosseini, M., see Rodriguez, A.S., TMECH Oct. 2021 2791-2802
- Hou, C., see Liu, F., TMECH Feb. 2021 113-123
- Hou, J., see Shao, S., TMECH April 2021 689-699
- Hou, J., see Chen, G., TMECH June 2021 1547-1557
- Hu, C., see Yang, W., TMECH Feb. 2021 246-254
- Hu, C., see Wang, Z., TMECH Oct. 2021 2274-2284
- Hu, L., see Deng, Z., TMECH June 2021 1295-1306
- Hu, X., see Ivanov, V., TMECH June 2021 1195-1200
- Hu, X., see Deng, Z., TMECH June 2021 1295-1306
- Hu, X., see Liu, K., TMECH Dec. 2021 2944-2955
- Hu, Y., see Zhao, B., TMECH April 2021 943-954
- Hu, Y., see Gan, C., TMECH April 2021 1118-1128
- Hu, Y., see Gong, X., TMECH June 2021 1271-1282
- Huang, C., Lv, C., Hang, P., and Xing, Y., Toward Safe and Personalized Autonomous Driving: Decision-Making and Motion Control With DPF and CDT Techniques; *TMECH April 2021 611-620*
- Huang, H., see Tu, L., TMECH Feb. 2021 156-167
- Huang, H., see Cai, C.J., TMECH June 2021 1678-1688
- Huang, H., see Du, H., TMECH June 2021 1455-1466
- Huang, J., see Cao, Y., TMECH Feb. 2021 574-585
- Huang, J., see Li, L., TMECH Feb. 2021 24-32
- Huang, J., see Li, L., TMECH June 2021 1700

- Huang, P., see Ma, Z., TMECH Oct. 2021 2472-2482
- Huang, P., see Chen, L., TMECH Dec. 2021 2922-2931
- Huang, Q., see Li, Q., TMECH April 2021 679-688
- Huang, R., see Li, J., TMECH June 2021 1591-1601
- Huang, T., see Cao, L., TMECH Feb. 2021 480-490
- Huang, T., see Song, Y., TMECH Dec. 2021 2986-2997
- Huang, W., Zhao, J., Yu, G., and Wong, P.K., Intelligent Vibration Control for Semiactive Suspension Systems Without Prior Knowledge of Dynamical Nonlinear Damper Behaviors Based on Improved Extreme Learning Machine; *TMECH Aug. 2021 2071-2079*
- Huang, X., Zou, J., and Gu, G., Kinematic Modeling and Control of Variable Curvature Soft Continuum Robots; *TMECH Dec. 2021 3175-3185*
- Huang, Y., Wang, F., Li, A., Shi, Y., and Chen, Y., Development and Performance Enhancement of an Overactuated Autonomous Ground Vehicle; *TMECH Feb. 2021 33-44*
- Huang, Y., Chen, Y., Zhang, X., Zhang, H., Song, C., and Ota, J., A Novel Cable-Driven 7-DOF Anthropomorphic Manipulator; *TMECH Aug. 2021* 2174-2185
- Huang, Y., see Zhang, C., TMECH Aug. 2021 2226-2236
- Huber, L., see Shokrollahi, P., TMECH Oct. 2021 2616-2628
- Hubschman, J., see Gerber, M.J., TMECH Oct. 2021 2758-2769
- Huo, X., Wang, B., Chen, S., and Chen, W., Sensorless Unbalance Diagnosis of Affiliated Rotating Chamber Based on Driving Current of Permanent Magnet Synchronous Motor; *TMECH Dec.* 2021 2899-2909
- Hutter, M., see Raab, M., TMECH June 2021 1380-1391
- Hwang, D., see Lee, J., TMECH Aug. 2021 1820-1827
- Hwang, D., see Lim, B., TMECH Aug. 2021 1728-1736
- Hwang, D., see Jang, N., TMECH Aug. 2021 1867-1876
- Hwang, S., Chin, J., and Lim, M., Design Process and Verification of SPMSM for a Wearable Robot Considering Thermal Characteristics Through LPTN; *TMECH April 2021 1033-1042*
- Hwang, S.T., see Jung, H.S., TMECH April 2021 1002-1012
- Hwu, E., see Liao, H., TMECH April 2021 1172-1177
- Hynninen, V., see Cenev, Z., TMECH Aug. 2021 1932-1940
- Hyung, S., see Lee, M., TMECH Feb. 2021 191-202

I

- Ibrahim, K., see Xiong, J., TMECH Dec. 2021 3211-3220
- Iizuka, A., see Takeyama, T., TMECH Dec. 2021 2881-2887
- in het Panhuis, M., see Tawk, C., TMECH April 2021 876-887
- Ino, S., see Tanabe, T., TMECH Feb. 2021 203-213
- Iordachita, I., see Sefati, S., TMECH Feb. 2021 369-380
- Iordachita, I., see Ebrahimi, A., TMECH June 2021 1512-1523
- Iturrospe, A., see Olaizola, J., TMECH Oct. 2021 2418-2428
- Ivanov, V., Lv, C., Boulon, L., Hu, X., and Ongel, A., Guest Editorial: Focused Section on Mechatronics in Road Mobility Systems; *TMECH June 2021* 1195-1200
- Iwata, H., see Tanabe, T., TMECH Feb. 2021 203-213
- Iwata, H., see Kamezaki, M., TMECH Dec. 2021 2857-2869

J

- Jaimes, J.C., see Escalante, F.M., TMECH Feb. 2021 491-502
- Jamil, B., and Choi, Y., Modified Stiffness-Based Soft Optical Waveguide Integrated Pneumatic Artificial Muscle (PAM) Actuators for Contraction and Force Sensing; *TMECH Dec. 2021 3243-3253*
- Jang, I., see Lee, S.J., TMECH April 2021 765-776
- Jang, K., see Hong, S., TMECH Aug. 2021 2115-2126
- Jang, N., Lee, M.W., and Hwang, D., A Suction-Based Peripheral Nerve Gripper Capable of Controlling the Suction Force; *TMECH Aug. 2021 1867-1876* Jayanth, G.R., see Vikrant, K.S., *TMECH April 2021 798-806*
- Jayantii, G.K., see vikiant, K.S., *TWECH April 2021* 790-00
- Jeon, H., Song, J., Lee, H., and Eun, Y., Modeling Quadrotor Dynamics in a Wind Field; *TMECH June 2021 1401-1411*
- Jeon, W., Chakrabarty, A., Zemouche, A., and Rajamani, R., Simultaneous State Estimation and Tire Model Learning for Autonomous Vehicle Applications; *TMECH Aug. 2021 1941-1950*

- Jeong, S., and Chwa, D., Sliding-Mode-Disturbance-Observer-Based Robust Tracking Control for Omnidirectional Mobile Robots With Kinematic and Dynamic Uncertainties; *TMECH April 2021 741-752*
- Jeong, U., see Kim, B., TMECH Dec. 2021 2932-2943
- Ji, J., see Zhang, Y., TMECH June 2021 1668-1677
- Ji, W., see Xie, G., TMECH April 2021 633-644
- Jia, M., see She, D., TMECH Oct. 2021 2440-2450
- Jia, N., see Gao, S., TMECH Feb. 2021 448-457
- Jia, Z., see Ma, J., TMECH April 2021 730-740
- **Jiang, B.,** see Ma, Y., *TMECH April 2021 1161-1171*
- Jiang, C., see Xie, H., TMECH Feb. 2021 515-526
- Jiang, D., see Guo, Q., TMECH Aug. 2021 2048-2058
- Jiang, N., Zhang, S., Xu, J., and Zhang, D., Model-Free Control of Flexible Manipulator Based on Intrinsic Design; *TMECH Oct. 2021 2641-2652*
- Jiang, W., see Pang, X., TMECH Aug. 2021 2027-2037
- Jiang, Y., see Wu, J., TMECH June 2021 1369-1379
- Jiang, Y., see Li, F., TMECH Oct. 2021 2676-2687
- Jiang, Z., see Xia, J., TMECH Oct. 2021 2803-2813
- Jiao, S., see Tan, Q., TMECH April 2021 621-632
- Jie, W., see Kim, J., TMECH Aug. 2021 1782-1790
- Jin, J., see Zhao, C., TMECH Feb. 2021 437-447
- Jin, L., Xie, Z., Liu, M., Chen, K., Li, C., and Yang, C., Novel Joint-Drift-Free Scheme at Acceleration Level for Robotic Redundancy Resolution With Tracking Error Theoretically Eliminated; *TMECH Feb. 2021 90-101*
- Jo, G., see Kim, H., TMECH Oct. 2021 2538-2547
- Jolfaei, A., see Farivar, F., TMECH June 2021 1350-1357
- Joos, K.M., see Giudice, G.D., TMECH Oct. 2021 2604-2615
- Jung, H., see Phung, H., TMECH Oct. 2021 2495-2505
- Jung, H.J., Eshghi, A.T., and Lee, S., Structural Failure Detection Using Wireless Transmission Rate From Piezoelectric Energy Harvesters; *TMECH Aug.* 2021 1708-1718
- Jung, H.S., Phung, H., Park, J.H., Yang, S.Y., Kim, K., Ko, J.U., Hwang, S.T., and Choi, H.R., Development of a Small and Lightweight Missile Fin Control Actuation System Driven by Novel Dielectric Elastomer Actuators; *TMECH April 2021 1002-1012*
- Jung, Y., see Cha, K., TMECH June 2021 1260-1270
- Jutinico, A.L., see Escalante, F.M., TMECH Feb. 2021 491-502

K

Kakogawa, A., Kawabata, T., and Ma, S., Plate-Springed Parallel Elastic Actuator for Efficient Snake Robot Movement; *TMECH Dec. 2021 3051-3063*

Kalairaj, M.S., see Cai, C.J., TMECH June 2021 1678-1688

Kali, Y., see Fallaha, C., TMECH Feb. 2021 539-550

- Kamezaki, M., Iwata, H., and Sugano, S., Basic Input–Output Gain Tuning System Based on Control Input Histogram Leveling for Human-Operated Machines; *TMECH Dec. 2021 2857-2869*
- Kamper, D.G., see Vertongen, J., TMECH April 2021 955-965

Kang, B.B., see Kim, B., TMECH Dec. 2021 2932-2943

Kang, Y., see Zeng, R., TMECH June 2021 1581-1590

- Karami, F., Wu, L., and Tadesse, Y., Modeling of One-Ply and Two-Ply Twisted and Coiled Polymer Artificial Muscles; TMECH Feb. 2021 300-310
- Kasaei, S.H., OrthographicNet: A Deep Transfer Learning Approach for 3-D Object Recognition in Open-Ended Domains; *TMECH Dec. 2021 2910-2921*
- Kasahara, J.Y.L., Fujii, H., Yamashita, A., and Asama, H., Weakly Supervised Acoustic Defect Detection in Concrete Structures Using Clustering-Based Augmentation; *TMECH Dec.* 2021 2826-2834
- Katagiri, S., see Shen, Y., TMECH Oct. 2021 2350-2361
- Kato, T., King, F., Takagi, K., and Hata, N., Robotized Catheter With Enhanced Distal Targeting for Peripheral Pulmonary Biopsy; *TMECH Oct. 2021 2451-2461*
- Kawabata, T., see Kakogawa, A., TMECH Dec. 2021 3051-3063
- Kayed, M.O., see Balbola, A.A., TMECH April 2021 1076-1083
- Kaynak, O., see He, W., TMECH April 2021 595-599

Kaynak, O., see Sedghi, F., TMECH Oct. 2021 2517-2527

Kazanzides, P., see Sefati, S., TMECH Feb. 2021 369-380

- Kazemy, A., see Shojaei, K., TMECH June 2021 1689-1699
- Kazi, A., see Raab, M., TMECH June 2021 1380-1391
- Khaled, T.A., Akhrif, O., and Bonev, I.A., Dynamic Path Correction of an Industrial Robot Using a Distance Sensor and an ADRC Controller; *TMECH* June 2021 1646-1656
- Khanuja, H., see Sefati, S., TMECH Feb. 2021 369-380
- Kim, B., Jeong, U., Kang, B.B., and Cho, K., Slider-Tendon Linear Actuator With Under-Actuation and Fast-Connection for Soft Wearable Robots; *TMECH Dec. 2021 2932-2943*
- Kim, D., see Lee, S.J., TMECH April 2021 765-776
- Kim, H., Lee, K., Jo, G., Kim, J., Lim, M.T., and Cha, Y., Tendon-Inspired Piezoelectric Sensor for Biometric Application; *TMECH Oct. 2021 2538-2547*
- Kim, H.H., see Kim, J., TMECH Aug. 2021 1782-1790
- Kim, H.J., see Lee, S.J., TMECH April 2021 765-776
- Kim, H.S., see Chae, H., TMECH Aug. 2021 1719-1727
- Kim, H.S., see Seo, M., TMECH Aug. 2021 1812-1819
- Kim, H.S., see Yoo, S., TMECH Aug. 2021 1754-1762
- Kim, J., see Lee, M., TMECH Feb. 2021 191-202
- Kim, J., see Lee, S.J., TMECH April 2021 765-776
- Kim, J., see Lee, J., TMECH Aug. 2021 1820-1827
- Kim, J., Jie, W., Kim, H.H., and Lee, M.C., Modified Configuration Control With Potential Field for Inverse Kinematic Solution of Redundant Manipulator; *TMECH Aug. 2021 1782-1790*
- Kim, J., see Kim, H., TMECH Oct. 2021 2538-2547
- Kim, K., see Jung, H.S., TMECH April 2021 1002-1012
- Kim, K., see Chae, H., TMECH Aug. 2021 1719-1727
- Kim, S., see Hong, S., TMECH Aug. 2021 2115-2126
- Kim, T., see Chae, H., TMECH Aug. 2021 1719-1727
- Kim, T., see Yoo, S., TMECH Aug. 2021 1754-1762
- King, F., see Kato, T., TMECH Oct. 2021 2451-2461
- Knoll, A., see Chen, G., TMECH June 2021 1547-1557
- Ko, J.U., see Jung, H.S., TMECH April 2021 1002-1012
- Kobayashi, Y., see Miura, S., TMECH April 2021 1013-1021
- Kolota, J., see Bernat, J., TMECH Oct. 2021 2664-2675
- Kommuri, S.K., Park, Y., and Lee, S.B., Online Compensation of Mechanical Load Defects With Composite Control in PMSM Drives; *TMECH June 2021* 1392-1400
- Kong, L., see Li, D., TMECH April 2021 709-718
- Kong, X., see Zhang, Z., TMECH Aug. 2021 1997-2006
- Kong, Y., see Dong, M., TMECH June 2021 1490-1500
- Kuang, Z., Gao, H., and Tomizuka, M., Precise Linear-Motor Synchronization Control via Cross-Coupled Second-Order Discrete-Time Fractional-Order Sliding Mode; *TMECH Feb. 2021 358-368*
- Kumar, K.S., see Megalingam, R.K., TMECH Feb. 2021 288-299
- Kuruppu, S.S., and Zou, Y., Static Position Sensor Bias Fault Diagnosis in Permanent Magnet Synchronous Machines via Current Estimation; *TMECH April 2021 888-896*

L

- La, H.M., see Acharya, P., TMECH Feb. 2021 527-538
- Lai, Y.P., see Shokrollahi, P., TMECH Oct. 2021 2616-2628
- Lamarque, F., see Tisnes, S.D., TMECH June 2021 1422-1432
- Lang, X., see Liu, W., TMECH Aug. 2021 1846-1857
- Larranaga, P., see Atienza, D., TMECH Feb. 2021 405-415
- Latikka, M., see Cenev, Z., TMECH Aug. 2021 1932-1940
- Laurent, G.J., see Tiwari, B., TMECH Aug. 2021 1837-1845
- Lazcano, A.M., Niu, T., Carrera Akutain, X., Cole, D., and Shyrokau, B., MPC-Based Haptic Shared Steering System: A Driver Modeling Approach for Symbiotic Driving; *TMECH June 2021 1201-1211*
- Le, A.V., see Rayguru, M.M., TMECH June 2021 1236-1247
- Le, T., Bui, M.P., and Yoon, J., Optimal Design and Implementation of a Novel Two-Dimensional Electromagnetic Navigation System That Allows Focused Heating of Magnetic Nanoparticles ; *TMECH Feb. 2021 551-562*
- Le Gorrec, Y., see Liu, N., TMECH Dec. 2021 3139-3150
- Leang, K.K., see Mitrovic, A., TMECH June 2021 1412-1421

- Lee, C., see Lim, B., TMECH Aug. 2021 1728-1736
- Lee, D., see Lee, S.J., TMECH April 2021 765-776
- Lee, D., Liu, J., Lim, R., Chan, J.L., and Foong, S., Geometrical-Based Displacement Measurement With Pseudostereo Monocular Camera on Bidirectional Cascaded Linear Actuator: *TMECH Aug. 2021 1923-1931*
- Lee, E., see Cha, K., TMECH June 2021 1260-1270
- Lee, H., see Haghjoo, M.R., TMECH Feb. 2021 13-23
- Lee, H., see Jeon, H., TMECH June 2021 1401-1411
- Lee, I.J.J., see Cai, C.J., TMECH June 2021 1678-1688
- Lee, J., see Lee, M., TMECH Feb. 2021 191-202
- Lee, J., see Lee, S., TMECH June 2021 1358-1368
- Lee, J., see Chae, H., TMECH Aug. 2021 1719-1727
- Lee, J., Kim, J., Park, S., Hwang, D., and Yang, S., Soft Robotic Palm With Tunable Stiffness Using Dual-Layered Particle Jamming Mechanism ; *TMECH Aug. 2021 1820-1827*
- Lee, K., see Oh, J., TMECH Feb. 2021 102-112
- Lee, K., see Li, L., TMECH April 2021 918-929
- Lee, K., see Kim, H., TMECH Oct. 2021 2538-2547
- Lee, M., Kim, J., Hyung, S., Lee, J., Seo, K., Park, Y.J., Cho, J., Choi, B., Shim, Y., and Choi, H., A Compact Ankle Exoskeleton With a Multiaxis Parallel Linkage Mechanism; *TMECH Feb. 2021 191-202*
- Lee, M., see Birla, M., TMECH June 2021 1445-1454
- Lee, M.C., see Kim, J., TMECH Aug. 2021 1782-1790
- Lee, M.W., see Jang, N., TMECH Aug. 2021 1867-1876
- Lee, S., Lee, J., Park, J., and Sim, S., Nontarget-Based Measurement of 6-DOF Structural Displacement Using Combined RGB Color and Depth Information; *TMECH June 2021 1358-1368*
- Lee, S., see Jung, H.J., TMECH Aug. 2021 1708-1718
- Lee, S.B., see Kommuri, S.K., TMECH June 2021 1392-1400
- Lee, S.J., Lee, D., Kim, J., Kim, D., Jang, I., and Kim, H.J., Fully Actuated Autonomous Flight of Thruster-Tilting Multirotor; *TMECH April 2021 765-*776
- Lee, T.H., see Chen, J., TMECH Oct. 2021 2770-2781
- Lee, Y., see Yang, S., TMECH Feb. 2021 226-234
- Lefeber, D., see Crispel, S., TMECH Aug. 2021 1980-1988
- Lei, L., see Zhao, B., TMECH April 2021 943-954
- Lei, Z., Chen, X., Chen, X., and Chai, L., Radial Coverage Strength for Optimization of Monocular Multicamera Deployment; *TMECH Dec. 2021 3221-3231*
- Leme, B., see Chen, Y., TMECH Aug. 2021 2007-2015
- Leonhardt, S., see Liu, L., TMECH Aug. 2021 2080-2091
- Lerner, E., see Zhang, H., TMECH Oct. 2021 2316-2326
- Li, A., see Huang, Y., TMECH Feb. 2021 33-44
- Li, B., see Cao, C., TMECH Dec. 2021 3151-3162
- Li, C., see Jin, L., TMECH Feb. 2021 90-101
- Li, C., see Wu, J., *TMECH June 2021 1369-1379*
- Li, C., see Xiao, X., TMECH Oct. 2021 2483-2494
- Li, C., see Helian, B., TMECH Oct. 2021 2593-2603
- Li, C.G., Zhou, L., and Chao, Y., Self-Balancing Two-Wheeled Robot Featuring Intelligent End-to-End Deep Visual-Steering; *TMECH Oct. 2021 2263-2273*
- Li, D., Cao, K., Kong, L., and Yu, H., Fully Distributed Cooperative Circumnavigation of Networked Unmanned Aerial Vehicles; *TMECH April 2021* 709-718
- Li, D., see Zhou, N., TMECH Aug. 2021 2092-2103
- Li, F., Jiang, Y., and Li, T., A Laser-Guided Solution to Manipulate Mobile Robot Arm Terminals Within a Large Workspace ; *TMECH Oct. 2021 2676-2687*
- Li, G., Patel, N.A., Burdette, E.C., Pilitsis, J.G., Su, H., and Fischer, G.S., A Fully Actuated Robotic Assistant for MRI-Guided Precision Conformal Ablation of Brain Tumors; *TMECH Feb. 2021 255-266*
- Li, G., see Wu, Y., TMECH Feb. 2021 563-573
- Li, G., see Ma, J., TMECH April 2021 730-740
- Li, G., Song, D., Xu, S., Sun, L., and Liu, J., On Perpendicular Curve-Based Model-Less Control Considering Incomplete Orientation Constraint; *TMECH June 2021 1479-1489*
- Li, G., see Birla, M., TMECH June 2021 1445-1454

- Li, G., and Zhu, W., Experimental Investigation on Control of an Infinitely Variable Transmission System for Tidal Current Energy Converters ; *TMECH* Aug. 2021 1960-1967
- Li, H., Cheng, L., Li, Z., and Xue, W., Active Disturbance Rejection Control for a Fluid-Driven Hand Rehabilitation Device; *TMECH April 2021 841-853*
- Li, H., see Birla, M., TMECH June 2021 1445-1454
- Li, H., see Tao, Y., TMECH Aug. 2021 2186-2194
- Li, H., see Cao, C., TMECH Dec. 2021 3151-3162
- Li, J., see Zhao, J., *TMECH Feb. 2021 3-12*
- Li, J., see Tan, Q., TMECH April 2021 621-632
- Li, J., see Dong, M., TMECH June 2021 1490-1500
- Li, J., Huang, R., He, G., Liao, Y., Wang, Z., and Li, W., A Two-Stage Transfer Adversarial Network for Intelligent Fault Diagnosis of Rotating Machinery With Multiple New Faults; *TMECH June 2021 1591-1601*
- Li, J., see Xu, Y., TMECH Aug. 2021 2249-2260
- Li, J., see Deng, J., TMECH Aug. 2021 2059-2070
- Li, K., see Guo, J., TMECH Aug. 2021 2151-2162
- Li, L., Huang, J., Aphale, S.S., and Zhu, L., A Smoothed Raster Scanning Trajectory Based on Acceleration-Continuous B-Spline Transition for High-Speed Atomic Force Microscopy; *TMECH Feb. 2021 24-32*
- Li, L., Lee, K., Ouyang, X., and Yang, H., Analytical Harmonic Method for Modeling High-Frequency Oscillation With Applications to Aircraft Piston Pump Vibration Analysis; *TMECH April 2021 918-929*
- Li, L., Huang, J., Aphale, S.S., and Zhu, L., Erratum to "A Smoothed Raster Scanning Trajectory Based on Acceleration-Continuous B-Spline Transition for High-Speed Atomic Force Microscopy" [Feb 21 24-32]; *TMECH June* 2021 1700
- Li, M., see Zhang, X., TMECH April 2021 807-817
- Li, N., see Shi, Y., TMECH Feb. 2021 214-225
- Li, P., see Roy, S., TMECH Dec. 2021 3064-3075
- Li, Q., see Zhao, C., TMECH Feb. 2021 437-447
- Li, Q., Meng, F., Yu, Z., Chen, X., and Huang, Q., Dynamic Torso Compliance Control for Standing and Walking Balance of Position-Controlled Humanoid Robots; *TMECH April 2021 679-688*
- Li, Q., see Li, Z., TMECH Oct. 2021 2700-2711
- Li, Q., see Li, T., TMECH Dec. 2021 3040-3050
- Li, S., see Zhao, B., TMECH April 2021 943-954
- Li, T., see Li, F., TMECH Oct. 2021 2676-2687
- Li, T., Wang, L., Yi, J., Li, Q., and Liu, T., Reconstructing Walking Dynamics From Two Shank-Mounted Inertial Measurement Units; *TMECH Dec. 2021* 3040-3050
- Li, W., see Tu, L., TMECH Feb. 2021 156-167
- Li, W., see Xie, H., TMECH Feb. 2021 515-526
- Li, W., see Li, J., TMECH June 2021 1591-1601
- Li, X., see Guo, Q., TMECH Aug. 2021 2048-2058
- Li, X., see Li, Z., TMECH Oct. 2021 2700-2711
- Li, X., see Zhou, J., TMECH Dec. 2021 3128-3138
- Li, Y., see Liu, T., TMECH April 2021 930-942
- Li, Y., see Xu, Y., TMECH Aug. 2021 2249-2260
- Li, Y., see Zheng, E., TMECH Oct. 2021 2373-2384
- Li, Y., Liu, Y., Yamazaki, K., Bai, M., and Chen, Y., Development of a Soft Robot Based Photodynamic Therapy for Pancreatic Cancer ; *TMECH Dec.* 2021 2977-2985
- Li, Y., see Fan, R., TMECH Dec. 2021 2870-2880
- Li, Y., see Cao, C., TMECH Dec. 2021 3151-3162
- Li, Y., see Chen, L., TMECH Dec. 2021 2922-2931
- Li, Z., see Liu, Y., TMECH April 2021 657-667
- Li, Z., see Zhang, X., TMECH April 2021 807-817
- Li, Z., see Li, H., TMECH April 2021 841-853
- Li, Z., see He, W., TMECH April 2021 595-599
- Li, Z., Gong, J., Lu, C., and Yi, Y., Interactive Behavior Prediction for Heterogeneous Traffic Participants in the Urban Road: A Graph-Neural-Network-Based Multitask Learning Framework; *TMECH June 2021 1339-1349*
- Li, Z., see Chen, G., TMECH June 2021 1547-1557
- Li, Z., see Zhang, B., TMECH Oct. 2021 2396-2407

- Li, Z., Zhao, K., Zhang, L., Wu, X., Zhang, T., Li, Q., Li, X., and Su, C., Human-in-the-Loop Control of a Wearable Lower Limb Exoskeleton for Stable Dynamic Walking; *TMECH Oct. 2021 2700-2711*
- Li, Z., see Zhou, J., TMECH Dec. 2021 3128-3138
- Liang, C., see Chen, S., TMECH Dec. 2021 3254-3264
- Liang, J., see Zhang, Z., TMECH Dec. 2021 3232-3242
- Liang, L., see Liu, F., TMECH Feb. 2021 113-123
- Liang, X., see Zheng, M., TMECH Feb. 2021 45-54
- Liao, C., see Chen, S., TMECH Dec. 2021 3254-3264
- Liao, H., Cheng, S., and Hwu, E., Development of a Resonant Scanner to Improve the Imaging Rate of Astigmatic Optical Profilometers; *TMECH April 2021 1172-1177*
- Liao, W., see Cai, M., TMECH Aug. 2021 2104-2114
- Liao, Y., see Li, J., TMECH June 2021 1591-1601
- Lim, B., Lee, C., and Hwang, D., Development of Embedded Sensor System for 5-DOF Finger-Wearable Tactile Interface; *TMECH Aug. 2021 1728-1736*
- Lim, M., see Hwang, S., TMECH April 2021 1033-1042
- Lim, M., see Cha, K., TMECH June 2021 1260-1270
- Lim, M.T., see Kim, H., TMECH Oct. 2021 2538-2547
- Lim, R., see Lee, D., TMECH Aug. 2021 1923-1931
- Lin, F., see Chen, S., TMECH Dec. 2021 3254-3264
- Lin, H., see Wang, Y., TMECH Aug. 2021 1858-1866
- Lin, L., Computationally Improved State-Dependent Riccati Equation Scheme for Nonlinear Benchmark System; *TMECH April 2021 1064-1075*
- Lin, T.X., see Tao, Q., TMECH Aug. 2021 1895-1904
- Lin, X., see Deng, Z., TMECH June 2021 1295-1306
- Lin, Y., see Wang, F., TMECH Feb. 2021 66-77
- Lin, Y., Chen, Z., and Yao, B., Unified Motion/Force/Impedance Control for Manipulators in Unknown Contact Environments Based on Robust Model-Reaching Approach; *TMECH Aug. 2021 1905-1913*
- Lin, Y., see Fu, Z., TMECH Oct. 2021 2688-2699
- Ling, J., see Chen, L., TMECH Aug. 2021 1951-1959
- Linner, T., see Cheah, C.C., TMECH Dec. 2021 2819-2825
- Liu, C., Chung, F., and Ho, Y., Topology Optimization for Design of a 3D-Printed Constant-Force Compliant Finger; *TMECH Aug. 2021 1828-1836*
- Liu, D., see Acharya, P., TMECH Feb. 2021 527-538
- Liu, D., see Liu, F., TMECH Feb. 2021 113-123
- Liu, F., Liang, L., Xu, G., Hou, C., and Liu, D., Four-Point Method in the Measurement and Separation of Spindle Rotation Error; *TMECH Feb. 2021* 113-123
- Liu, G., Zhu, S., and Sun, X., Kernel Principal Components Analysis of Lateral Force Data for Quantitative Evaluation of 3D Features Rendering Fidelity; *TMECH June 2021 1602-1612*
- Liu, H., Selvaggio, M., Ferrentino, P., Moccia, R., Pirozzi, S., Bracale, U., and Ficuciello, F., The MUSHA Hand II:A Multifunctional Hand for Robot-Assisted Laparoscopic Surgery; *TMECH Feb. 2021 393-404*
- Liu, H., see Tan, Q., TMECH April 2021 621-632
- Liu, H., see Liu, X., TMECH June 2021 1536-1546
- Liu, J., see Li, G., TMECH June 2021 1479-1489
- Liu, J., see Lee, D., TMECH Aug. 2021 1923-1931
- Liu, K., see Shimonomura, S., TMECH Aug. 2021 2163-2173
- Liu, K., see Chen, F., TMECH Oct. 2021 2629-2640
- Liu, K., Hu, X., Zhou, H., Tong, L., Widanage, W.D., and Marco, J., Feature Analyses and Modeling of Lithium-Ion Battery Manufacturing Based on Random Forest Classification; *TMECH Dec. 2021 2944-2955*
- Liu, L., see Liu, Y., TMECH Feb. 2021 168-178
- Liu, L., Hong, Z., Penzlin, B., Misgeld, B.J.E., Ngo, C., Bergmann, L., and Leonhardt, S., Low Impedance-Guaranteed Gain-Scheduled GESO for Torque-Controlled VSA With Application of Exoskeleton-Assisted Sit-to-Stand; *TMECH Aug. 2021 2080-2091*
- Liu, M., see Jin, L., TMECH Feb. 2021 90-101
- Liu, M., see Wu, J., TMECH June 2021 1369-1379
- Liu, N., Wu, Y., and Le Gorrec, Y., Energy-Based Modeling of Ionic Polymer– Metal Composite Actuators Dedicated to the Control of Flexible Structures; *TMECH Dec.* 2021 3139-3150
- Liu, P.X., see Bao, J., TMECH June 2021 1570-1580

- Liu, S., Wang, F., Liu, Z., Zhang, W., Tian, Y., and Zhang, D., A Two-Finger Soft-Robotic Gripper With Enveloping and Pinching Grasping Modes; *TMECH Feb. 2021 146-155*
- Liu, S., see Liu, Z., TMECH Aug. 2021 2195-2203
- Liu, S., see Liu, W., TMECH Aug. 2021 1846-1857
- Liu, S., Zhu, Y., Zhang, Z., Fang, Z., Tan, J., Peng, J., Song, C., Asada, H.H., and Wang, Z., Otariidae-Inspired Soft-Robotic Supernumerary Flippers by Fabric Kirigami and Origami ; *TMECH Oct. 2021 2747-2757*
- Liu, T., Xu, W., Yang, T., and Li, Y., A Hybrid Active and Passive Cable-Driven Segmented Redundant Manipulator: Design, Kinematics, and Planning; *TMECH April 2021 930-942*
- Liu, T., see Li, T., TMECH Dec. 2021 3040-3050
- Liu, W., Liu, S., Cao, J., Wang, Q., Lang, X., and Liu, Y., Learning Communication for Cooperation in Dynamic Agent-Number Environment; *TMECH* Aug. 2021 1846-1857
- Liu, X., see Wu, Y., TMECH Feb. 2021 563-573
- Liu, X., see Dong, X., TMECH Feb. 2021 427-436
- Liu, X., Chen, W., Madhusudanan, H., Du, L., and Sun, Y., Camera Orientation Optimization in Stereo Vision Systems for Low Measurement Error; *TMECH April 2021 1178-1182*
- Liu, X., Liu, H., and Tan, J., Actuation Frequency Modeling and Prediction for Shape Memory Alloy Actuators; *TMECH June 2021 1536-1546*
- Liu, X., Ge, S.S., Zhao, F., and Mei, X., Optimized Interaction Control for Robot Manipulator Interacting With Flexible Environment; *TMECH Dec.* 2021 2888-2898
- Liu, Y., Zhang, Y., Liu, L., Tong, S., and Chen, C.L.P., Adaptive Finite-Time Control for Half-Vehicle Active Suspension Systems With Uncertain Dynamics; *TMECH Feb. 2021 168-178*
- Liu, Y., Li, Z., Su, H., and Su, C., Whole-Body Control of an Autonomous Mobile Manipulator Using Series Elastic Actuators; *TMECH April 2021* 657-667
- Liu, Y., see Wang, Z., TMECH April 2021 1095-1105
- Liu, Y., see Zhao, H., TMECH April 2021 645-656
- Liu, Y., see Wang, T., TMECH April 2021 1183-1188
- Liu, Y., see Wang, Y., TMECH June 2021 1318-1327
- Liu, Y., see Zhou, S., TMECH June 2021 1467-1478
- Liu, Y., see Deng, J., TMECH Aug. 2021 2059-2070
- Liu, Y., see Liu, W., TMECH Aug. 2021 1846-1857
- Liu, Y., see Zhang, Z., TMECH Aug. 2021 1997-2006
- Liu, Y., see Li, Y., TMECH Dec. 2021 2977-2985
- Liu, Y., see Cheah, C.C., TMECH Dec. 2021 2819-2825
- Liu, Z., see Liu, S., TMECH Feb. 2021 146-155
- Liu, Z., Wu, J., Wang, L., and Zhang, B., Control Parameters Design Based on Dynamic Characteristics of a Hybrid Robot With Parallelogram Structures ; *TMECH April 2021 1140-1150*
- Liu, Z., see Zhou, S., TMECH June 2021 1467-1478
- Liu, Z., see Han, L., TMECH Aug. 2021 2016-2026
- Liu, Z., Wang, F., Liu, S., Tian, Y., and Zhang, D., Modeling and Analysis of Soft Pneumatic Network Bending Actuators; *TMECH Aug. 2021 2195-2203*
- Liu, Z., see Ma, Z., TMECH Oct. 2021 2472-2482
- Liu, Z., see Song, Y., TMECH Dec. 2021 2986-2997
- Long, F., Cheng, P., Meng, T., and Menq, C., Optimal Current Allocation Rendering 3-D Magnetic Force Production in Hexapole Electromagnetic Actuation; *TMECH Oct. 2021 2408-2417*
- Lou, E., see Balbola, A.A., TMECH April 2021 1076-1083
- Lu, C., see Li, Z., TMECH June 2021 1339-1349
- Lu, J., see Zhu, H., TMECH Oct. 2021 2712-2723
- Lu, K., see Lu, W., TMECH June 2021 1613-1623
- Lu, K., see Pang, X., TMECH Aug. 2021 2027-2037
- Lu, L., see Gong, X., TMECH June 2021 1271-1282
- Lu, L., see Ding, C., TMECH Aug. 2021 2237-2248
- Lu, W., Tang, B., Wu, Y., Lu, K., Wang, D., and Wang, X., A New Position Detection and Status Monitoring System for Joint of SCARA; *TMECH June* 2021 1613-1623
- Lu, X., see Ma, J., TMECH April 2021 730-740

- Lu, Z., Wang, N., and Yang, C., A Constrained DMPs Framework for Robot Skills Learning and Generalization From Human Demonstrations; *TMECH Dec.* 2021 3265-3275
- Luo, J., see Zhao, J., TMECH Aug. 2021 2038-2047
- Luo, Y., see Guo, J., TMECH Aug. 2021 2151-2162
- Lutz, P., see Tiwari, B., TMECH Aug. 2021 1837-1845
- Lv, C., see Huang, C., TMECH April 2021 611-620
- Lv, C., see Ivanov, V., TMECH June 2021 1195-1200
- Lyu, L., see Helian, B., TMECH Oct. 2021 2593-2603
- Lyu, X., see Zheng, M., TMECH Feb. 2021 45-54

Μ

- Ma, B., see Gong, X., TMECH June 2021 1271-1282
- Ma, B., and Wang, Y., Adaptive Output Feedback Control of Steer-by-Wire Systems With Event-Triggered Communication; *TMECH Aug. 2021 1968-1979*
- Ma, J., Li, G., Lu, X., Jia, Z., Qin, F., and Qu, Z., Toolpath Regeneration in Subregional Contour-Parallel Processing Based on Isoscallop Method; *TMECH April 2021 730-740*
- Ma, S., see Kakogawa, A., TMECH Dec. 2021 3051-3063
- Ma, Y., Jiang, B., and Cocquempot, V., Modeling and Adaptive Fault Compensation for Two Physically Linked 2WD Mobile Robots; *TMECH April* 2021 1161-1171
- Ma, Z., Liu, Z., and Huang, P., Fractional-Order Control for Uncertain Teleoperated Cyber-Physical System With Actuator Fault; *TMECH Oct. 2021* 2472-2482
- Madhusudanan, H., see Liu, X., TMECH April 2021 1178-1182
- Mai, J., see Gao, S., TMECH Oct. 2021 2429-2439
- Malysheva, J., Ustinov, S., and Handroos, H., Computationally Efficient Practical Method for Solving the Dynamics of Fluid Power Circuits in the Presence of Singularities; *TMECH Oct.* 2021 2385-2395
- Manoharan, S.K., see Megalingam, R.K., TMECH Feb. 2021 288-299
- Marco, J., see Liu, K., TMECH Dec. 2021 2944-2955
- Maroufi, M., see Nikooienejad, N., TMECH Aug. 2021 2127-2138
- Martel, S., see Shi, Y., TMECH Feb. 2021 214-225
- Matsuura, N., see Shokrollahi, P., TMECH Oct. 2021 2616-2628
- Megalingam, R.K., Manoharan, S.K., Mohandas, S.M., Vadivel, S.R.R., Gangireddy, R., Ghanta, S., Kumar, K.S., Teja, P.S., and Sivanantham, V., Amaran:An Unmanned Robotic Coconut Tree Climber and Harvester; *TMECH Feb.* 2021 288-299
- Mehling, J.S., see Thomas, G.C., TMECH Feb. 2021 586-591
- Mei, X., see Liu, X., TMECH Dec. 2021 2888-2898
- Melchiorri, C., see Biagiotti, L., TMECH Oct. 2021 2724-2734
- Mendoza-Trejo, O., and Cruz-Villar, C.A., Robust Concurrent Design of a 2-DOF Collaborative Robot (Cobot); *TMECH Feb. 2021 347-357*
- Meng, F., see Li, Q., TMECH April 2021 679-688
- Meng, Q., Guo, H., Zhao, X., Cao, D., and Chen, H., Loop-Closure Detection With a Multiresolution Point Cloud Histogram Mode in Lidar Odometry and Mapping for Intelligent Vehicles; *TMECH June 2021 1307-1317*
- Meng, T., see Long, F., TMECH Oct. 2021 2408-2417
- Meng, Z., see Wang, Z., TMECH April 2021 1095-1105
- Meng, Z., see Chen, L., TMECH Dec. 2021 2922-2931
- Mengacci, R., Garabini, M., Grioli, G., Catalano, M.G., and Bicchi, A., Overcoming the Torque/Stiffness Range Tradeoff in Antagonistic Variable Stiffness Actuators; *TMECH Dec. 2021 3186-3197*
- Menq, C., see Long, F., TMECH Oct. 2021 2408-2417
- Meurer, T., see He, W., TMECH April 2021 595-599
- Meyer, T.J.J., see Shanbhag, V.V., TMECH Dec. 2021 3087-3103
- Miao, Y., see Chen, S., TMECH Aug. 2021 1745-1753
- Miao, Z., see Zhao, H., TMECH April 2021 645-656
- Mineo, C., see Wong, C., TMECH Oct. 2021 2294-2305
- Mioskowska, M., see Chen, S., TMECH Aug. 2021 1989-1996
- Misgeld, B.J.E., see Liu, L., TMECH Aug. 2021 2080-2091
- Mishra, S., Syed, D.F., Ploughe, M., and Zhang, W., Autonomous Vision-Guided Object Collection From Water Surfaces With a Customized Multirotor; *TMECH Aug. 2021 1914-1922*

- Mitrovic, A., Nagel, W.S., Leang, K.K., and Clayton, G.M., Closed-Loop Range-Based Control of Dual-Stage Nanopositioning Systems; *TMECH* June 2021 1412-1421
- Miura, S., Takazawa, J., Kobayashi, Y., and Fujie, M.G., Brain–Machine Interface Using Functional Electrical Stimulation and Motion-Related Cortical Potentials Identified by a Support Vector Machine; *TMECH April 2021* 1013-1021
- Moccia, R., see Liu, H., TMECH Feb. 2021 393-404
- **Mohajer, N.,** Najdovski, Z., and Nahavandi, S., An Efficient Design Solution for a Low-Cost High-G Centrifuge System; *TMECH Feb. 2021 134-145*
- Mohammad, A., see Ba, W., *TMECH Dec. 2021 3010-3021* Mohammadigheisar, M., see Shokrollahi, P., *TMECH Oct. 2021 2616-2628*
- Mohan, R.E., see Rayguru, M.M., *TMECH June 2021 1236-1247*
- Mohandas, S.M., see Megalingam, R.K., TMECH Feb. 2021 288-299
- Moheimani, S.O.R., see Nikooienejad, N., *TMECH Aug. 2021 200 299*
- Montanaro, U., see Dalboni, M., TMECH June 2021 1212-1224
- Mou, Q., see Zhao, J., TMECH Feb. 2021 3-12
- Moussa, W.A., see Balbola, A.A., TMECH April 2021 1076-1083
- Mugilvannan, A.K., see Cai, C.J., TMECH June 2021 1678-1688
- Muhammad, I., Ying, K., Nithish, M., Xin, J., Xinge, Z., and Cheah, C.C., Robot-Assisted Object Detection for Construction Automation: Data and Information-Driven Approach; *TMECH Dec.* 2021 2845-2856

Ν

- Na, J., see Zhang, C., TMECH Aug. 2021 2226-2236
- Nagel, W.S., see Mitrovic, A., TMECH June 2021 1412-1421
- Nahavandi, S., see Mohajer, N., TMECH Feb. 2021 134-145
- Najdovski, Z., see Mohajer, N., TMECH Feb. 2021 134-145
- Narang, D., see Chen, J., TMECH Aug. 2021 1737-1744
- Nesler, C., see Zhu, H., TMECH Dec. 2021 3104-3115
- Ngo, C., see Liu, L., TMECH Aug. 2021 2080-2091
- Nguyen, A., Dinh, T.Q., Guerra, T., and Pan, J., Takagi–Sugeno Fuzzy Unknown Input Observers to Estimate Nonlinear Dynamics of Autonomous Ground Vehicles: Theory and Real-Time Verification; *TMECH June 2021* 1328-1338
- Nguyen, C.T., see Phung, H., TMECH Oct. 2021 2495-2505
- Nguyen, D., Saussie, D., and Saydy, L., Design and Experimental Validation of Robust Self-Scheduled Fault-Tolerant Control Laws for a Multicopter UAV ; *TMECH Oct. 2021 2548-2557*
- Nguyen, K., see Acharya, P., TMECH Feb. 2021 527-538
- Nguyen, T.D., see Phung, H., TMECH Oct. 2021 2495-2505
- Nie, R., see Chen, H., TMECH Feb. 2021 469-479
- Nikooienejad, N., Maroufi, M., and Moheimani, S.O.R., Iterative Learning Control for Video-Rate Atomic Force Microscopy; *TMECH Aug. 2021* 2127-2138
- Ning, D., see Tu, L., TMECH Feb. 2021 156-167
- Nithish, M., see Muhammad, I., TMECH Dec. 2021 2845-2856
- Niu, T., see Lazcano, A.M., TMECH June 2021 1201-1211
- Njaka, T., Brizzolara, S., and Ben-Tzvi, P., Design and Experimental Validation of a Novel High-Speed Omnidirectional Underwater Propulsion Mechanism; *TMECH Oct. 2021 2339-2349*
- Norton, A., see Ba, W., TMECH Dec. 2021 3010-3021
- Nozaki, T., see Sariyildiz, E., TMECH Aug. 2021 2139-2150
- Nurmi, S., see Cenev, Z., TMECH Aug. 2021 1932-1940

0

- O-Tani, H., see Takeyama, T., TMECH Dec. 2021 2881-2887
- Oh, J., Sim, O., Cho, B., and Lee, K., Online Delayed Reference Generation for a Humanoid Imitating Human Walking Motion; *TMECH Feb. 2021 102-112*
- Oh, J., see Oh, J., TMECH Feb. 2021 102-112
- Oh, J., see Seo, M., TMECH Aug. 2021 1812-1819
- Oh, J., see Yoo, S., TMECH Aug. 2021 1754-1762
- Ohnishi, K., see Sariyildiz, E., TMECH Aug. 2021 2139-2150
- Oishi, S., see Takeyama, T., TMECH Dec. 2021 2881-2887
- Oka, K., see Zhao, C., TMECH Feb. 2021 437-447

- Olaizola, J., Esteban, E., Trinidad, J., Iturrospe, A., Galdos, L., Abete, J.M., Argandona, E.S.d., Integral Design and Manufacturing Methodology of a Reduced-Scale Servo Press ; *TMECH Oct. 2021 2418-2428*
- Oldham, K.R., see Birla, M., TMECH June 2021 1445-1454
- **Oncken, J.,** Sachdeva, K., Wang, H., and Chen, B., Integrated Predictive Powertrain Control for a Multimode Plug-in Hybrid Electric Vehicle; *TMECH June 2021 1248-1259*
- Ongel, A., see Ivanov, V., TMECH June 2021 1195-1200
- Orekhov, A.L., see Giudice, G.D., TMECH Oct. 2021 2604-2615
- **Orozco-Magdaleno, E.C.,** Gomez-Bravo, F., Castillo-Castaneda, E., and Carbone, G., Evaluation of Locomotion Performances for a Mecanum-Wheeled Hybrid Hexapod Robot; *TMECH June 2021 1657-1667*
- Ota, J., see Huang, Y., TMECH Aug. 2021 2174-2185
- Ouyang, X., see Li, L., TMECH April 2021 918-929

Р

- Paez-Granados, D.F., see Chen, Y., TMECH Aug. 2021 2007-2015
- Paik, J., see Rodriguez, A.S., TMECH Oct. 2021 2791-2802
- Pal, A., Zhu, L., Wang, Y., G. Zhu, G., Constrained Surrogate-Based Engine Calibration Using Lower Confidence Bound; *TMECH Dec. 2021 3116-3127*
- Pan, J., see Nguyen, A., TMECH June 2021 1328-1338
- Pan, J., see Fu, Z., TMECH Oct. 2021 2688-2699
- Pan, Q., see Chen, F., TMECH Oct. 2021 2629-2640
- Pan, Z., see Bu, F., TMECH April 2021 1129-1139
- Pang, X., Xue, X., Jiang, W., and Lu, K., An Investigation Into Fault Diagnosis of Planetary Gearboxes Using A Bispectrum Convolutional Neural Network; *TMECH Aug. 2021 2027-2037*
- Park, G., see Chae, H., TMECH Aug. 2021 1719-1727
- Park, J., see Lee, S., TMECH June 2021 1358-1368
- Park, J., see Hong, S., TMECH Aug. 2021 2115-2126
- Park, J.H., see Jung, H.S., TMECH April 2021 1002-1012
- Park, S., see Cha, K., TMECH June 2021 1260-1270
- Park, S., see Lee, J., TMECH Aug. 2021 1820-1827
- Park, Y., see Kommuri, S.K., TMECH June 2021 1392-1400
- Park, Y.J., see Lee, M., TMECH Feb. 2021 191-202
- Parkinson, J., see Shokrollahi, P., TMECH Oct. 2021 2616-2628
- Parween, R., see Rayguru, M.M., TMECH June 2021 1236-1247
- Pascoal, A.M., see Teng, M., TMECH Oct. 2021 2570-2580
- Patel, N., see Ebrahimi, A., TMECH June 2021 1512-1523
- Patel, N.A., see Li, G., TMECH Feb. 2021 255-266
- Pecht, M.G., see She, D., TMECH Oct. 2021 2440-2450
- Peddinti, V., see Zhu, H., TMECH Dec. 2021 3104-3115
- Peng, B., see Zhou, W., TMECH Aug. 2021 1773-1781
- Peng, J., see Liu, S., TMECH Oct. 2021 2747-2757
- Peng, T., see Zhu, Y., TMECH April 2021 1151-1160
- Peng, Y., see Zhao, J., TMECH Aug. 2021 2038-2047
- Penzlin, B., see Liu, L., TMECH Aug. 2021 2080-2091
- Petersen, I.R., see Tran, V.P., TMECH Oct. 2021 2306-2315
- Petit, L., see Tisnes, S.D., TMECH June 2021 1422-1432
- Phung, H., see Jung, H.S., TMECH April 2021 1002-1012
- Phung, H., Hoang, P.T., Jung, H., Nguyen, T.D., Nguyen, C.T., and Choi, H.R., Haptic Display Responsive to Touch Driven by Soft Actuator and Soft Sensor; *TMECH Oct.* 2021 2495-2505
- Pilitsis, J.G., see Li, G., TMECH Feb. 2021 255-266
- Pirozzi, S., see Liu, H., TMECH Feb. 2021 393-404
- Ploughe, M., see Mishra, S., TMECH Aug. 2021 1914-1922
- Poletkin, K.V., Static Pull-In Behavior of Hybrid Levitation Microactuators: Simulation, Modeling, and Experimental Study; *TMECH April 2021 753-764*
- Popieul, J., see Fouka, M., TMECH Aug. 2021 1763-1772
- Pozzato, G., Strada, S.C., Tanelli, M., Savaresi, S.M., and Dambach, G., MEMS-Enabled Retrofitting of Automobile Wheel Balancer for Automatic Unbalance Detection; *TMECH April 2021 830-840*
- Prelle, C., see Tisnes, S.D., TMECH June 2021 1422-1432
- Pu, H., see Zhao, J., TMECH Aug. 2021 2038-2047

Q

- Qian, F., see Xie, G., TMECH April 2021 633-644
- Qian, Z., see Wang, F., TMECH Feb. 2021 66-77
- Qianyi, Z., see Teng, M., TMECH Oct. 2021 2570-2580
- Qiao, H., see Zheng, E., TMECH Oct. 2021 2373-2384 Qin, B., see Zeng, R., TMECH June 2021 1581-1590
- **Qin, F.,** see Ma, J., *TMECH April 2021 730-740*
- Qin, Y., see Zhao, J., TMECH Aug. 2021 2038-2047
- Qu, Z., see Ma, J., TMECH April 2021 730-740
- Quintana, J., see Simetti, E., TMECH June 2021 1635-1645

R

- Raab, M., Hutter, M., Kazi, A., Schinkoethe, W., and Gundelsweiler, B., Magnetically Levitated Linear Drive Using an Active Gravity Compensation Based on Hybrid Shape Memory Actuators; *TMECH June 2021 1380-1391*
- Raggini, D., see Bosso, A., TMECH June 2021 1501-1511
- Rajamani, R., see Jeon, W., TMECH Aug. 2021 1941-1950
- Ramalingam, V.S., see Abirami B, S., TMECH Oct. 2021 2814-2817
- Ran, L., see Zhou, W., TMECH Aug. 2021 1773-1781
- Ras, R., see Cenev, Z., TMECH Aug. 2021 1932-1940
- Rash-Ahmadi, S., see Shokrollahi, P., TMECH Oct. 2021 2616-2628
- Rayguru, M.M., Mohan, R.E., Parween, R., Yi, L., Le, A.V., and Roy, S., An Output Feedback Based Robust Saturated Controller Design for Pavement Sweeping Self-Reconfigurable Robot; *TMECH June 2021 1236-1247*
- Rehan, M., Al-Bahadly, I., Thomas, D.G., and Avci, E., Measurement of Peristaltic Forces Exerted by Living Intestine on Robotic Capsule; *TMECH Aug.* 2021 1803-1811
- Ren, H., see Cai, C.J., TMECH June 2021 1678-1688
- Ren, H., see Xiao, X., TMECH Oct. 2021 2483-2494
- Rodriguez, A.S., Hosseini, M., and Paik, J., Hybrid Control Strategy for Force and Precise End Effector Positioning of a Twisted String Actuator; *TMECH* Oct. 2021 2791-2802
- Rong, X., see Dong, M., TMECH June 2021 1490-1500
- Rosset, S., see Bernat, J., TMECH Oct. 2021 2664-2675
- Roy, S., see Rayguru, M.M., TMECH June 2021 1236-1247
- Roy, S., Baldi, S., Li, P., and Sankaranarayanan, V.N., Artificial-Delay Adaptive Control for Underactuated Euler–Lagrange Robotics ; *TMECH Dec. 2021* 3064-3075
- Ru, H., see Cao, Y., TMECH Feb. 2021 574-585

S

- Saad, M., see Fallaha, C., TMECH Feb. 2021 539-550
- Sachdeva, K., see Oncken, J., TMECH June 2021 1248-1259
- Saerens, E., see Crispel, S., TMECH Aug. 2021 1980-1988
- Salcudean, S.E., see Hosseinabadi, A.H.H., TMECH Oct. 2021 2581-2592
- Sandoz, P., see Tiwari, B., TMECH Aug. 2021 1837-1845
- Sankaranarayanan, V.N., see Roy, S., TMECH Dec. 2021 3064-3075
- Santoso, F., see Tran, V.P., TMECH Oct. 2021 2306-2315
- Sariyildiz, E., see Tawk, C., TMECH April 2021 876-887
- Sariyildiz, E., Hangai, S., Uzunovic, T., Nozaki, T., and Ohnishi, K., Stability
- and Robustness of the Disturbance Observer-Based Motion Control Systems in Discrete-Time Domain; *TMECH Aug. 2021 2139-2150*
- Saruhan, E.N., see Demircali, A.A., TMECH Dec. 2021 2956-2966
- Saussie, D., see Nguyen, D., TMECH Oct. 2021 2548-2557
- Savaresi, S.M., see Pozzato, G., TMECH April 2021 830-840
- Saydy, L., see Nguyen, D., TMECH Oct. 2021 2548-2557
- Scharff, R.B.N., Fang, G., Tian, Y., Wu, J., Geraedts, J.M.P., and Wang, C.C., Sensing and Reconstruction of 3-D Deformation on Pneumatic Soft Robots; *TMECH Aug. 2021 1877-1885*
- Schinkoethe, W., see Raab, M., TMECH June 2021 1380-1391
- Schitter, G., see Csencsics, E., TMECH April 2021 1053-1063
- Schlanbusch, R., see Shanbhag, V.V., TMECH Dec. 2021 3087-3103
- Secchi, C., see Ferraguti, F., TMECH Feb. 2021 276-287

- Sedghi, F., Arefi, M.M., Abooee, A., and Kaynak, O., Adaptive Robust Finite-Time Nonlinear Control of a Typical Autonomous Underwater Vehicle With Saturated Inputs and Uncertainties; TMECH Oct. 2021 2517-2527
- Sefati, S., Hegeman, R., Alambeigi, F., Iordachita, I., Kazanzides, P., Khanuja, H., Taylor, R.H., and Armand, M., A Surgical Robotic System for Treatment of Pelvic Osteolysis Using an FBG-Equipped Continuum Manipulator and Flexible Instruments; TMECH Feb. 2021 369-380
- Sefati, S., see Ebrahimi, A., TMECH June 2021 1512-1523
- Selvaggio, M., see Liu, H., TMECH Feb. 2021 393-404
- Sencer, B., see Dumanli, A., TMECH Oct. 2021 2735-2746
- Sentis, L., see Thomas, G.C., TMECH Feb. 2021 586-591
- Sentouh, C., see Fouka, M., TMECH Aug. 2021 1763-1772
- Seo, K., see Lee, M., TMECH Feb. 2021 191-202
- Seo, M., Yoo, S., Choi, M., Oh, J., Kim, H.S., and Seo, T., Vibration Reduction of Flexible Rope-Driven Mobile Robot for Safe Façade Operation; TMECH Aug. 2021 1812-1819
- Seo, M., see Yoo, S., TMECH Aug. 2021 1754-1762
- Seo, T., see Chae, H., TMECH Aug. 2021 1719-1727
- Seo, T., see Seo, M., TMECH Aug. 2021 1812-1819
- Seo, T., see Yoo, S., TMECH Aug. 2021 1754-1762
- Sergi, F., see Buchanan, S., TMECH Oct. 2021 2462-2471
- Seyfarth, A., see Sharbafi, M.A., TMECH Feb. 2021 335-346
- Shan, M., see Wang, Y., TMECH April 2021 719-729
- Shanbhag, V.V., Meyer, T.J.J., Caspers, L.W., and Schlanbusch, R., Failure Monitoring and Predictive Maintenance of Hydraulic Cylinder-State-ofthe-Art Review; TMECH Dec. 2021 3087-3103
- Shang, W., see Zhang, B., TMECH Oct. 2021 2396-2407
- Shangguan, A., see Xie, G., TMECH April 2021 633-644
- Shao, S., Chen, M., Hou, J., and Zhao, Q., Event-Triggered-Based Discrete-Time Neural Control for a Quadrotor UAV Using Disturbance Observer; TMECH April 2021 689-699
- Sharbafi, M.A., Yazdanpanah, M.J., Ahmadabadi, M.N., and Seyfarth, A., Parallel Compliance Design for Increasing Robustness and Efficiency in Legged Locomotion-Theoretical Background and Applications; TMECH Feb. 2021 335-346
- Sharifzadeh, M., and Aukes, D.M., Curvature-Induced Buckling for Flapping-Wing Vehicles; TMECH Feb. 2021 503-514
- She, D., Jia, M., and Pecht, M.G., Weighted Entropy Minimization Based Deep Conditional Adversarial Diagnosis Approach Under Variable Working Conditions; TMECH Oct. 2021 2440-2450
- Shen, J., see Giudice, G.D., TMECH Oct. 2021 2604-2615
- Shen, Y., Harada, N., Katagiri, S., and Tanaka, H., Biomimetic Realization of a Robotic Penguin Wing: Design and Thrust Characteristics; TMECH Oct. 2021 2350-2361
- Sheng, H., see Zhang, K., TMECH April 2021 700-708
- Sheng, X., see Chen, G., TMECH April 2021 668-678
- Shi, C., Dong, X., and Yang, Z., A Microgripper With a Large Magnification Ratio and High Structural Stiffness Based on a Flexure-Enabled Mechanism; TMECH Dec. 2021 3076-3086
- Shi, Y., see Huang, Y., TMECH Feb. 2021 33-44
- Shi, Y., Li, N., Tremblay, C.C., and Martel, S., A Piezoelectric Robotic System for MRI Targeting Assessments of Therapeutics During Dipole Field Navigation; TMECH Feb. 2021 214-225
- Shi, Y., see Zhang, K., TMECH April 2021 700-708
- Shi, Y., see Guo, Q., TMECH Aug. 2021 2048-2058
- Shim, Y., see Lee, M., TMECH Feb. 2021 191-202
- Shimonomura, S., Fang, J., Liu, K., Yamaguchi, T., Akiyama, T., and Sugiura, K., A Phase-Shaping Approach to the Control of Parametric Systems and Its Application; TMECH Aug. 2021 2163-2173
- Shojaei, K., Kazemy, A., and Chatraei, A., An Observer-Based Neural Adaptive\$PID^2\$ Controller for Robot Manipulators Including Motor Dynamics With a Prescribed Performance; TMECH June 2021 1689-1699
- Shokrollahi, P., Lai, Y.P., Rash-Ahmadi, S., Stewart, V., Mohammadigheisar, M., Huber, L., Matsuura, N., Zavodni, A.E.H., Parkinson, J., and Diller, E., Blindly Controlled Magnetically Actuated Capsule for Noninvasive Sampling of the Gastrointestinal Microbiome; TMECH Oct. 2021 2616-2628 Shon, H.W., see Song, S.H., TMECH Feb. 2021 267-275

- Shyrokau, B., see Lazcano, A.M., TMECH June 2021 1201-1211
- Si, J., see Gan, C., TMECH April 2021 1118-1128
- Sim, O., see Oh, J., TMECH Feb. 2021 102-112
- Sim, S., see Lee, S., TMECH June 2021 1358-1368
- Simaan, N., see Giudice, G.D., TMECH Oct. 2021 2604-2615
- Simetti, E., Campos, R., Vito, D.D., Quintana, J., Antonelli, G., Garcia, R., and Turetta, A., Sea Mining Exploration With an UVMS: Experimental Validation of the Control and Perception Framework; TMECH June 2021 1635-1645
- Siqueira, A.A.G., see Escalante, F.M., TMECH Feb. 2021 491-502
- Sivanantham, V., see Megalingam, R.K., TMECH Feb. 2021 288-299
- Smit, G., see Vertongen, J., TMECH April 2021 955-965
- Soldati, A., see Dalboni, M., TMECH June 2021 1212-1224
- Song, C., see Huang, Y., TMECH Aug. 2021 2174-2185
- Song, C., see Liu, S., TMECH Oct. 2021 2747-2757
- Song, D., see Li, G., TMECH June 2021 1479-1489
- Song, J., see Jeon, H., TMECH June 2021 1401-1411
- Song, P., see Dong, X., TMECH Feb. 2021 427-436
- Song, R., see Zhou, J., TMECH Dec. 2021 3128-3138
- Song, S.H., Yeon, G.Y., Shon, H.W., and Choi, H.R., Design and Control of Soft Unmanned Aerial Vehicle "S-CLOUD" TMECH Feb. 2021 267-275
- Song, Y., Wu, J., Liu, Z., Zhang, B., and Huang, T., Similitude Analysis Method of the Dynamics of a Hybrid Spray-Painting Robot Considering Electromechanical Coupling Effect; TMECH Dec. 2021 2986-2997
- Sorniotti, A., see Dalboni, M., TMECH June 2021 1212-1224
- Spinks, G.M., see Tawk, C., TMECH April 2021 876-887
- Spyrakos-Papastavridis, E., see Fu, Z., TMECH Oct. 2021 2688-2699
- Stelson, K.A., see Wang, F., TMECH Feb. 2021 78-89
- Stevenson, D.T., see Chen, S., TMECH Aug. 2021 1989-1996
- Stewart, V., see Shokrollahi, P., TMECH Oct. 2021 2616-2628
- Stommel, M., see Hashem, R., TMECH Oct. 2021 2327-2338
- Strada, S.C., see Pozzato, G., TMECH April 2021 830-840
- Su, C., see Liu, Y., TMECH April 2021 657-667
- Su, C., see Li, Z., TMECH Oct. 2021 2700-2711
- Su, H., see Li, G., TMECH Feb. 2021 255-266
- Su, H., see Liu, Y., TMECH April 2021 657-667
- Su, H., see Chen, S., TMECH Aug. 2021 1989-1996
- Sugano, S., see Kamezaki, M., TMECH Dec. 2021 2857-2869
- Sugiura, K., see Shimonomura, S., TMECH Aug. 2021 2163-2173
- Sun, C., Wang, C., Deng, Z., and Cao, D., Dimensionless Model-Based System Tracking Via Augmented Kalman Filter for Multiscale Unmanned Ground Vehicles; TMECH April 2021 600-610
- Sun, F., see Zhao, C., TMECH Feb. 2021 437-447
- Sun, L., see Li, G., TMECH June 2021 1479-1489
- Sun, Q., see Gan, C., TMECH April 2021 1118-1128
- Sun, X., see Liu, G., TMECH June 2021 1602-1612
- Sun, Y., see Liu, X., TMECH April 2021 1178-1182
- Sun, Y., see Zhao, J., TMECH Aug. 2021 2038-2047
- Sun, Y., see Zhao, J., TMECH Aug. 2021 2038-2047
- Sundarsingh, E.F., see Abirami B, S., TMECH Oct. 2021 2814-2817
- Suzuki, K., see Chen, Y., TMECH Aug. 2021 2007-2015
- Syed, D.F., see Mishra, S., TMECH Aug. 2021 1914-1922

Т

- Tadesse, Y., see Karami, F., TMECH Feb. 2021 300-310
- Takagi, K., see Kato, T., TMECH Oct. 2021 2451-2461
- Takazawa, J., see Miura, S., TMECH April 2021 1013-1021
- Takeyama, T., O-Tani, H., Oishi, S., Hori, M., and Iizuka, A., Automatic Construction of Three-Dimensional Ground Model by Data Processing; TMECH Dec. 2021 2881-2887
- Tan, J., see Liu, X., TMECH June 2021 1536-1546
- Tan, J., see Liu, S., TMECH Oct. 2021 2747-2757
- Tan, J.H., see Cai, C.J., TMECH June 2021 1678-1688
- Tan, M., see Yan, S., TMECH Oct. 2021 2506-2516

- Tan, Q., Zhang, X., Liu, H., Jiao, S., Zhou, M., and Li, J., Multimodal Dynamics Analysis and Control for Amphibious Fly-Drive Vehicle; TMECH April 2021 621-632
- Tanabe, T., Yano, H., Endo, H., Ino, S., and Iwata, H., Pulling Illusion Based on the Phase Difference of the Frequency Components of Asymmetric Vibrations; TMECH Feb. 2021 203-213
- Tanaka, H., see Shen, Y., TMECH Oct. 2021 2350-2361
- Tanelli, M., see Pozzato, G., TMECH April 2021 830-840
- Tang, B., see Lu, W., TMECH June 2021 1613-1623
- Tang, C., Tian, G.Y., and Wu, J., Segmentation-Oriented Compressed Sensing for Efficient Impact Damage Detection on CFRP Materials ; TMECH Oct. 2021 2528-2537
- Tang, H., He, S., Zhu, Z., Gao, J., Zhang, L., Cui, C., and Chen, X., A Monolithic Force Sensing Integrated Flexure Bonder Dedicated to Flip-Chip Active Soft-Landing Interconnection; TMECH Feb. 2021 323-334
- Tang, J., see Zhao, C., TMECH Feb. 2021 437-447
- Tao, B., see Zhang, Y., TMECH April 2021 990-1001
- Tao, Q., Wang, J., Xu, Z., Lin, T.X., Yuan, Y., and Zhang, F., Swing-Reducing Flight Control System for an Underactuated Indoor Miniature Autonomous Blimp; TMECH Aug. 2021 1895-1904
- Tao, Y., Li, H., and Zhu, L., Time/Space-Separation-Based Gaussian Process Modeling for the Cross-Coupling Effect of a 2-DOF Nanopositioning Stage; TMECH Aug. 2021 2186-2194
- Tavernini, D., see Dalboni, M., TMECH June 2021 1212-1224
- Tawk, C., Zhou, H., Sariyildiz, E., in het Panhuis, M., Spinks, G.M., and Alici, G., Design, Modeling, and Control of a 3D Printed Monolithic Soft Robotic Finger With Embedded Pneumatic Sensing Chambers; TMECH April 2021 876-887
- Taylor, R.H., see Sefati, S., TMECH Feb. 2021 369-380
- Taylor, R.H., see Wang, Y., TMECH Aug. 2021 1858-1866
- Teja, P.S., see Megalingam, R.K., TMECH Feb. 2021 288-299
- Teng, M., Ye, L., Yuxin, Z., Yanqing, J., Qianyi, Z., and Pascoal, A.M., Efficient Bathymetric SLAM With Invalid Loop Closure Identification; TMECH Oct. 2021 2570-2580
- Terra, M.H., see Escalante, F.M., TMECH Feb. 2021 491-502
- Thomas, D.G., see Rehan, M., TMECH Aug. 2021 1803-1811
- Thomas, G.C., Mehling, J.S., Holley, J., and Sentis, L., Phase-Relaxed-Passive Full State Feedback Gain Limits for Series Elastic Actuators; TMECH Feb. 2021 586-591
- Tian, G., see Gao, S., TMECH Feb. 2021 448-457
- Tian, G.Y., see Tang, C., TMECH Oct. 2021 2528-2537
- Tian, H., see Xia, J., TMECH Oct. 2021 2803-2813
- Tian, X., and Zhan, O., A Hermaphrodite Electromechanical Connector for Self-Reconfigurable Robot Modules ; TMECH Dec. 2021 3276-3281
- Tian, Y., see Liu, S., TMECH Feb. 2021 146-155
- Tian, Y., see Scharff, R.B.N., TMECH Aug. 2021 1877-1885
- Tian, Y., see Liu, Z., TMECH Aug. 2021 2195-2203
- Tijjani, A.S., Chemori, A., and Creuze, V., Robust Adaptive Tracking Control of Underwater Vehicles: Design, Stability Analysis, and Experiments; TMECH April 2021 897-907
- Tilli, A., see Bosso, A., TMECH June 2021 1501-1511
- Timonen, J., see Cenev, Z., TMECH Aug. 2021 1932-1940
- Tisnes, S.D., Petit, L., Prelle, C., and Lamarque, F., Modeling and Experimental Validation of a Planar Microconveyor Based on a 2 × 2 Array of Digital Electromagnetic Actuators; TMECH June 2021 1422-1432
- Tiwari, B., Blot, M., Laurent, G.J., Agnus, J., Sandoz, P., Lutz, P., and Clevy, C., A High Range-to-Resolution Multiaxis µForce and Torque Sensing Platform; TMECH Aug. 2021 1837-1845
- Tomizuka, M., see Kuang, Z., TMECH Feb. 2021 358-368
- Tong, L., see Liu, K., TMECH Dec. 2021 2944-2955
- Tong, S., see Liu, Y., TMECH Feb. 2021 168-178
- Toriumi, F.Y., and Angelico, B.A., Passivity-Based Nonlinear Control Approach for Tracking Task of an Underactuated CMG; TMECH Oct. 2021 2285-2293
- Towfighian, S., see Hossain, N.A., TMECH Dec. 2021 2967-2976

- Tran, V.P., Santoso, F., Garratt, M.A., and Petersen, I.R., Distributed Formation Control Using Fuzzy Self-Tuning of Strictly Negative Imaginary Consensus Controllers in Aerial Robotics; TMECH Oct. 2021 2306-2315
- Treios, A.L., see Edmonds, B.P.R., TMECH April 2021 966-977
- Tremblay, C.C., see Shi, Y., TMECH Feb. 2021 214-225
- Trinidad, J., see Olaizola, J., TMECH Oct. 2021 2418-2428
- Trkov, M., see Chen, S., TMECH Aug. 2021 1989-1996
- Trumper, D.L., see Zhou, L., TMECH April 2021 1084-1094
- Trumper, D.L., see Bhushan, B.M., TMECH Oct. 2021 2362-2372
- Tsai, W., Wu, C., and Cheng, M., Tracking Accuracy Improvement Based on Adaptive Nonlinear Sliding Mode Control; TMECH Feb. 2021 179-190 Tsao, T., see Gerber, M.J., TMECH Oct. 2021 2758-2769
- Tu, L., Du, H., Dong, M., Ning, D., Wu, Y., Li, W., and Huang, H., Semiactively Controllable Vehicle Seat Suspension System With Negative Stiffness Magnetic Spring; TMECH Feb. 2021 156-167
- Turetta, A., see Simetti, E., TMECH June 2021 1635-1645
- Tysse, G.O., Cibicik, A., and Egeland, O., Vision-Based Control of a Knuckle Boom Crane With Online Cable Length Estimation; TMECH Feb. 2021 416-426

U

- Ustinov, S., see Malysheva, J., TMECH Oct. 2021 2385-2395
- Uvet, H., see Demircali, A.A., TMECH Dec. 2021 2956-2966
- Uzunovic, T., see Sariyildiz, E., TMECH Aug. 2021 2139-2150

V

- Vadamalu, R.S., and Beidl, C., Adaptive Harmonic and Disturbance Estimators for Rotary Machines With Applications to Engines; TMECH Feb. 2021 381-392
- Vadivel, S.R.R., see Megalingam, R.K., TMECH Feb. 2021 288-299
- Vailati, L.G., and Goldfarb, M., A Method for Mass Flow and Displacement Estimation in a Pneumatic Actuation System Using Valve-Based Pressure Sensing; TMECH Feb. 2021 235-245
- Vallery, H., see Vertongen, J., TMECH April 2021 955-965
- Vanderborght, B., see Chen, X., TMECH Aug. 2021 1705-1707
- Vanderborght, B., see Crispel, S., TMECH Aug. 2021 1980-1988
- Varadharajan, A., see Crispel, S., TMECH Aug. 2021 1980-1988
- Varol, R., see Demircali, A.A., TMECH Dec. 2021 2956-2966
- Venancio, M.M., Gonalves, R.S., Bianchi, R.A.d.C., Terrain Identification for Humanoid Robots Applying Convolutional Neural Networks; TMECH June 2021 1433-1444
- Verstraten, T., see Crispel, S., TMECH Aug. 2021 1980-1988
- Vertongen, J., Kamper, D.G., Smit, G., and Vallery, H., Mechanical Aspects of Robot Hands, Active Hand Orthoses, and Prostheses: A Comparative Review; TMECH April 2021 955-965
- Vikrant, K.S., Hithiksha, K., and Jayanth, G.R., An Automated AFM Tip-Replacement System for In Situ Tip-Replacement; TMECH April 2021 798-806 Vito, D.D., see Simetti, E., TMECH June 2021 1635-1645

W

- Wagner, J.R., see Wang, C., TMECH April 2021 777-788
- Walker, I.D., see Wang, C., TMECH April 2021 777-788
- Wang, A., see Zhao, W., TMECH June 2021 1558-1569
- Wang, B., see Wang, C., TMECH April 2021 908-917
- Wang, B., see Huo, X., TMECH Dec. 2021 2899-2909
- Wang, C., Frazelle, C.G., Wagner, J.R., and Walker, I.D., Dynamic Control of Multisection Three-Dimensional Continuum Manipulators Based on Virtual Discrete-Jointed Robot Models; TMECH April 2021 777-788
- Wang, C., see Sun, C., TMECH April 2021 600-610
- Wang, C., Wang, B., Deng, Z., and Fu, M., A Delaunay Triangulation-Based Matching Area Selection Algorithm for Underwater Gravity-Aided Inertial Navigation; TMECH April 2021 908-917
- Wang, C., see Zheng, S., TMECH Dec. 2021 3031-3039
- Wang, C.C., see Scharff, R.B.N., TMECH Aug. 2021 1877-1885

3295

- Wang, D., see Wang, Y., TMECH April 2021 719-729
- Wang, D., see Yue, Y., TMECH April 2021 978-989
- Wang, D., see Lu, W., TMECH June 2021 1613-1623
- Wang, F., see Liu, S., TMECH Feb. 2021 146-155
- Wang, F., Zhang, H., Xu, B., and Stelson, K.A., Steady-State Characteristics Study of a Power Split Hydraulic Transmission; *TMECH Feb. 2021 78-89*
- Wang, F., see Huang, Y., TMECH Feb. 2021 33-44
- Wang, F., Qian, Z., Lin, Y., and Zhang, W., Design and Rapid Construction of a Cost-Effective Virtual Haptic Device; *TMECH Feb. 2021 66-77*
- Wang, F., see Liu, Z., TMECH Aug. 2021 2195-2203
- Wang, G., Chadli, M., and Basin, M.V., Practical Terminal Sliding Mode Control of Nonlinear Uncertain Active Suspension Systems With Adaptive Disturbance Observer; *TMECH April 2021 789-797*
- Wang, H., Wang, X., Yang, W., Du, Z., and Yan, Z., Construction of Controller Model of Notch Continuum Manipulator for Laryngeal Surgery Based on Hybrid Method; *TMECH April 2021 1022-1032*
- Wang, H., see Oncken, J., TMECH June 2021 1248-1259
- Wang, H., see Zhou, S., TMECH June 2021 1467-1478
- Wang, H., see Bao, J., TMECH June 2021 1570-1580
- Wang, H., see Han, L., TMECH Aug. 2021 2016-2026
- Wang, J., and Han, Q., Neurodynamics-Based Model Predictive Control of Continuous-Time Under-Actuated Mechatronic Systems; *TMECH Feb.* 2021 311-322
- Wang, J., see Wang, J., TMECH Feb. 2021 311-322
- Wang, J., see Gong, X., TMECH June 2021 1271-1282
- Wang, J., see Guo, J., TMECH Aug. 2021 2151-2162
- Wang, J., see Tao, Q., TMECH Aug. 2021 1895-1904
- Wang, J., see Yan, S., TMECH Oct. 2021 2506-2516
- Wang, J., see Chen, J., TMECH Oct. 2021 2770-2781
- Wang, L., see Liu, Z., TMECH April 2021 1140-1150
- Wang, L., see Du, H., TMECH June 2021 1455-1466
- Wang, L., see Li, T., TMECH Dec. 2021 3040-3050
- Wang, L., see Cao, C., TMECH Dec. 2021 3151-3162
- Wang, M., see Zhao, J., TMECH Aug. 2021 2038-2047
- Wang, M., see Ba, W., TMECH Dec. 2021 3010-3021
- Wang, N., see Lu, Z., TMECH Dec. 2021 3265-3275
- Wang, N., and Ahn, C.K., Coordinated Trajectory-Tracking Control of a Marine Aerial-Surface Heterogeneous System; *TMECH Dec. 2021 3198-3210*
- Wang, Q., see Gao, S., TMECH Feb. 2021 448-457
- Wang, Q., see Liu, W., TMECH Aug. 2021 1846-1857
- Wang, Q., see Gao, S., TMECH Oct. 2021 2429-2439
- Wang, Q., see Zheng, E., TMECH Oct. 2021 2373-2384
- Wang, T., Liu, Y., Xu, Q., and Han, D., Novel Structure for Waveform Control of Twin Rotary Flowrate Valve Controlled Vibration Exciter; *TMECH April* 2021 1183-1188
- Wang, T.D., see Birla, M., TMECH June 2021 1445-1454
- Wang, X., see Dong, X., TMECH Feb. 2021 427-436
- Wang, X., see Wang, H., TMECH April 2021 1022-1032
- Wang, X., see Lu, W., TMECH June 2021 1613-1623
- Wang, X., and Zhou, K., Electrical Parameter Identification of Medium-Frequency DC Resistance Spot Welding System Using Intelligent Algorithm; *TMECH Aug. 2021 1791-1802*
- Wang, X., see Zhou, J., TMECH Dec. 2021 3128-3138
- Wang, Y., Yue, Y., Shan, M., He, L., and Wang, D., Formation Reconstruction and Trajectory Replanning for Multi-UAV Patrol; *TMECH April 2021 719-729*
- Wang, Y., see Zhu, Y., TMECH April 2021 1151-1160
- Wang, Y., see Yue, Y., TMECH April 2021 978-989
- Wang, Y., Xu, L., Zhang, F., Dong, H., Liu, Y., and Yin, G., An Adaptive Fault-Tolerant EKF for Vehicle State Estimation With Partial Missing Measurements; *TMECH June 2021 1318-1327*
- Wang, Y., see Chen, J., TMECH Aug. 2021 1737-1744
- Wang, Y., see Chen, S., TMECH Aug. 2021 1745-1753
- Wang, Y., Yip, H., Zheng, H., Lin, H., Taylor, R.H., and Au, K.W.S., Design and Experimental Validation of a Miniaturized Robotic Tendon-Driven Articulated Surgical Drill for Enhancing Distal Dexterity in Minimally Invasive Spine Fusion; *TMECH Aug. 2021 1858-1866*

- Wang, Y., see Ma, B., TMECH Aug. 2021 1968-1979
- Wang, Y., see Pal, A., TMECH Dec. 2021 3116-3127
- Wang, Z., see Gao, S., TMECH Feb. 2021 448-457
- Wang, Z., Zou, Y., Liu, Y., and Meng, Z., Distributed Control Algorithm for Leader–Follower Formation Tracking of Multiple Quadrotors: Theory and Experiment; *TMECH April 2021 1095-1105*
- Wang, Z., see Li, J., TMECH June 2021 1591-1601
- Wang, Z., Hu, C., Zhu, Y., and Zhu, L., Prediction-Model-Based Contouring Error Iterative Precompensation Scheme for Precision Multiaxis Motion Systems; *TMECH Oct. 2021 2274-2284*
- Wang, Z., see Liu, S., TMECH Oct. 2021 2747-2757
- Wasserfall, F., see Ahlers, D., TMECH Aug. 2021 1886-1894
- Wei, J., see Zhao, J., TMECH Aug. 2021 2038-2047
- Wei, S., see Zhu, H., TMECH Oct. 2021 2712-2723
- Wei, Y., and Xu, Q., Design and Testing of a New Force-Sensing Cell Microinjector Based on Small-Stiffness Compliant Mechanism; *TMECH April 2021* 818-829
- Wen, B., see Zhang, X., TMECH April 2021 807-817
- Wen, S., see Farivar, F., TMECH June 2021 1350-1357
- Weng, C., see Dong, H., TMECH Aug. 2021 2215-2225
- Widanage, W.D., see Liu, K., TMECH Dec. 2021 2944-2955
- Williams, H., see Zhou, Q., TMECH June 2021 1225-1235
- Willing, R., see Hossain, N.A., TMECH Dec. 2021 2967-2976
- Wong, C., Mineo, C., Yang, E., Yan, X., and Gu, D., A Novel Clustering-Based Algorithm for Solving Spatially Constrained Robotic Task Sequencing Problems; *TMECH Oct. 2021 2294-2305*
- Wong, P.K., see Huang, W., TMECH Aug. 2021 2071-2079
- Wu, C., see Tsai, W., TMECH Feb. 2021 179-190
- Wu, C., see Chen, J., TMECH Aug. 2021 1737-1744
- Wu, J., see Liu, Z., TMECH April 2021 1140-1150
- Wu, J., see Gan, C., TMECH April 2021 1118-1128
- Wu, J., Liu, M., Zhu, Y., Zou, Z., Dai, M., Zhang, C., Jiang, Y., and Li, C., Globally Optimal Symbolic Hand-Eye Calibration; *TMECH June 2021* 1369-1379
- Wu, J., see Scharff, R.B.N., TMECH Aug. 2021 1877-1885
- Wu, J., see Zhang, C., TMECH Aug. 2021 2226-2236
- Wu, J., Zhu, J., Xu, Z., and Xia, H., A DC-Biased Scanning Induction Thermographic System for Characterizing Surface Cracks in Ferromagnetic Components; *TMECH Oct. 2021 2782-2790*
- Wu, J., see Tang, C., TMECH Oct. 2021 2528-2537
- Wu, J., see Song, Y., TMECH Dec. 2021 2986-2997
- Wu, L., see Karami, F., TMECH Feb. 2021 300-310
- Wu, Q., see Xiao, X., TMECH Oct. 2021 2483-2494
- Wu, X., see Li, Z., TMECH Oct. 2021 2700-2711
- Wu, Y., see Tu, L., TMECH Feb. 2021 156-167
- Wu, Y., Li, G., Zuo, Z., Liu, X., and Xu, P., Practical Fixed-Time Position Tracking Control of Permanent Magnet DC Torque Motor Systems; *TMECH Feb.* 2021 563-573
- Wu, Y., see Lu, W., TMECH June 2021 1613-1623
- Wu, Y., see Xiao, X., TMECH Oct. 2021 2483-2494
- Wu, Y., see Liu, N., TMECH Dec. 2021 3139-3150
- Wu, Z., see Yue, Y., TMECH April 2021 978-989
- Wu, Z., see Yan, S., TMECH Oct. 2021 2506-2516

Х

- Xia, H., see Wu, J., TMECH Oct. 2021 2782-2790
- Xia, J., Jiang, Z., Zhang, H., Zhu, R., and Tian, H., Dual Fast Marching Tree Algorithm for Human-Like Motion Planning of Anthropomorphic Arms With Task Constraints; *TMECH Oct. 2021 2803-2813*
- Xia, X., see Yang, W., TMECH Feb. 2021 246-254
- Xia, Z., see Xiong, J., TMECH Dec. 2021 3211-3220

Xian, B., and Yang, S., Robust Tracking Control of a Quadrotor Unmanned Aerial Vehicle-Suspended Payload System; *TMECH Oct. 2021 2653-2663*

Xiao, X., see Cai, C.J., TMECH June 2021 1678-1688

- Xiao, X., Li, C., Gu, X., Yan, Y., Wu, Y., Wu, Q., Chiong, E., and Ren, H., A Tubular Dual-Roller Bending Mechanism Toward Robotic Transurethral Prostate Biopsy; *TMECH Oct. 2021 2483-2494*
- Xie, G., Shangguan, A., Fei, R., Hei, X., Ji, W., and Qian, F., Unmanned System Safety Decision-Making Support: Analysis and Assessment of Road Traffic Accidents; *TMECH April 2021 633-644*
- Xie, H., Li, W., Jiang, C., Zhu, D., Yin, Z., and Ding, H., Pose Error Estimation Using a Cylinder in Scanner-Based Robotic Belt Grinding; *TMECH Feb.* 2021 515-526
- Xie, S., see Zhao, J., TMECH Aug. 2021 2038-2047
- Xie, Z., see Jin, L., TMECH Feb. 2021 90-101

3296

- Xie, Z., see Zhao, J., TMECH Aug. 2021 2038-2047
- Xin, J., see Muhammad, I., TMECH Dec. 2021 2845-2856
- Xing, Y., see Huang, C., TMECH April 2021 611-620
- Xinge, Z., see Muhammad, I., TMECH Dec. 2021 2845-2856
- Xiong, C., see Cao, Y., TMECH Feb. 2021 574-585
- Xiong, J., Xu, C., Ibrahim, K., Deng, H., and Xia, Z., A Mechanism-Image Fusion Approach to Calibration of an Ultrasound-Guided Dual-Arm Robotic Brachytherapy System; *TMECH Dec. 2021 3211-3220*
- Xu, B., see Wang, F., TMECH Feb. 2021 78-89
- Xu, B., see Ding, R., TMECH Oct. 2021 2558-2569
- Xu, C., see Xiong, J., TMECH Dec. 2021 3211-3220
- Xu, F., see Zhao, C., TMECH Feb. 2021 437-447
- Xu, G., see Liu, F., TMECH Feb. 2021 113-123
- Xu, H., see Zhou, Q., TMECH June 2021 1225-1235
- Xu, J., see Jiang, N., TMECH Oct. 2021 2641-2652
- Xu, K., see Chen, J., TMECH June 2021 1624-1634
- Xu, L., see Zhao, B., TMECH April 2021 943-954
- Xu, L., see Zhou, Q., TMECH June 2021 1225-1235
- Xu, L., see Wang, Y., TMECH June 2021 1318-1327
- Xu, L., see Deng, Z., TMECH June 2021 1295-1306
- Xu, P., see Wu, Y., TMECH Feb. 2021 563-573
- Xu, Q., see Wei, Y., TMECH April 2021 818-829
- Xu, Q., see Wang, T., TMECH April 2021 1183-1188
- Xu, S., see Li, G., TMECH June 2021 1479-1489
- Xu, W., see Liu, T., TMECH April 2021 930-942
- Xu, W., see Hashem, R., TMECH Oct. 2021 2327-2338
- Xu, Y., Guo, K., Li, J., and Li, Y., A Novel Rotational Actuator With Variable Stiffness Using S-Shaped Springs; *TMECH Aug. 2021 2249-2260*
- Xu, Z., see Tao, Q., TMECH Aug. 2021 1895-1904
- Xu, Z., see Wu, J., TMECH Oct. 2021 2782-2790
- Xuan, F., see Bu, F., TMECH April 2021 1129-1139
- Xue, W., see Li, H., TMECH April 2021 841-853
- Xue, X., see Pang, X., TMECH Aug. 2021 2027-2037

Y

- Yamaguchi, T., see Shimonomura, S., TMECH Aug. 2021 2163-2173
- Yamashita, A., see Kasahara, J.Y.L., TMECH Dec. 2021 2826-2834
- Yamashita, A., see Cheah, C.C., TMECH Dec. 2021 2819-2825
- Yamazaki, K., see Li, Y., TMECH Dec. 2021 2977-2985
- Yamomo, G.G., see Hossain, N.A., TMECH Dec. 2021 2967-2976
- Yan, F., see Zhou, Q., TMECH June 2021 1225-1235
- Yan, G., see Gao, J., TMECH Feb. 2021 55-65
- Yan, J., see Zhang, Z., TMECH Aug. 2021 1997-2006
- Yan, S., see Chen, H., TMECH Feb. 2021 469-479
- Yan, S., Wu, Z., Wang, J., Tan, M., and Yu, J., Efficient Cooperative Structured Control for a Multijoint Biomimetic Robotic Fish; *TMECH Oct. 2021 2506-2516*
- Yan, X., see Wong, C., TMECH Oct. 2021 2294-2305
- Yan, Y., see Xiao, X., TMECH Oct. 2021 2483-2494
- Yan, Z., see Wang, H., TMECH April 2021 1022-1032
- Yang, C., see Jin, L., TMECH Feb. 2021 90-101
- Yang, C., see Yue, Y., TMECH April 2021 978-989

+ Check author entry for coauthors

- Yang, C., see Lu, Z., TMECH Dec. 2021 3265-3275
- Yang, E., see Wong, C., TMECH Oct. 2021 2294-2305
- Yang, H., see Zhu, Y., TMECH April 2021 1151-1160

- Yang, H., see Li, L., TMECH April 2021 918-929
- Yang, J., see Zeng, R., TMECH June 2021 1581-1590
- Yang, L., see Du, X., TMECH June 2021 1524-1535
- Yang, L., see Yang, Z., TMECH Dec. 2021 3163-3174
- Yang, L., see Cheah, C.C., TMECH Dec. 2021 2819-2825
- Yang, S., and Lee, Y., Ultraviolet Beam Lithography System for Digital Fabrication of Roller Molds; *TMECH Feb. 2021 226-234*
- Yang, S., Kernel-Orthogonal Control of Tensegrity Systems; TMECH April 2021 1043-1052
- Yang, S., see Lee, J., TMECH Aug. 2021 1820-1827
- Yang, S., see Xian, B., TMECH Oct. 2021 2653-2663
- Yang, S.Y., see Jung, H.S., TMECH April 2021 1002-1012
- Yang, T., see Liu, T., TMECH April 2021 930-942
- Yang, W., Zhang, C., Dai, H., Hu, C., and Xia, X., A Novel Wireless 5-D Electromagnetic Tracking System Based on Nine-Channel Sinusoidal Signals; *TMECH Feb. 2021 246-254*
- Yang, W., see Wang, H., TMECH April 2021 1022-1032
- Yang, X., see Gao, S., TMECH Feb. 2021 448-457
- Yang, X., see Zhao, B., TMECH April 2021 943-954
- Yang, Y., see Zhu, Y., TMECH April 2021 1151-1160
- Yang, Z., see Bu, F., TMECH April 2021 1129-1139
- Yang, Z., Yang, L., and Zhang, L., Autonomous Navigation of Magnetic Microrobots in a Large Workspace Using Mobile-Coil System ; *TMECH Dec.* 2021 3163-3174
- Yang, Z., see Shi, C., TMECH Dec. 2021 3076-3086
- Yano, H., see Tanabe, T., TMECH Feb. 2021 203-213
- Yanqing, J., see Teng, M., TMECH Oct. 2021 2570-2580
- Yao, B., see Lin, Y., TMECH Aug. 2021 1905-1913
- Yao, B., see Helian, B., TMECH Oct. 2021 2593-2603
- Yao, J., see Deng, W., TMECH Aug. 2021 2204-2214
- Yazdanpanah, M.J., see Sharbafi, M.A., TMECH Feb. 2021 335-346
- Ye, L., see Teng, M., TMECH Oct. 2021 2570-2580
- Yeon, G.Y., see Song, S.H., TMECH Feb. 2021 267-275
- Yeow, B.S., see Cai, C.J., TMECH June 2021 1678-1688
- Yi, J., see Chen, S., TMECH Aug. 2021 1989-1996
- Yi, J., see Li, T., TMECH Dec. 2021 3040-3050
- Yi, L., see Rayguru, M.M., TMECH June 2021 1236-1247
- Yi, Y., see Li, Z., TMECH June 2021 1339-1349
- Yin, G., see Wang, Y., TMECH June 2021 1318-1327
- Yin, Z., see Xie, H., TMECH Feb. 2021 515-526
- Ying, K., see Muhammad, I., TMECH Dec. 2021 2845-2856
- Yip, H., see Wang, Y., TMECH Aug. 2021 1858-1866
- Yoo, S., see Seo, M., TMECH Aug. 2021 1812-1819
- Yoo, S., Kim, T., Seo, M., Oh, J., Kim, H.S., and Seo, T., Position-Tracking Control of Dual-Rope Winch Robot With Rope Slip Compensation; *TMECH* Aug. 2021 1754-1762

Yue, Y., Zhao, C., Wu, Z., Yang, C., Wang, Y., and Wang, D., Collaborative

Semantic Understanding and Mapping Framework for Autonomous Sys-

- Yoon, J., see Haghjoo, M.R., TMECH Feb. 2021 13-23
- Yoon, J., see Le, T., TMECH Feb. 2021 551-562
- Yoon, J.Y., see Bhushan, B.M., TMECH Oct. 2021 2362-2372
- Yu, G., see Huang, W., TMECH Aug. 2021 2071-2079
- Yu, G., see Chen, J., TMECH Aug. 2021 1737-1744
- Yu, H., see Li, D., TMECH April 2021 709-718
- Yu, H., see Zhou, W., *TMECH Aug. 2021 1773-1781* Yu, H., see Dong, H., *TMECH Aug. 2021 2215-2225*

Yu, H., see Zhong, Y., TMECH Dec. 2021 2998-3009

Yu, J., see Du, X., TMECH June 2021 1524-1535

Yu, J., see Yan, S., *TMECH Oct. 2021 2506-2516* Yu, S., see Chen, S., *TMECH Aug. 2021 1989-1996*

Yu, Z., see Li, Q., TMECH April 2021 679-688

tems; TMECH April 2021 978-989

Yu, J., see Chen, G., TMECH June 2021 1547-1557

Yuan, S., see Zhao, J., *TMECH Aug. 2021 2038-2047* Yuan, Y., see Tao, Q., *TMECH Aug. 2021 1895-1904*

Yue, Y., see Wang, Y., TMECH April 2021 719-729

Yuxin, Z., see Teng, M., TMECH Oct. 2021 2570-2580

Z

- Zanoni, C., and Bortoluzzi, D., Estimation of the Electrostatic Effects in the LISA-Pathfinder Critical Test Mass Dynamics via the Method of Moments; *TMECH Dec. 2021 3022-3030*
- Zavodni, A.E.H., see Shokrollahi, P., TMECH Oct. 2021 2616-2628
- Zemouche, A., see Jeon, W., TMECH Aug. 2021 1941-1950
- Zeng, R., Kang, Y., Yang, J., Qin, B., Chen, S., and Cao, D., An Integrated Terrain Identification Framework for Mobile Robots: System Development, Analysis, and Verification; *TMECH June 2021 1581-1590*
- Zeng, Z., see Guan, Y., TMECH April 2021 864-875
- Zhai, G., see Zhang, Z., TMECH Aug. 2021 1997-2006
- Zhan, L., see Zhou, W., TMECH Aug. 2021 1773-1781
- Zhan, Q., see Tian, X., TMECH Dec. 2021 3276-3281
- Zhang, B., see Liu, Z., TMECH April 2021 1140-1150
- Zhang, B., see Chen, G., TMECH June 2021 1547-1557
- Zhang, B., Shang, W., Cong, S., and Li, Z., Coordinated Dynamic Control in the Task Space for Redundantly Actuated Cable-Driven Parallel Robots; *TMECH Oct. 2021 2396-2407*
- Zhang, B., see Song, Y., TMECH Dec. 2021 2986-2997
- Zhang, C., see Yang, W., TMECH Feb. 2021 246-254
- Zhang, C., see Wu, J., TMECH June 2021 1369-1379
- Zhang, C., Na, J., Wu, J., Chen, Q., and Huang, Y., Proportional-Integral Approximation-Free Control of Robotic Systems With Unknown Dynamics ; *TMECH Aug. 2021 2226-2236*
- Zhang, D., see Liu, S., TMECH Feb. 2021 146-155
- Zhang, D., see Duan, H., TMECH Feb. 2021 458-468
- Zhang, D., see Liu, Z., TMECH Aug. 2021 2195-2203
- Zhang, D., see Jiang, N., TMECH Oct. 2021 2641-2652
- Zhang, F., see Zheng, M., TMECH Feb. 2021 45-54
- Zhang, F., see Wang, Y., TMECH June 2021 1318-1327
- Zhang, F., see Tao, Q., TMECH Aug. 2021 1895-1904
- Zhang, H., see Wang, F., TMECH Feb. 2021 78-89
- Zhang, H., see Zhao, W., TMECH June 2021 1558-1569
- Zhang, H., see Huang, Y., TMECH Aug. 2021 2174-2185
- Zhang, H., see Xia, J., TMECH Oct. 2021 2803-2813
- Zhang, H., Lerner, E., Cheng, B., and Zhao, J., Compliant Bistable Grippers Enable Passive Perching for Micro Aerial Vehicles; *TMECH Oct. 2021* 2316-2326
- Zhang, J., see Zhao, B., TMECH April 2021 943-954
- Zhang, J., see Ahlers, D., TMECH Aug. 2021 1886-1894
- Zhang, K., Shi, Y., and Sheng, H., Robust Nonlinear Model Predictive Control Based Visual Servoing of Quadrotor UAVs; *TMECH April 2021 700-708*
- Zhang, L., see Tang, H., TMECH Feb. 2021 323-334
- Zhang, L., see Zhu, Y., TMECH April 2021 1151-1160
- Zhang, L., see Du, X., TMECH June 2021 1524-1535
- Zhang, L., see Li, Z., TMECH Oct. 2021 2700-2711
- Zhang, L., see Yang, Z., TMECH Dec. 2021 3163-3174
- Zhang, M., see Du, X., TMECH June 2021 1524-1535
- Zhang, Q., see Gao, S., TMECH Feb. 2021 448-457
- Zhang, S., see Deng, J., TMECH Aug. 2021 2059-2070
- Zhang, S., see Jiang, N., TMECH Oct. 2021 2641-2652
- Zhang, T., see Guan, Y., TMECH April 2021 864-875
- Zhang, T., see Li, Z., TMECH Oct. 2021 2700-2711
- Zhang, W., see Liu, S., TMECH Feb. 2021 146-155
- Zhang, W., see Wang, F., TMECH Feb. 2021 66-77
- Zhang, W., see Mishra, S., TMECH Aug. 2021 1914-1922
- Zhang, X., see Cao, L., TMECH Feb. 2021 480-490
- Zhang, X., Li, Z., Li, M., and Wen, B., Stability and Sommerfeld Effect of a Vibrating System With Two Vibrators Driven Separately by Induction Motors; *TMECH April 2021 807-817*
- Zhang, X., see Tan, Q., TMECH April 2021 621-632
- Zhang, X., see Gao, Y., TMECH June 2021 1283-1294
- Zhang, X., see Han, L., TMECH Aug. 2021 2016-2026
- Zhang, X., see Huang, Y., TMECH Aug. 2021 2174-2185
- Zhang, Y., see Liu, Y., TMECH Feb. 2021 168-178
- Zhang, Y., see Zhao, B., TMECH April 2021 943-954

- Zhang, Y., Zhao, X., Tao, B., and Ding, H., Point Stabilization of Nonholonomic Mobile Robot by Bézier Smooth Subline Constraint Nonlinear Model Predictive Control; *TMECH April 2021 990-1001*
- Zhang, Y., and Ji, J., Intelligent Fault Diagnosis of a Reciprocating Compressor Using Mode Isolation Convolutional Deep Belief Networks; *TMECH June* 2021 1668-1677
- Zhang, Z., see Gao, J., TMECH Feb. 2021 55-65
- Zhang, Z., Yan, J., Kong, X., Zhai, G., and Liu, Y., Efficient Motion Planning Based on Kinodynamic Model for Quadruped Robots Following Persons in Confined Spaces; *TMECH Aug. 2021 1997-2006*
- Zhang, Z., see Liu, S., TMECH Oct. 2021 2747-2757
- Zhang, Z., Chen, S., Deng, X., and Liang, J., A Circadian Rhythms Neural Network for Solving the Redundant Robot Manipulators Tracking Problem Perturbed by Periodic Noise; *TMECH Dec.* 2021 3232-3242
- Zhao, B., Lei, L., Xu, L., Li, S., Hu, Y., Zhang, J., Yang, X., and Zhang, Y., Needle Deflection Modeling and Preoperative Trajectory Planning During Insertion Into Multilayered Tissues; *TMECH April 2021 943-954*
- Zhao, C., Sun, F., Jin, J., Tang, J., Xu, F., Li, Q., and Oka, K., Analysis of Quasi-Zero Power Characteristic for a Permanent Magnetic Levitation System With a Variable Flux Path Control Mechanism; *TMECH Feb. 2021 437-447* Zhao, C., see Yue, Y., *TMECH April 2021 978-989*
- **Zhao, F.,** see Liu, X., *TMECH Dec. 2021 2888-2898*
- Zhao, H., Zhou, S., Chen, W., Miao, Z., and Liu, Y., Modeling and Motion Control of Industrial Tractor–Trailers Vehicles Using Force Compensation; *TMECH April 2021 645-656*
- Zhao, H., see Zhou, S., TMECH June 2021 1467-1478
- Zhao, J., Mou, Q., Zhu, C., Chen, Z., and Li, J., Study on a Double-Sided Permanent-Magnet Linear Synchronous Motor With Reversed Slots; *TMECH Feb. 2021 3-12*
- Zhao, J., Sun, Y., Ding, J., Sun, Y., Wang, M., Yuan, S., Pu, H., Luo, J., Xie, Z., Qin, Y., Wei, J., Xie, S., and Peng, Y., Shock Isolation Capability of an Electromagnetic Variable Stiffness Isolator With Bidirectional Stiffness Regulation
- ; TMECH Aug. 2021 2038-2047
- Zhao, J., see Huang, W., TMECH Aug. 2021 2071-2079
- Zhao, J., see Zhang, H., TMECH Oct. 2021 2316-2326
- Zhao, K., see Li, Z., TMECH Oct. 2021 2700-2711
- Zhao, Q., see Shao, S., TMECH April 2021 689-699
- Zhao, R., see Chen, H., TMECH Feb. 2021 469-479
- Zhao, W., Wang, A., Zou, S., and Zhang, H., Individual Auxiliary and Fault-Tolerant Control of Steer-by-Wire System Considering Different Drivers Steering Characteristics; *TMECH June 2021 1558-1569*
- Zhao, X., see Zhang, Y., TMECH April 2021 990-1001
- Zhao, X., see Meng, Q., TMECH June 2021 1307-1317
- Zhao, Z., see Zheng, E., TMECH Oct. 2021 2373-2384
- Zheng, E., Li, Y., Zhao, Z., Wang, Q., and Qiao, H., An Electrical Impedance Tomography Based Interface for Human–Robot Collaboration; *TMECH* Oct. 2021 2373-2384
- Zheng, H., see Wang, Y., TMECH Aug. 2021 1858-1866
- Zheng, M., Lyu, X., Liang, X., and Zhang, F., A Generalized Design Method for Learning-Based Disturbance Observer; *TMECH Feb. 2021 45-54*
- Zheng, S., see Ding, R., TMECH Oct. 2021 2558-2569
- Zheng, S., and Wang, C., Rotor Balancing for Magnetically Levitated TMPs Integrated With Vibration Self-Sensing of Magnetic Bearings; *TMECH Dec.* 2021 3031-3039
- Zhong, Y., Du, R., Guo, P., and Yu, H., Investigation on a New Approach for Designing Articulated Soft Robots With Discrete Variable Stiffness; *TMECH Dec.* 2021 2998-3009
- Zhou, H., see Tawk, C., TMECH April 2021 876-887
- Zhou, H., see Liu, K., TMECH Dec. 2021 2944-2955
- Zhou, J., Li, Z., Li, X., Wang, X., and Song, R., Human–Robot Cooperation Control Based on Trajectory Deformation Algorithm for a Lower Limb Rehabilitation Robot; *TMECH Dec. 2021 3128-3138*
- Zhou, K., see Wang, X., TMECH Aug. 2021 1791-1802
- Zhou, L., and Trumper, D.L., Magnetically Levitated Linear Stage With Linear Bearingless Slice Hysteresis Motors; *TMECH April 2021 1084-1094*
- Zhou, L., see Li, C.G., TMECH Oct. 2021 2263-2273

- Zhou, M., see Tan, Q., TMECH April 2021 621-632
- Zhou, N., and Li, D., Cyber–Physical Codesign of Field-Level Reconfigurations in Networked Motion Controllers; *TMECH Aug. 2021 2092-2103*
- Zhou, Q., Guo, S., Xu, L., Guo, X., Williams, H., Xu, H., and Yan, F., Global Optimization of the Hydraulic-Electromagnetic Energy-Harvesting Shock Absorber for Road Vehicles With Human-Knowledge-Integrated Particle Swarm Optimization Scheme; *TMECH June 2021 1225-1235*
- Zhou, Q., see Cenev, Z., TMECH Aug. 2021 1932-1940

Zhou, S., see Zhao, H., TMECH April 2021 645-656

- Zhou, S., Zhao, H., Chen, W., Liu, Z., Wang, H., and Liu, Y., Dynamic State Estimation and Control of a Heavy Tractor–Trailers Vehicle; *TMECH June* 2021 1467-1478
- Zhou, W., He, J., Ran, L., Chen, L., Zhan, L., Chen, Q., Yu, H., and Peng, B., A Piezoelectric Microultrasonic Motor With High Q and Good Mode Match; *TMECH Aug. 2021 1773-1781*
- Zhou, X., see Dong, M., TMECH June 2021 1490-1500

Zhou, X., see Fu, Z., TMECH Oct. 2021 2688-2699

Zhou, Y., see Dong, M., TMECH June 2021 1490-1500

Zhu, C., see Zhao, J., TMECH Feb. 2021 3-12

Zhu, C., see Gao, Y., TMECH June 2021 1283-1294

Zhu, D., see Xie, H., TMECH Feb. 2021 515-526

Zhu, H., see Guan, Y., TMECH April 2021 864-875

- Zhu, H., Lu, J., Gu, S., Wei, S., and Guan, Y., Planning Three-Dimensional Collision-Free Optimized Climbing Path for Biped Wall-Climbing Robots; *TMECH Oct. 2021 2712-2723*
- Zhu, H., Nesler, C., Divekar, N., Peddinti, V., and Gregg, R.D., Design Principles for Compact, Backdrivable Actuation in Partial-Assist Powered Knee Orthoses; *TMECH Dec.* 2021 3104-3115
- Zhu, J., see Wu, J., TMECH Oct. 2021 2782-2790
- Zhu, J., see Gao, S., TMECH Oct. 2021 2429-2439
- Zhu, J., see Chen, J., TMECH Oct. 2021 2770-2781
- Zhu, L., see Li, L., TMECH Feb. 2021 24-32
- Zhu, L., see Li, L., TMECH June 2021 1700
- Zhu, L., see Tao, Y., TMECH Aug. 2021 2186-2194
- Zhu, L., see Wang, Z., TMECH Oct. 2021 2274-2284
- Zhu, L., see Pal, A., TMECH Dec. 2021 3116-3127
- Zhu, R., see Xia, J., TMECH Oct. 2021 2803-2813
- Zhu, S., see Liu, G., TMECH June 2021 1602-1612
- Zhu, W., see Li, G., TMECH Aug. 2021 1960-1967
- Zhu, X., see Chen, G., TMECH April 2021 668-678
- Zhu, X., see Chen, S., TMECH Aug. 2021 1745-1753
- Zhu, X., see Chen, F., TMECH Oct. 2021 2629-2640
- Zhu, Y., Yang, Y., Wang, Y., Peng, T., Zhang, L., and Yang, H., Localized Property Design and Gradient Processing of a Hydraulic Valve Body Using Selective Laser Melting; *TMECH April 2021 1151-1160*
- Zhu, Y., see Wu, J., TMECH June 2021 1369-1379
- Zhu, Y., see Chen, L., TMECH Aug. 2021 1951-1959
- Zhu, Y., see Wang, Z., TMECH Oct. 2021 2274-2284
- Zhu, Y., see Liu, S., TMECH Oct. 2021 2747-2757
- Zhu, Z., see Tang, H., TMECH Feb. 2021 323-334
- Zou, J., see Huang, X., TMECH Dec. 2021 3175-3185
- Zou, S., see Zhao, W., TMECH June 2021 1558-1569
- Zou, Y., see Wang, Z., TMECH April 2021 1095-1105
- Zou, Y., see Kuruppu, S.S., TMECH April 2021 888-896
- Zou, Z., see Wu, J., TMECH June 2021 1369-1379
- **Zuo, Z.,** see Wu, Y., TMECH Feb. 2021 563-573
- Zuo, Z., see Guo, Q., TMECH Aug. 2021 2048-2058

Subject Index

Numeric

II-VI semiconductors

Robotic Prototyping of Paper-Based Field-Effect Transistors With Rolled-Up Semiconductor Microtubes. *Dong, X.*, +, *TMECH Feb. 2021 427-436*

Development of a Resonant Scanner to Improve the Imaging Rate of Astigmatic Optical Profilometers. *Liao, H.*, +, *TMECH April 2021 1172-1177* Acceleration

A

Sensorless Unbalance Diagnosis of Affiliated Rotating Chamber Based on Driving Current of Permanent Magnet Synchronous Motor. *Huo, X.*, +, *TMECH Dec. 2021 2899-2909*

Acceleration control

Proportional-Integral Approximation-Free Control of Robotic Systems With Unknown Dynamics. Zhang, C., +, TMECH Aug. 2021 2226-2236

Accelerometers

Aberrations

MEMS-Enabled Retrofitting of Automobile Wheel Balancer for Automatic Unbalance Detection. *Pozzato, G., +, TMECH April 2021 830-840*

Acoustic devices

A Mechanism-Image Fusion Approach to Calibration of an Ultrasound-Guided Dual-Arm Robotic Brachytherapy System. *Xiong, J.*, +, *TMECH Dec. 2021 3211-3220*

Acoustics

Weakly Supervised Acoustic Defect Detection in Concrete Structures Using Clustering-Based Augmentation. *Kasahara, J.Y.L.*, +, *TMECH Dec. 2021* 2826-2834

Active disturbance rejection control

Dynamic Path Correction of an Industrial Robot Using a Distance Sensor and an ADRC Controller. *Khaled, T.A.*, +, *TMECH June 2021 1646-1656*

Actuators

- A New Ankle Robotic System Enabling Whole-Stage Compliance Rehabilitation Training. Dong, M., +, TMECH June 2021 1490-1500
- A Novel Rotational Actuator With Variable Stiffness Using S-Shaped Springs. Xu, Y., +, TMECH Aug. 2021 2249-2260
- A Novel Wolfrom-Based Gearbox for Robotic Actuators. Crispel, S., +, TMECH Aug. 2021 1980-1988
- A Tilting-Rotor Unmanned Aerial Vehicle for Enhanced Aerial Locomotion and Manipulation Capabilities: Design, Control, and Applications. *Ding, C.*, +, *TMECH Aug. 2021 2237-2248*
- A Visual Servo-Based Predictive Control With Echo State Gaussian Process for Soft Bending Actuator. *Cao, Y., +, TMECH Feb. 2021 574-585*
- Accurate Motion Control of a Direct-Drive Hydraulic System With an Adaptive Nonlinear Pump Flow Compensation. *Helian, B.*, +, *TMECH Oct.* 2021 2593-2603
- Active Disturbance Rejection Control for a Fluid-Driven Hand Rehabilitation Device. Li, H., +, TMECH April 2021 841-853
- Actuation Frequency Modeling and Prediction for Shape Memory Alloy Actuators. Liu, X., +, TMECH June 2021 1536-1546
- An Output Feedback Based Robust Saturated Controller Design for Pavement Sweeping Self-Reconfigurable Robot. Rayguru, M.M., +, TMECH June 2021 1236-1247
- Analytical Design and Experimental Verification of Geofencing Control for Aerial Applications. *Ghaffari, A., TMECH April 2021 1106-1117*
- Biomimetic Realization of a Robotic Penguin Wing: Design and Thrust Characteristics. Shen, Y., +, TMECH Oct. 2021 2350-2361
- Coordinated Dynamic Control in the Task Space for Redundantly Actuated Cable-Driven Parallel Robots. Zhang, B., +, TMECH Oct. 2021 2396-2407
- Design and Experimental Validation of Robust Self-Scheduled Fault-Tolerant Control Laws for a Multicopter UAV. Nguyen, D., +, TMECH Oct. 2021 2548-2557
- Design and Real-Time Optimization for a Magnetic Actuation System With Enhanced Flexibility. *Du*, *X*., +, *TMECH June 2021 1524-1535*
- Design Principles for Compact, Backdrivable Actuation in Partial-Assist Powered Knee Orthoses. Zhu, H., +, TMECH Dec. 2021 3104-3115
- Development and Performance Enhancement of an Overactuated Autonomous Ground Vehicle. *Huang, Y.*, +, *TMECH Feb. 2021 33-44*
- Development of a Nanopositioning Platform With Large Travel Range Based on Bionic Quadruped Piezoelectric Actuator. *Deng, J.*, +, *TMECH Aug.* 2021 2059-2070
- Development of Embedded Sensor System for 5-DOF Finger-Wearable Tactile Interface. *Lim, B., +, TMECH Aug. 2021 1728-1736*

- Diversified and Untethered Motion Generation Via Crease Patterning from Magnetically Actuated Caterpillar-Inspired Origami Robot. *Cai, C.J.*, +, *TMECH June 2021 1678-1688*
- Dynamic Modeling and State Estimation of Cable-Conduit Actuation During Interaction With Nonpassive Environments. *Buchanan, S.*, +, *TMECH Oct.* 2021 2462-2471
- Energy-Based Modeling of Ionic Polymer–Metal Composite Actuators Dedicated to the Control of Flexible Structures. *Liu*, *N*., +, *TMECH Dec. 2021* 3139-3150
- Fractional-Order Control for Uncertain Teleoperated Cyber-Physical System With Actuator Fault. *Ma*, *Z*., +, *TMECH Oct.* 2021 2472-2482
- Geometrical-Based Displacement Measurement With Pseudostereo Monocular Camera on Bidirectional Cascaded Linear Actuator. *Lee, D.*, +, *TMECH Aug. 2021 1923-1931*
- Guest Editorial: Focused Section on Mechatronics in Road Mobility Systems. *Ivanov, V.*, +, *TMECH June 2021 1195-1200*
- Haptic Display Responsive to Touch Driven by Soft Actuator and Soft Sensor. *Phung, H., +, TMECH Oct. 2021 2495-2505*
- Human-in-the-Loop Control of a Wearable Lower Limb Exoskeleton for Stable Dynamic Walking. *Li*, *Z*., +, *TMECH Oct. 2021 2700-2711*
- Hybrid Control Strategy for Force and Precise End Effector Positioning of a Twisted String Actuator. Rodriguez, A.S., +, TMECH Oct. 2021 2791-2802
- Individual Auxiliary and Fault-Tolerant Control of Steer-by-Wire System Considering Different Drivers Steering Characteristics. *Zhao, W.*, +, *TMECH June 2021 1558-1569*
- Kinematic Modeling and Control of Variable Curvature Soft Continuum Robots. *Huang, X.*, +, *TMECH Dec. 2021 3175-3185*
- Low Impedance-Guaranteed Gain-Scheduled GESO for Torque-Controlled VSA With Application of Exoskeleton-Assisted Sit-to-Stand. *Liu, L.*, +, *TMECH Aug. 2021 2080-2091*
- Magnetically Levitated Linear Drive Using an Active Gravity Compensation Based on Hybrid Shape Memory Actuators. *Raab, M.*, +, *TMECH June* 2021 1380-1391
- Mech-Walker: A Novel Single-DOF Linkage Device With Movable Frame for Gait Rehabilitation. *Haghjoo*, M.R., +, TMECH Feb. 2021 13-23
- Modeling and Adaptive Fault Compensation for Two Physically Linked 2WD Mobile Robots. *Ma*, *Y*, +, *TMECH April 2021 1161-1171*
- Modeling and Analysis of Soft Pneumatic Network Bending Actuators. *Liu*, Z., +, *TMECH Aug. 2021 2195-2203*
- Modified Stiffness-Based Soft Optical Waveguide Integrated Pneumatic Artificial Muscle (PAM) Actuators for Contraction and Force Sensing. *Jamil, B.*, +, *TMECH Dec. 2021 3243-3253*
- Nonlinear Model Predictive Control for Integrated Energy-Efficient Torque-Vectoring and Anti-Roll Moment Distribution. *Dalboni, M.*, +, *TMECH June 2021 1212-1224*
- On Perpendicular Curve-Based Model-Less Control Considering Incomplete Orientation Constraint. Li, G., +, TMECH June 2021 1479-1489
- On the Mechanical Power Output Comparisons of Cone Dielectric Elastomer Actuators. Cao, C., +, TMECH Dec. 2021 3151-3162

Otariidae-Inspired Soft-Robotic Supernumerary Flippers by Fabric Kirigami and Origami. *Liu, S.*, +, *TMECH Oct. 2021 2747-2757*

- Overcoming the Torque/Stiffness Range Tradeoff in Antagonistic Variable Stiffness Actuators. *Mengacci, R., +, TMECH Dec. 2021 3186-3197*
- Phase-Relaxed-Passive Full State Feedback Gain Limits for Series Elastic Actuators. *Thomas, G.C.,* +, *TMECH Feb. 2021 586-591*
- Plate-Springed Parallel Elastic Actuator for Efficient Snake Robot Movement. Kakogawa, A., +, TMECH Dec. 2021 3051-3063
- Self-Sensing and Control of Soft Electrothermal Actuator. Cao, Y., +, TMECH April 2021 854-863
- Slider-Tendon Linear Actuator With Under-Actuation and Fast-Connection for Soft Wearable Robots. *Kim, B., +, TMECH Dec. 2021 2932-2943*
- Takagi–Sugeno Fuzzy-Based Robust H∞ Integrated Lane-Keeping and Direct Yaw Moment Controller of Unmanned Electric Vehicles. Guo, J., +, TMECH Aug. 2021 2151-2162
- Thermal Modeling and Characterization of Twisted Coiled Actuators for Upper Limb Wearable Devices. *Edmonds, B.P.R.*, +, *TMECH April 2021* 966-977

Whole-Body Control of an Autonomous Mobile Manipulator Using Series Elastic Actuators. *Liu*, *Y*, +, *TMECH April 2021 657-667*

Adaptation models

- Accurate Motion Control of a Direct-Drive Hydraulic System With an Adaptive Nonlinear Pump Flow Compensation. *Helian, B.*, +, *TMECH Oct.* 2021 2593-2603
- An Adaptive Fuzzy Trajectory Tracking Control via Improved Cerebellar Model Articulation Controller for Electro-Hydraulic Shovel. Fan, R., +, TMECH Dec. 2021 2870-2880

Adaptive control

- A Tilting-Rotor Unmanned Aerial Vehicle for Enhanced Aerial Locomotion and Manipulation Capabilities: Design, Control, and Applications. *Ding, C.*, +, *TMECH Aug. 2021 2237-2248*
- Adaptive Finite-Time Control for Half-Vehicle Active Suspension Systems With Uncertain Dynamics. *Liu*, Y, +, *TMECH Feb. 2021 168-178*
- Adaptive Output Feedback Control of Steer-by-Wire Systems With Event-Triggered Communication. *Ma*, *B*., +, *TMECH Aug. 2021 1968-1979*
- Adaptive Robust Finite-Time Nonlinear Control of a Typical Autonomous Underwater Vehicle With Saturated Inputs and Uncertainties. *Sedghi, F*, +, *TMECH Oct. 2021 2517-2527*
- An Observer-Based Neural Adaptive\$PID^2\$ Controller for Robot Manipulators Including Motor Dynamics With a Prescribed Performance. *Shojaei*, *K.*, +, *TMECH June 2021 1689-1699*
- Asymptotic Tracking Control of Mechanical Servosystems With Mismatched Uncertainties. *Deng, W.*, +, *TMECH Aug. 2021 2204-2214*
- Coordinated Dynamic Control in the Task Space for Redundantly Actuated Cable-Driven Parallel Robots. Zhang, B., +, TMECH Oct. 2021 2396-2407
- Design and Experimental Validation of Robust Self-Scheduled Fault-Tolerant Control Laws for a Multicopter UAV. Nguyen, D., +, TMECH Oct. 2021 2548-2557
- Distributed Formation Control Using Fuzzy Self-Tuning of Strictly Negative Imaginary Consensus Controllers in Aerial Robotics. *Tran, V.P.*, +, *TMECH Oct. 2021 2306-2315*
- Event-Triggered-Based Discrete-Time Neural Control for a Quadrotor UAV Using Disturbance Observer. Shao, S., +, TMECH April 2021 689-699
- Finite-Time Synchronization Control for Bilateral Teleoperation Systems With Asymmetric Time-Varying Delay and Input Dead Zone. *Bao, J.*, +, *TMECH June 2021 1570-1580*
- Fractional-Order Control for Uncertain Teleoperated Cyber-Physical System With Actuator Fault. *Ma*, *Z*., +, *TMECH Oct. 2021 2472-2482*
- Human-in-the-Loop Control of a Wearable Lower Limb Exoskeleton for Stable Dynamic Walking. *Li*, *Z*., +, *TMECH Oct. 2021 2700-2711*
- Modeling and Adaptive Fault Compensation for Two Physically Linked 2WD Mobile Robots. *Ma*, *Y*, +, *TMECH April 2021 1161-1171*
- Modeling and Motion Control of Industrial Tractor–Trailers Vehicles Using Force Compensation. Zhao, H., +, TMECH April 2021 645-656
- Path Following of Wheeled Mobile Robots Using Online-Optimization-Based Guidance Vector Field. *Chen, J.*, +, *TMECH Aug. 2021 1737-1744*
- Practical Fixed-Time Position Tracking Control of Permanent Magnet DC Torque Motor Systems. *Wu, Y., +, TMECH Feb. 2021 563-573*
- Practical Terminal Sliding Mode Control of Nonlinear Uncertain Active Suspension Systems With Adaptive Disturbance Observer. *Wang, G.*, +, *TMECH April 2021* 789-797
- Proportional-Integral Approximation-Free Control of Robotic Systems With Unknown Dynamics. *Zhang, C.,* +, *TMECH Aug. 2021 2226-2236*
- Quasi-Synchronization Control of Multiple Electrohydraulic Actuators With Load Disturbance and Uncertain Parameters. *Guo, Q.*, +, *TMECH Aug.* 2021 2048-2058
- Robust Adaptive Tracking Control of Underwater Vehicles: Design, Stability Analysis, and Experiments. *Tijjani, A.S.*, +, *TMECH April 2021 897-907*
- Sliding-Mode-Disturbance-Observer-Based Robust Tracking Control for Omnidirectional Mobile Robots With Kinematic and Dynamic Uncertainties. Jeong, S., +, TMECH April 2021 741-752
- Tracking Accuracy Improvement Based on Adaptive Nonlinear Sliding Mode Control. Tsai, W., +, TMECH Feb. 2021 179-190

- Unified Motion/Force/Impedance Control for Manipulators in Unknown Contact Environments Based on Robust Model-Reaching Approach. *Lin, Y.*, +, *TMECH Aug. 2021 1905-1913*
- Whole-Body Control of an Autonomous Mobile Manipulator Using Series Elastic Actuators. *Liu*, *Y*., +, *TMECH April 2021 657-667*

Aerodynamics

- Compliant Bistable Grippers Enable Passive Perching for Micro Aerial Vehicles. Zhang, H., +, TMECH Oct. 2021 2316-2326
- Curvature-Induced Buckling for Flapping-Wing Vehicles. Sharifzadeh, M., +, TMECH Feb. 2021 503-514
- Modeling Quadrotor Dynamics in a Wind Field. Jeon, H., +, TMECH June 2021 1401-1411
- Swing-Reducing Flight Control System for an Underactuated Indoor Miniature Autonomous Blimp. *Tao*, Q., +, *TMECH Aug. 2021 1895-1904*

Aerospace components

- Biomimetic Realization of a Robotic Penguin Wing: Design and Thrust Characteristics. Shen, Y., +, TMECH Oct. 2021 2350-2361
- Compliant Bistable Grippers Enable Passive Perching for Micro Aerial Vehicles. Zhang, H., +, TMECH Oct. 2021 2316-2326
- Curvature-Induced Buckling for Flapping-Wing Vehicles. Sharifzadeh, M., +, TMECH Feb. 2021 503-514
- Multimodal Dynamics Analysis and Control for Amphibious Fly-Drive Vehicle. *Tan, Q.*, +, *TMECH April 2021 621-632*

Aerospace computing

An Efficient Design Solution for a Low-Cost High-G Centrifuge System. Mohajer, N., +, TMECH Feb. 2021 134-145

Aerospace control

- Compliant Bistable Grippers Enable Passive Perching for Micro Aerial Vehicles. Zhang, H., +, TMECH Oct. 2021 2316-2326
- Distributed Control Algorithm for Leader–Follower Formation Tracking of Multiple Quadrotors: Theory and Experiment. *Wang, Z.*, +, *TMECH April* 2021 1095-1105
- Distributed Formation Control Using Fuzzy Self-Tuning of Strictly Negative Imaginary Consensus Controllers in Aerial Robotics. Tran, V.P., +, TMECH Oct. 2021 2306-2315

Swing-Reducing Flight Control System for an Underactuated Indoor Miniature Autonomous Blimp. Tao, Q., +, TMECH Aug. 2021 1895-1904

Aerospace engineering

Curvature-Induced Buckling for Flapping-Wing Vehicles. Sharifzadeh, M., +, TMECH Feb. 2021 503-514

Aerospace engines

Analytical Harmonic Method for Modeling High-Frequency Oscillation With Applications to Aircraft Piston Pump Vibration Analysis. *Li*, *L.*, +, *TMECH April 2021 918-929*

Aerospace propulsion

A Computational-Effective Field-Oriented Control Strategy for Accurate and Efficient Electric Propulsion of Unmanned Aerial Vehicles. *Bosso, A.*, +, *TMECH June 2021 1501-1511*

Aerospace robotics

- An Active Sense and Avoid System for Flying Robots in Dynamic Environments. Chen, G., +, TMECH April 2021 668-678
- Coordinated Dynamic Control in the Task Space for Redundantly Actuated Cable-Driven Parallel Robots. *Zhang, B., +, TMECH Oct. 2021 2396-2407* Swing-Reducing Flight Control System for an Underactuated Indoor Minia-

ture Autonomous Blimp. Tao, Q., +, TMECH Aug. 2021 1895-1904

Aerospace safety

An Efficient Design Solution for a Low-Cost High-G Centrifuge System. Mohajer, N., +, TMECH Feb. 2021 134-145

Aging

Global Parameter Sensitivity Analysis of Electrochemical Model for Lithium-Ion Batteries Considering Aging. *Gao, Y.*, +, *TMECH June 2021 1283-1294*

Agricultural machinery

Dynamic State Estimation and Control of a Heavy Tractor–Trailers Vehicle. Zhou, S., +, TMECH June 2021 1467-1478

Modeling and Motion Control of Industrial Tractor–Trailers Vehicles Using Force Compensation. Zhao, H., +, TMECH April 2021 645-656

Air gaps

Analysis of Quasi-Zero Power Characteristic for a Permanent Magnetic Levitation System With a Variable Flux Path Control Mechanism. *Zhao, C.*, +, *TMECH Feb. 2021 437-447*

Aircraft

Analytical Harmonic Method for Modeling High-Frequency Oscillation With Applications to Aircraft Piston Pump Vibration Analysis. *Li*, *L.*, +, *TMECH April 2021 918-929*

Aircraft control

- Analytical Design and Experimental Verification of Geofencing Control for Aerial Applications. *Ghaffari, A., TMECH April 2021 1106-1117*
- Compliant Bistable Grippers Enable Passive Perching for Micro Aerial Vehicles. Zhang, H., +, TMECH Oct. 2021 2316-2326
- Design and Experimental Validation of Robust Self-Scheduled Fault-Tolerant Control Laws for a Multicopter UAV. Nguyen, D., +, TMECH Oct. 2021 2548-2557
- Distributed Formation Control Using Fuzzy Self-Tuning of Strictly Negative Imaginary Consensus Controllers in Aerial Robotics. *Tran, V.P.*, +, *TMECH Oct. 2021 2306-2315*
- Event-Triggered-Based Discrete-Time Neural Control for a Quadrotor UAV Using Disturbance Observer. Shao, S., +, TMECH April 2021 689-699
- Modeling Quadrotor Dynamics in a Wind Field. Jeon, H., +, TMECH June 2021 1401-1411
- Swing-Reducing Flight Control System for an Underactuated Indoor Miniature Autonomous Blimp. Tao, Q., +, TMECH Aug. 2021 1895-1904

Amplitude modulation

Development of a Resonant Scanner to Improve the Imaging Rate of Astigmatic Optical Profilometers. *Liao, H., +, TMECH April 2021 1172-1177*

Analytical models

- Automatic Construction of Three-Dimensional Ground Model by Data Processing. *Takeyama*, *T.*, +, *TMECH Dec.* 2021 2881-2887
- Feature Analyses and Modeling of Lithium-Ion Battery Manufacturing Based on Random Forest Classification. *Liu, K.*, +, *TMECH Dec. 2021* 2944-2955

Similitude Analysis Method of the Dynamics of a Hybrid Spray-Painting Robot Considering Electromechanical Coupling Effect. *Song, Y*, +, *TMECH Dec. 2021 2986-2997*

Anchors

A Piezoelectric Microultrasonic Motor With High Q and Good Mode Match. Zhou, W., +, TMECH Aug. 2021 1773-1781

Angular velocity control

- Experimental Investigation on Control of an Infinitely Variable Transmission System for Tidal Current Energy Converters. *Li*, *G.*, +, *TMECH Aug.* 2021 1960-1967
- Fully Distributed Cooperative Circumnavigation of Networked Unmanned Aerial Vehicles. *Li*, *D.*, +, *TMECH April 2021 709-718*

Online Compensation of Mechanical Load Defects With Composite Control in PMSM Drives. *Kommuri, S.K.*, +, *TMECH June 2021 1392-1400*

Antireflection coatings

Ultraviolet Beam Lithography System for Digital Fabrication of Roller Molds. Yang, S., +, TMECH Feb. 2021 226-234

Approximation theory

Analytical Harmonic Method for Modeling High-Frequency Oscillation With Applications to Aircraft Piston Pump Vibration Analysis. *Li*, *L.*, +, *TMECH April 2021 918-929* Arithmetic

Toolpath Regeneration in Subregional Contour-Parallel Processing Based on

Isoscallop Method. Ma, J., +, TMECH April 2021 730-740

Artificial limbs

- Human-in-the-Loop Control of a Wearable Lower Limb Exoskeleton for Stable Dynamic Walking. Li, Z., +, TMECH Oct. 2021 2700-2711
- Mechanism and Controller Design of a Transfemoral Prosthesis With Electrohydraulic Knee and Motor-Driven Ankle. *Gao, S.*, +, *TMECH Oct. 2021* 2429-2439

Artificial neural networks

An Adaptive Fuzzy Trajectory Tracking Control via Improved Cerebellar Model Articulation Controller for Electro-Hydraulic Shovel. *Fan, R.*, +, *TMECH Dec. 2021 2870-2880*

Assembling

Analytical Harmonic Method for Modeling High-Frequency Oscillation With Applications to Aircraft Piston Pump Vibration Analysis. *Li*, *L.*, +, *TMECH April 2021 918-929*

Assisted living

Low Impedance-Guaranteed Gain-Scheduled GESO for Torque-Controlled VSA With Application of Exoskeleton-Assisted Sit-to-Stand. *Liu, L.*, +, *TMECH Aug. 2021 2080-2091*

Asymptotic stability

- Analytical Design and Experimental Verification of Geofencing Control for Aerial Applications. *Ghaffari, A., TMECH April 2021 1106-1117*
- Distributed Control Algorithm for Leader–Follower Formation Tracking of Multiple Quadrotors: Theory and Experiment. *Wang, Z.*, +, *TMECH April* 2021 1095-1105
- Robust Adaptive Tracking Control of Underwater Vehicles: Design, Stability Analysis, and Experiments. *Tijjani, A.S.*, +, *TMECH April 2021 897-907*
- Robust Tracking Control of a Quadrotor Unmanned Aerial Vehicle-Suspended Payload System. *Xian, B., +, TMECH Oct. 2021 2653-2663*
- Vision-Based Cutting Control of Deformable Objects With Surface Tracking. Han, L., +, TMECH Aug. 2021 2016-2026

Atomic force microscopy

- A Smoothed Raster Scanning Trajectory Based on Acceleration-Continuous B-Spline Transition for High-Speed Atomic Force Microscopy. *Li*, *L.*, +, *TMECH Feb. 2021 24-32*
- An Automated AFM Tip-Replacement System for *In Situ* Tip-Replacement. *Vikrant, K.S.*, +, *TMECH April 2021 798-806*
- Closed-Loop Range-Based Control of Dual-Stage Nanopositioning Systems. *Mitrovic, A., +, TMECH June 2021 1412-1421*
- Erratum to "A Smoothed Raster Scanning Trajectory Based on Acceleration-Continuous B-Spline Transition for High-Speed Atomic Force Microscopy" [Feb 21 24-32]. *Li*, *L.*, +, *TMECH June 2021 1700*
- Iterative Learning Control for Video-Rate Atomic Force Microscopy. Nikooienejad, N., +, TMECH Aug. 2021 2127-2138

Attitude control

- A Tilting-Rotor Unmanned Aerial Vehicle for Enhanced Aerial Locomotion and Manipulation Capabilities: Design, Control, and Applications. *Ding*, *C.*, +, *TMECH Aug. 2021 2237-2248*
- Analytical Design and Experimental Verification of Geofencing Control for Aerial Applications. *Ghaffari, A., TMECH April 2021 1106-1117*
- Fully Actuated Autonomous Flight of Thruster-Tilting Multirotor. Lee, S.J., +, TMECH April 2021 765-776
- Passivity-Based Nonlinear Control Approach for Tracking Task of an Underactuated CMG. Toriumi, F.Y., +, TMECH Oct. 2021 2285-2293

Automatic guided vehicles

Development and Performance Enhancement of an Overactuated Autonomous Ground Vehicle. *Huang, Y.*, +, *TMECH Feb. 2021 33-44*

Automation

- Autonomous Navigation of Magnetic Microrobots in a Large Workspace Using Mobile-Coil System. Yang, Z., +, TMECH Dec. 2021 3163-3174
- Guest Editorial Focused Section on Mechatronics in Unmanned Systems. *He, W.*, +, *TMECH April 2021 595-599*
- Guest Editorial Introduction to the Focused Section on Mechatronics and Automation for Constructions. *Cheah, C.C.*, +, *TMECH Dec. 2021 2819-*2825
- Weakly Supervised Acoustic Defect Detection in Concrete Structures Using Clustering-Based Augmentation. Kasahara, J.Y.L., +, TMECH Dec. 2021 2826-2834

Automobiles

- A Phase-Shaping Approach to the Control of Parametric Systems and Its Application. *Shimonomura, S.,* +, *TMECH Aug. 2021 2163-2173*
- MEMS-Enabled Retrofitting of Automobile Wheel Balancer for Automatic Unbalance Detection. *Pozzato, G., +, TMECH April 2021 830-840*
- Quasi-LPV Interconnected Observer Design for Full Vehicle Dynamics Estimation With Hardware Experiments. *Fouka*, *M.*, +, *TMECH Aug. 2021* 1763-1772

Automotive components

MEMS-Enabled Retrofitting of Automobile Wheel Balancer for Automatic Unbalance Detection. *Pozzato, G., +, TMECH April 2021 830-840*

Automotive engineering

- Covert Attacks Through Adversarial Learning: Study of Lane Keeping Attacks on the Safety of Autonomous Vehicles. *Farivar, F., +, TMECH June 2021 1350-1357*
- Individual Auxiliary and Fault-Tolerant Control of Steer-by-Wire System Considering Different Drivers Steering Characteristics. *Zhao, W.*, +, *TMECH June 2021 1558-1569*

Autonomous aerial vehicles

- A Binary Tree Based Coordination Scheme for Target Enclosing With Micro Aerial Vehicles. *Duan, H., +, TMECH Feb. 2021 458-468*
- A Computational-Effective Field-Oriented Control Strategy for Accurate and Efficient Electric Propulsion of Unmanned Aerial Vehicles. *Bosso, A.*, +, *TMECH June 2021 1501-1511*
- A Tilting-Rotor Unmanned Aerial Vehicle for Enhanced Aerial Locomotion and Manipulation Capabilities: Design, Control, and Applications. *Ding, C.*, +, *TMECH Aug. 2021 2237-2248*
- Analytical Design and Experimental Verification of Geofencing Control for Aerial Applications. *Ghaffari, A., TMECH April 2021 1106-1117*
- Compliant Bistable Grippers Enable Passive Perching for Micro Aerial Vehicles. Zhang, H., +, TMECH Oct. 2021 2316-2326
- Design and Control of Soft Unmanned Aerial Vehicle "S-CLOUD". Song, S.H., +, TMECH Feb. 2021 267-275
- Design and Experimental Validation of Robust Self-Scheduled Fault-Tolerant Control Laws for a Multicopter UAV. Nguyen, D., +, TMECH Oct. 2021 2548-2557
- Distributed Formation Control Using Fuzzy Self-Tuning of Strictly Negative Imaginary Consensus Controllers in Aerial Robotics. *Tran, V.P.*, +, *TMECH Oct. 2021 2306-2315*
- Event-Triggered-Based Discrete-Time Neural Control for a Quadrotor UAV Using Disturbance Observer. Shao, S., +, TMECH April 2021 689-699
- Formation Reconstruction and Trajectory Replanning for Multi-UAV Patrol. *Wang, Y.*, +, *TMECH April 2021 719-729*
- Fully Actuated Autonomous Flight of Thruster-Tilting Multirotor. Lee, S.J., +, TMECH April 2021 765-776
- Fully Distributed Cooperative Circumnavigation of Networked Unmanned Aerial Vehicles. *Li*, *D.*, +, *TMECH April 2021 709-718*
- Geometrical-Based Displacement Measurement With Pseudostereo Monocular Camera on Bidirectional Cascaded Linear Actuator. *Lee, D.*, +, *TMECH Aug. 2021 1923-1931*
- Modeling Quadrotor Dynamics in a Wind Field. Jeon, H., +, TMECH June 2021 1401-1411
- Robust Nonlinear Model Predictive Control Based Visual Servoing of Quadrotor UAVs. *Zhang, K.,* +, *TMECH April 2021 700-708*
- Robust Tracking Control of a Quadrotor Unmanned Aerial Vehicle-Suspended Payload System. Xian, B., +, TMECH Oct. 2021 2653-2663

Autonomous underwater vehicles

- Design and Experimental Validation of a Novel High-Speed Omnidirectional Underwater Propulsion Mechanism. *Njaka, T., +, TMECH Oct. 2021* 2339-2349
- Efficient Bathymetric SLAM With Invalid Loop Closure Identification. Teng, M., +, TMECH Oct. 2021 2570-2580
- Robust Adaptive Tracking Control of Underwater Vehicles: Design, Stability Analysis, and Experiments. *Tijjani, A.S.*, +, *TMECH April 2021 897-907*
- Sea Mining Exploration With an UVMS: Experimental Validation of the Control and Perception Framework. *Simetti, E., +, TMECH June 2021* 1635-1645

Autonomous vehicles

- Coordinated Trajectory-Tracking Control of a Marine Aerial-Surface Heterogeneous System. Wang, N., +, TMECH Dec. 2021 3198-3210
- Simultaneous State Estimation and Tire Model Learning for Autonomous Vehicle Applications. *Jeon, W.*, +, *TMECH Aug. 2021 1941-1950*

Autoregressive processes

A Visual Servo-Based Predictive Control With Echo State Gaussian Process for Soft Bending Actuator. *Cao*, Y, +, *TMECH Feb. 2021 574-585*

Avatars

Tendon-Inspired Piezoelectric Sensor for Biometric Application. *Kim, H.*, +, *TMECH Oct. 2021 2538-2547* В

Bandwidth

Data-Driven Iterative Trajectory Shaping for Precision Control of Flexible Feed Drives. *Dumanli, A.*, +, *TMECH Oct. 2021 2735-2746*

Bathymetry

Efficient Bathymetric SLAM With Invalid Loop Closure Identification. Teng, M., +, TMECH Oct. 2021 2570-2580

Batteries

- Feature Analyses and Modeling of Lithium-Ion Battery Manufacturing Based on Random Forest Classification. *Liu, K.*, +, *TMECH Dec. 2021* 2944-2955
- Integrated Predictive Powertrain Control for a Multimode Plug-in Hybrid Electric Vehicle. Oncken, J., +, TMECH June 2021 1248-1259

Battery management systems

- General Discharge Voltage Information Enabled Health Evaluation for Lithium-Ion Batteries. Deng, Z., +, TMECH June 2021 1295-1306
- Global Parameter Sensitivity Analysis of Electrochemical Model for Lithium-Ion Batteries Considering Aging. *Gao, Y.*, +, *TMECH June 2021 1283-1294*

Battery powered vehicles

General Discharge Voltage Information Enabled Health Evaluation for Lithium-Ion Batteries. Deng, Z., +, TMECH June 2021 1295-1306

Bayes methods

Collaborative Semantic Understanding and Mapping Framework for Autonomous Systems. Yue, Y., +, TMECH April 2021 978-989

Beams (structures)

A Piezoelectric Microultrasonic Motor With High Q and Good Mode Match. Zhou, W., +, TMECH Aug. 2021 1773-1781

Belief networks

Intelligent Fault Diagnosis of a Reciprocating Compressor Using Mode Isolation Convolutional Deep Belief Networks. *Zhang, Y.*, +, *TMECH June* 2021 1668-1677

Bellows

Design and Characterization of a Bellows-Driven Soft Pneumatic Actuator. Hashem, R., +, TMECH Oct. 2021 2327-2338

Belts

Pose Error Estimation Using a Cylinder in Scanner-Based Robotic Belt Grinding. Xie, H., +, TMECH Feb. 2021 515-526

Bending

- A Tubular Dual-Roller Bending Mechanism Toward Robotic Transurethral Prostate Biopsy. Xiao, X., +, TMECH Oct. 2021 2483-2494
- A Two-Finger Soft-Robotic Gripper With Enveloping and Pinching Grasping Modes. *Liu*, *S.*, +, *TMECH Feb. 2021 146-155*
- Design, Modeling, and Control of a 3D Printed Monolithic Soft Robotic Finger With Embedded Pneumatic Sensing Chambers. Tawk, C., +, TMECH April 2021 876-887
- Investigation on a New Approach for Designing Articulated Soft Robots With Discrete Variable Stiffness. *Zhong, Y.*, +, *TMECH Dec. 2021 2998-3009*
- Modeling and Analysis of Soft Pneumatic Network Bending Actuators. *Liu*, *Z.*, +, *TMECH Aug. 2021 2195-2203*
- Self-Sensing and Control of Soft Electrothermal Actuator. Cao, Y, +, TMECH April 2021 854-863

Topology Optimization of Skeleton-Reinforced Soft Pneumatic Actuators for Desired Motions. Chen, S., +, TMECH Aug. 2021 1745-1753

Bicycles

Kinematic Modeling, Analysis, and Verification of an Essboard-Like Robot. *Guan, Y.*, +, *TMECH April 2021 864-875*

Biocontrol

Mechanism and Controller Design of a Transfemoral Prosthesis With Electrohydraulic Knee and Motor-Driven Ankle. *Gao, S.*, +, *TMECH Oct. 2021* 2429-2439

Biological organs

A Tubular Dual-Roller Bending Mechanism Toward Robotic Transurethral Prostate Biopsy. Xiao, X., +, TMECH Oct. 2021 2483-2494

Design and Characterization of a Bellows-Driven Soft Pneumatic Actuator. Hashem, R., +, TMECH Oct. 2021 2327-2338

Biological techniques

Design and Testing of a New Force-Sensing Cell Microinjector Based on Small-Stiffness Compliant Mechanism. *Wei*, *Y*, +, *TMECH April 2021* 818-829

Biological tissues

- Construction of Controller Model of Notch Continuum Manipulator for Laryngeal Surgery Based on Hybrid Method. *Wang, H.*, +, *TMECH April* 2021 1022-1032
- Image Processing Metrics for Phase Identification of a Multiaxis MEMS Scanner Used in Single Pixel Imaging. *Birla, M.*, +, *TMECH June 2021* 1445-1454
- Measurement of Peristaltic Forces Exerted by Living Intestine on Robotic Capsule. *Rehan, M.*, +, *TMECH Aug. 2021 1803-1811*
- Needle Deflection Modeling and Preoperative Trajectory Planning During Insertion Into Multilayered Tissues. *Zhao, B., +, TMECH April 2021 943-954*
- Robotized Catheter With Enhanced Distal Targeting for Peripheral Pulmonary Biopsy. *Kato, T., +, TMECH Oct. 2021 2451-2461*

Biology computing

Tendon-Inspired Piezoelectric Sensor for Biometric Application. *Kim, H.*, +, *TMECH Oct. 2021 2538-2547*

Biomagnetism

Optimal Design and Implementation of a Novel Two-Dimensional Electromagnetic Navigation System That Allows Focused Heating of Magnetic Nanoparticles. *Le, T.,* +, *TMECH Feb. 2021 551-562*

Biomechanics

- A New Ankle Robotic System Enabling Whole-Stage Compliance Rehabilitation Training. Dong, M., +, TMECH June 2021 1490-1500
- A Surgical Robotic System for Treatment of Pelvic Osteolysis Using an FBG-Equipped Continuum Manipulator and Flexible Instruments. *Sefati, S.*, +, *TMECH Feb.* 2021 369-380
- Biomimetic Realization of a Robotic Penguin Wing: Design and Thrust Characteristics. Shen, Y., +, TMECH Oct. 2021 2350-2361
- Brain–Machine Interface Using Functional Electrical Stimulation and Motion-Related Cortical Potentials Identified by a Support Vector Machine. *Miura*, S., +, *TMECH April 2021 1013-1021*
- Curvature-Induced Buckling for Flapping-Wing Vehicles. Sharifzadeh, M., +, TMECH Feb. 2021 503-514
- Design, Modeling, and Control of a 3D Printed Monolithic Soft Robotic Finger With Embedded Pneumatic Sensing Chambers. *Tawk, C.*, +, *TMECH April 2021 876-887*
- Dynamic Modeling and State Estimation of Cable-Conduit Actuation During Interaction With Nonpassive Environments. *Buchanan, S.*, +, *TMECH Oct.* 2021 2462-2471
- Haptic Display Responsive to Touch Driven by Soft Actuator and Soft Sensor. *Phung, H., +, TMECH Oct. 2021 2495-2505*
- Human-in-the-Loop Control of a Wearable Lower Limb Exoskeleton for Stable Dynamic Walking. *Li*, *Z*., +, *TMECH Oct. 2021 2700-2711*
- Mechanism and Controller Design of a Transfemoral Prosthesis With Electrohydraulic Knee and Motor-Driven Ankle. *Gao, S.*, +, *TMECH Oct. 2021* 2429-2439
- Needle Deflection Modeling and Preoperative Trajectory Planning During Insertion Into Multilayered Tissues. *Zhao, B., +, TMECH April 2021 943-954*
- On-Body RF Sensor Toward Tremor Detection in Parkinson's Disease. Abirami B, S., +, TMECH Oct. 2021 2814-2817
- Stochastic Force-Based Insertion Depth and Tip Position Estimations of Flexible FBG-Equipped Instruments in Robotic Retinal Surgery. *Ebrahimi, A.*, +, *TMECH June 2021 1512-1523*
- Tendon-Inspired Piezoelectric Sensor for Biometric Application. Kim, H., +, TMECH Oct. 2021 2538-2547
- The MUSHA Hand II:A Multifunctional Hand for Robot-Assisted Laparoscopic Surgery. Liu, H., +, TMECH Feb. 2021 393-404
- Topology Optimization of Skeleton-Reinforced Soft Pneumatic Actuators for Desired Motions. Chen, S., +, TMECH Aug. 2021 1745-1753
- Wearable Knee Assistive Devices for Kneeling Tasks in Construction. *Chen, S.*, +, *TMECH Aug. 2021 1989-1996*

Biomedical MRI

- A Fully Actuated Robotic Assistant for MRI-Guided Precision Conformal Ablation of Brain Tumors. *Li*, *G.*, +, *TMECH Feb. 2021 255-266*
- A Piezoelectric Robotic System for MRI Targeting Assessments of Therapeutics During Dipole Field Navigation. *Shi*, Y., +, *TMECH Feb. 2021* 214-225

Biomedical optical imaging

- A Tubular Dual-Roller Bending Mechanism Toward Robotic Transurethral Prostate Biopsy. *Xiao*, *X*., +, *TMECH Oct. 2021 2483-2494*
- Automated Retinal Vein Cannulation on Silicone Phantoms Using Optical-Coherence-Tomography-Guided Robotic Manipulations. Gerber, M.J., +, TMECH Oct. 2021 2758-2769
- Image Processing Metrics for Phase Identification of a Multiaxis MEMS Scanner Used in Single Pixel Imaging. *Birla, M.*, +, *TMECH June 2021* 1445-1454
- Investigation of Micromotion Kinematics of Continuum Robots for Volumetric OCT and OCT-Guided Visual Servoing. *Giudice, G.D.*, +, *TMECH Oct.* 2021 2604-2615
- Measurement of Peristaltic Forces Exerted by Living Intestine on Robotic Capsule. Rehan, M., +, TMECH Aug. 2021 1803-1811

Biomedical ultrasonics

- A Fully Actuated Robotic Assistant for MRI-Guided Precision Conformal Ablation of Brain Tumors. *Li*, *G.*, +, *TMECH Feb. 2021 255-266*
- A Tubular Dual-Roller Bending Mechanism Toward Robotic Transurethral Prostate Biopsy. Xiao, X., +, TMECH Oct. 2021 2483-2494

BioMEMS

Flux-Biased, Energy-Efficient Electromagnetic Micropumps Utilizing Bistable Magnetic Latching and Energy-Storage Springs. *Bhushan*, B.M., +, TMECH Oct. 2021 2362-2372

Biometrics (access control)

Tendon-Inspired Piezoelectric Sensor for Biometric Application. Kim, H., +, TMECH Oct. 2021 2538-2547

Biomimetics

Biomimetic Realization of a Robotic Penguin Wing: Design and Thrust Characteristics. Shen, Y., +, TMECH Oct. 2021 2350-2361

Diversified and Untethered Motion Generation Via Crease Patterning from Magnetically Actuated Caterpillar-Inspired Origami Robot. Cai, C.J., +, TMECH June 2021 1678-1688

- Dual Fast Marching Tree Algorithm for Human-Like Motion Planning of Anthropomorphic Arms With Task Constraints. Xia, J., +, TMECH Oct. 2021 2803-2813
- Efficient Cooperative Structured Control for a Multijoint Biomimetic Robotic Fish. Yan, S., +, TMECH Oct. 2021 2506-2516

Biothermics

A Fully Actuated Robotic Assistant for MRI-Guided Precision Conformal Ablation of Brain Tumors. *Li*, *G*., +, *TMECH Feb. 2021 255-266*

Blades

Design and Experimental Validation of a Novel High-Speed Omnidirectional Underwater Propulsion Mechanism. Njaka, T., +, TMECH Oct. 2021 2339-2349

Modeling Quadrotor Dynamics in a Wind Field. Jeon, H., +, TMECH June 2021 1401-1411

Blood

Automated Retinal Vein Cannulation on Silicone Phantoms Using Optical-Coherence-Tomography-Guided Robotic Manipulations. Gerber, M.J., +, TMECH Oct. 2021 2758-2769

Blood vessels

Automated Retinal Vein Cannulation on Silicone Phantoms Using Optical-Coherence-Tomography-Guided Robotic Manipulations. Gerber, M.J., +, TMECH Oct. 2021 2758-2769

Bode diagrams

Stability and Robustness of the Disturbance Observer-Based Motion Control Systems in Discrete-Time Domain. *Sariyildiz, E., +, TMECH Aug. 2021* 2139-2150

Body sensor networks

Incorporating the Qualitative Variable Comfort Into the Design of a Wearable Body Sensor System. Falch, L., +, TMECH Feb. 2021 124-133

+ Check author entry for coauthors

Bone

- A Surgical Robotic System for Treatment of Pelvic Osteolysis Using an FBG-Equipped Continuum Manipulator and Flexible Instruments. *Sefati, S.*, +, *TMECH Feb. 2021 369-380*
- Design and Experimental Validation of a Miniaturized Robotic Tendon-Driven Articulated Surgical Drill for Enhancing Distal Dexterity in Minimally Invasive Spine Fusion. Wang, Y., +, TMECH Aug. 2021 1858-1866
- Wearable Knee Assistive Devices for Kneeling Tasks in Construction. *Chen*, *S.*, +, *TMECH Aug. 2021 1989-1996*

Brachytherapy

- A Mechanism-Image Fusion Approach to Calibration of an Ultrasound-Guided Dual-Arm Robotic Brachytherapy System. *Xiong, J.*, +, *TMECH Dec. 2021 3211-3220*
- A Mechanism-Image Fusion Approach to Calibration of an Ultrasound-Guided Dual-Arm Robotic Brachytherapy System. *Xiong, J.*, +, *TMECH Dec. 2021 3211-3220*

Bragg gratings

A Surgical Robotic System for Treatment of Pelvic Osteolysis Using an FBG-Equipped Continuum Manipulator and Flexible Instruments. *Sefati, S.*, +, *TMECH Feb. 2021 369-380*

Brain

- A Fully Actuated Robotic Assistant for MRI-Guided Precision Conformal Ablation of Brain Tumors. *Li*, *G.*, +, *TMECH Feb. 2021 255-266*
- Brain–Machine Interface Using Functional Electrical Stimulation and Motion-Related Cortical Potentials Identified by a Support Vector Machine. *Miura*, S., +, *TMECH April 2021 1013-1021*

Brain-computer interfaces

Brain–Machine Interface Using Functional Electrical Stimulation and Motion-Related Cortical Potentials Identified by a Support Vector Machine. *Miura*, S., +, *TMECH April 2021 1013-1021*

Brakes

Nonlinear Model Predictive Control for Integrated Energy-Efficient Torque-Vectoring and Anti-Roll Moment Distribution. *Dalboni, M.*, +, *TMECH June 2021 1212-1224*

Bridges

- A Microgripper With a Large Magnification Ratio and High Structural Stiffness Based on a Flexure-Enabled Mechanism. *Shi*, C., +, *TMECH Dec.* 2021 3076-3086
- Development of a Concrete Floating and Delamination Detection System Using Infrared Thermography. *Chun, P., +, TMECH Dec. 2021 2835-2844* ideas (ctauatures)

Bridges (structures)

Geometrical-Based Displacement Measurement With Pseudostereo Monocular Camera on Bidirectional Cascaded Linear Actuator. *Lee, D.*, +, *TMECH Aug. 2021 1923-1931*

Brushless DC motors

A Computational-Effective Field-Oriented Control Strategy for Accurate and Efficient Electric Propulsion of Unmanned Aerial Vehicles. *Bosso, A.*, +, *TMECH June 2021 1501-1511*

Buckling

Curvature-Induced Buckling for Flapping-Wing Vehicles. Sharifzadeh, M., +, TMECH Feb. 2021 503-514

Buildings

C language

Robot-Assisted Object Detection for Construction Automation: Data and Information-Driven Approach. *Muhammad, I.*, +, *TMECH Dec. 2021* 2845-2856

Buildings (structures)

Façade Cleaning Robot With Manipulating and Sensing Devices Equipped on a Gondola. Chae, H., +, TMECH Aug. 2021 1719-1727

С

Computationally Efficient Practical Method for Solving the Dynamics of Fluid Power Circuits in the Presence of Singularities. *Malysheva*, J., +, *TMECH Oct. 2021 2385-2395*

Cables (electric)

- Dynamic Modeling and State Estimation of Cable-Conduit Actuation During Interaction With Nonpassive Environments. *Buchanan, S.*, +, *TMECH Oct.* 2021 2462-2471
- Cables (mechanical)
 - Coordinated Dynamic Control in the Task Space for Redundantly Actuated Cable-Driven Parallel Robots. *Zhang, B.,* +, *TMECH Oct. 2021 2396-2407* Vibration Reduction of Flexible Rope-Driven Mobile Robot for Safe Façade Operation. *Seo, M.,* +, *TMECH Aug. 2021 1812-1819*

CAD

Automated In Situ Placing of Metal Components Into 3-D Printed FFF Objects. Ahlers, D., +, TMECH Aug. 2021 1886-1894

Calibration

- A Mechanism-Image Fusion Approach to Calibration of an Ultrasound-Guided Dual-Arm Robotic Brachytherapy System. *Xiong, J.*, +, *TMECH Dec. 2021 3211-3220*
- An Automated AFM Tip-Replacement System for *In Situ* Tip-Replacement. *Vikrant, K.S.*, +, *TMECH April 2021 798-806*
- Constrained Surrogate-Based Engine Calibration Using Lower Confidence Bound. Pal, A., +, TMECH Dec. 2021 3116-3127
- Design and Testing of a New Force-Sensing Cell Microinjector Based on Small-Stiffness Compliant Mechanism. *Wei, Y., +, TMECH April 2021 818-829*
- Development of a Resonant Scanner to Improve the Imaging Rate of Astigmatic Optical Profilometers. *Liao, H., +, TMECH April 2021 1172-1177*
- Dynamic Path Correction of an Industrial Robot Using a Distance Sensor and an ADRC Controller. *Khaled, T.A.*, +, *TMECH June 2021 1646-1656* Globally Optimal Symbolic Hand-Eye Calibration. *Wu, J.*, +, *TMECH June* 2021 1369-1379
- MEMS-Enabled Retrofitting of Automobile Wheel Balancer for Automatic Unbalance Detection. *Pozzato, G.,* +, *TMECH April 2021 830-840*
- Pose Error Estimation Using a Cylinder in Scanner-Based Robotic Belt Grinding. Xie, H., +, TMECH Feb. 2021 515-526
- UltraLow Noise, High Bandwidth, Low Latency, No Overload 6-Axis Optical Force Sensor. *Hosseinabadi, A.H.H.*, +, *TMECH Oct. 2021 2581-2592*

Cameras

- Automated Retinal Vein Cannulation on Silicone Phantoms Using Optical-Coherence-Tomography-Guided Robotic Manipulations. Gerber, M.J., +, TMECH Oct. 2021 2758-2769
- Autonomous Navigation of Magnetic Microrobots in a Large Workspace Using Mobile-Coil System. Yang, Z., +, TMECH Dec. 2021 3163-3174
- Camera Orientation Optimization in Stereo Vision Systems for Low Measurement Error. *Liu*, *X.*, +, *TMECH April 2021 1178-1182*
- Development of a Concrete Floating and Delamination Detection System Using Infrared Thermography. Chun, P., +, TMECH Dec. 2021 2835-2844
- Geometrical-Based Displacement Measurement With Pseudostereo Monocular Camera on Bidirectional Cascaded Linear Actuator. *Lee, D.*, +, *TMECH Aug. 2021 1923-1931*
- Modeling and Experimental Validation of a Planar Microconveyor Based on a 2 × 2 Array of Digital Electromagnetic Actuators. *Tisnes, S.D.*, +, *TMECH June 2021 1422-1432*
- Nontarget-Based Measurement of 6-DOF Structural Displacement Using Combined RGB Color and Depth Information. *Lee, S.*, +, *TMECH June* 2021 1358-1368
- Radial Coverage Strength for Optimization of Monocular Multicamera Deployment. Lei, Z., +, TMECH Dec. 2021 3221-3231
- Self-Balancing Two-Wheeled Robot Featuring Intelligent End-to-End Deep Visual-Steering. Li, C.G., +, TMECH Oct. 2021 2263-2273
- Virtual Landmark-Based Control of Docking Support for Assistive Mobility Devices. Chen, Y., +, TMECH Aug. 2021 2007-2015

Cancer

- A Tubular Dual-Roller Bending Mechanism Toward Robotic Transurethral Prostate Biopsy. Xiao, X., +, TMECH Oct. 2021 2483-2494
- Development of a Soft Robot Based Photodynamic Therapy for Pancreatic Cancer. *Li*, *Y*., +, *TMECH Dec. 2021 2977-2985*
- Robotized Catheter With Enhanced Distal Targeting for Peripheral Pulmonary Biopsy. Kato, T., +, TMECH Oct. 2021 2451-2461

Carbon fiber reinforced composites

Segmentation-Oriented Compressed Sensing for Efficient Impact Damage Detection on CFRP Materials. *Tang, C.*, +, *TMECH Oct. 2021 2528-2537* Cascade control

Vision-Based Control of a Knuckle Boom Crane With Online Cable Length Estimation. *Tysse, G.O.*, +, *TMECH Feb. 2021 416-426*

Catheters

Robotized Catheter With Enhanced Distal Targeting for Peripheral Pulmonary Biopsy. *Kato*, *T.*, +, *TMECH Oct. 2021 2451-2461*

Centrifuges

- An Efficient Design Solution for a Low-Cost High-G Centrifuge System. Mohajer, N., +, TMECH Feb. 2021 134-145
- Cleaning Façade Cleaning Robot With Manipulating and Sensing Devices Equipped on a Gondola. *Chae, H., +, TMECH Aug. 2021 1719-1727*

Closed loop systems

- A Monolithic Force Sensing Integrated Flexure Bonder Dedicated to Flip-Chip Active Soft-Landing Interconnection. *Tang, H.*, +, *TMECH Feb.* 2021 323-334
- A Novel Rotational Actuator With Variable Stiffness Using S-Shaped Springs. Xu, Y., +, TMECH Aug. 2021 2249-2260
- A Visual Servo-Based Predictive Control With Echo State Gaussian Process for Soft Bending Actuator. *Cao*, Y., +, *TMECH Feb. 2021 574-585*
- Adaptive Output Feedback Control of Steer-by-Wire Systems With Event-Triggered Communication. *Ma*, *B*., +, *TMECH Aug. 2021 1968-1979*
- Adaptive Robust Finite-Time Nonlinear Control of a Typical Autonomous Underwater Vehicle With Saturated Inputs and Uncertainties. *Sedghi, F.,* +, *TMECH Oct. 2021 2517-2527*
- An Output Feedback Based Robust Saturated Controller Design for Pavement Sweeping Self-Reconfigurable Robot. *Rayguru, M.M.*, +, *TMECH June 2021 1236-1247*
- Asymptotic Tracking Control of Mechanical Servosystems With Mismatched Uncertainties. Deng, W., +, TMECH Aug. 2021 2204-2214
- Closed-Loop Range-Based Control of Dual-Stage Nanopositioning Systems. *Mitrovic, A., +, TMECH June 2021 1412-1421*
- Coordinated Dynamic Control in the Task Space for Redundantly Actuated Cable-Driven Parallel Robots. Zhang, B., +, TMECH Oct. 2021 2396-2407
- Development and Test of a Two-Dimensional Stacked Terfenol-D Actuator With High Bandwidth and Large Stroke. *Chen, L.*, +, *TMECH Aug. 2021* 1951-1959
- Development of a Nanopositioning Platform With Large Travel Range Based on Bionic Quadruped Piezoelectric Actuator. *Deng, J.*, +, *TMECH Aug.* 2021 2059-2070
- Distributed Control Algorithm for Leader–Follower Formation Tracking of Multiple Quadrotors: Theory and Experiment. *Wang, Z.*, +, *TMECH April* 2021 1095-1105
- Distributed Formation Control Using Fuzzy Self-Tuning of Strictly Negative Imaginary Consensus Controllers in Aerial Robotics. *Tran, V.P.*, +, *TMECH Oct. 2021 2306-2315*
- Dynamic Control of Multisection Three-Dimensional Continuum Manipulators Based on Virtual Discrete-Jointed Robot Models. *Wang, C.*, +, *TMECH April 2021 777-788*
- Event-Triggered-Based Discrete-Time Neural Control for a Quadrotor UAV Using Disturbance Observer. Shao, S., +, TMECH April 2021 689-699
- Experimental Investigation on Control of an Infinitely Variable Transmission System for Tidal Current Energy Converters. *Li*, *G.*, +, *TMECH Aug.* 2021 1960-1967
- Finite-Time Synchronization Control for Bilateral Teleoperation Systems With Asymmetric Time-Varying Delay and Input Dead Zone. *Bao, J.*, +, *TMECH June 2021 1570-1580*
- Fractional-Order Control for Uncertain Teleoperated Cyber-Physical System With Actuator Fault. *Ma*, *Z*., +, *TMECH Oct. 2021 2472-2482*
- Investigation of Micromotion Kinematics of Continuum Robots for Volumetric OCT and OCT-Guided Visual Servoing. *Giudice, G.D.*, +, *TMECH Oct.* 2021 2604-2615

- Low Impedance-Guaranteed Gain-Scheduled GESO for Torque-Controlled VSA With Application of Exoskeleton-Assisted Sit-to-Stand. *Liu, L.*, +, *TMECH Aug. 2021 2080-2091*
- Modeling and Motion Control of Industrial Tractor-Trailers Vehicles Using Force Compensation. Zhao, H., +, TMECH April 2021 645-656
- Neurodynamics-Based Model Predictive Control of Continuous-Time Under-Actuated Mechatronic Systems. *Wang, J.*, +, *TMECH Feb. 2021* 311-322
- Passivity-Based Nonlinear Control Approach for Tracking Task of an Underactuated CMG. *Toriumi, F.Y.*, +, *TMECH Oct. 2021 2285-2293*
- Path Following of Wheeled Mobile Robots Using Online-Optimization-Based Guidance Vector Field. Chen, J., +, TMECH Aug. 2021 1737-1744
- Proportional-Integral Approximation-Free Control of Robotic Systems With Unknown Dynamics. *Zhang, C., +, TMECH Aug. 2021 2226-2236*
- Quasi-Synchronization Control of Multiple Electrohydraulic Actuators With Load Disturbance and Uncertain Parameters. *Guo, Q.*, +, *TMECH Aug.* 2021 2048-2058
- Robust Adaptive Tracking Control of Underwater Vehicles: Design, Stability Analysis, and Experiments. *Tijjani, A.S.*, +, *TMECH April 2021 897-907*
- Robust Tracking Control of a Quadrotor Unmanned Aerial Vehicle-Suspended Payload System. Xian, B., +, TMECH Oct. 2021 2653-2663
- Self-Sensing and Control of Soft Electrothermal Actuator. Cao, Y., +, TMECH April 2021 854-863
- Semiactively Controllable Vehicle Seat Suspension System With Negative Stiffness Magnetic Spring. *Tu, L.*, +, *TMECH Feb. 2021 156-167*
- Unified Motion/Force/Impedance Control for Manipulators in Unknown Contact Environments Based on Robust Model-Reaching Approach. *Lin*, *Y*, +, *TMECH Aug. 2021 1905-1913*
- Vision-Based Cutting Control of Deformable Objects With Surface Tracking. Han, L., +, TMECH Aug. 2021 2016-2026

Clustering methods

Weakly Supervised Acoustic Defect Detection in Concrete Structures Using Clustering-Based Augmentation. Kasahara, J.Y.L., +, TMECH Dec. 2021 2826-2834

Coatings

Feature Analyses and Modeling of Lithium-Ion Battery Manufacturing Based on Random Forest Classification. *Liu, K., +, TMECH Dec. 2021* 2944-2955

Coils

A Novel Wireless 5-D Electromagnetic Tracking System Based on Nine-Channel Sinusoidal Signals. *Yang, W.*, +, *TMECH Feb. 2021 246-254*

- Design Method for Reducing AC Resistance of Traction Motor Using High Fill Factor Coil to Improve the Fuel Economy of eBus. *Cha, K., +, TMECH June 2021 1260-1270*
- Design, Modeling, and Experiments of Electromagnetic Energy Harvester Embedded in Smart Watch and Wristband as Power Source. *Cai*, *M.*, +, *TMECH Aug. 2021 2104-2114*

Collaboration

- MPC-Based Haptic Shared Steering System: A Driver Modeling Approach for Symbiotic Driving. *Lazcano, A.M.*, +, *TMECH June 2021 1201-1211* Collision avoidance
 - A Constrained DMPs Framework for Robot Skills Learning and Generalization From Human Demonstrations. Lu, Z., +, TMECH Dec. 2021 3265-3275
 - A Hybrid Active and Passive Cable-Driven Segmented Redundant Manipulator: Design, Kinematics, and Planning. *Liu, T., +, TMECH April 2021* 930-942
 - A Novel Clustering-Based Algorithm for Solving Spatially Constrained Robotic Task Sequencing Problems. *Wong, C., +, TMECH Oct. 2021 2294-2305*
 - An Active Sense and Avoid System for Flying Robots in Dynamic Environments. Chen, G., +, TMECH April 2021 668-678
 - Design and Real-Time Optimization for a Magnetic Actuation System With Enhanced Flexibility. *Du*, *X.*, +, *TMECH June 2021 1524-1535*
 - Efficient Motion Planning Based on Kinodynamic Model for Quadruped Robots Following Persons in Confined Spaces. *Zhang, Z.*, +, *TMECH Aug.* 2021 1997-2006

- Formation Reconstruction and Trajectory Replanning for Multi-UAV Patrol. Wang, Y., +, TMECH April 2021 719-729
- Human-in-the-Loop Control of a Wearable Lower Limb Exoskeleton for Stable Dynamic Walking. *Li*, *Z*., +, *TMECH Oct. 2021 2700-2711*
- Modified Configuration Control With Potential Field for Inverse Kinematic Solution of Redundant Manipulator. *Kim, J.*, +, *TMECH Aug. 2021 1782-1790*
- Planning Three-Dimensional Collision-Free Optimized Climbing Path for Biped Wall-Climbing Robots. *Zhu, H.*, +, *TMECH Oct. 2021 2712-2723*
- Real-Time Avoidance Strategy of Dynamic Obstacles via Half Model-Free Detection and Tracking With 2D Lidar for Mobile Robots. *Dong, H.*, +, *TMECH Aug. 2021 2215-2225*
- Toward Safe and Personalized Autonomous Driving: Decision-Making and Motion Control With DPF and CDT Techniques. *Huang, C.*, +, *TMECH April 2021 611-620*

Combustion

Adaptive Harmonic and Disturbance Estimators for Rotary Machines With Applications to Engines. *Vadamalu, R.S.*, +, *TMECH Feb. 2021 381-392* Compensation

- Magnetically Levitated Linear Drive Using an Active Gravity Compensation Based on Hybrid Shape Memory Actuators. *Raab, M.*, +, *TMECH June*
- 2021 1380-1391 Modeling and Adaptive Fault Compensation for Two Physically Linked 2WD Mobile Robots. *Ma*, *Y*, +, *TMECH April 2021 1161-1171*
- Online Compensation of Mechanical Load Defects With Composite Control in PMSM Drives. Kommuri, S.K., +, TMECH June 2021 1392-1400
- Testing of a Strained Silicon Based 3-D Stress Sensor for Out-of-Plane Stress Measurements. *Balbola, A.A.*, +, *TMECH April 2021 1076-1083*
- Tracking Accuracy Improvement Based on Adaptive Nonlinear Sliding Mode Control. *Tsai*, W., +, *TMECH Feb. 2021 179-190*

Compliance control

Dynamic Torso Compliance Control for Standing and Walking Balance of Position-Controlled Humanoid Robots. *Li*, *Q*., +, *TMECH April 2021 679-688*

Compliant mechanisms

Topology Optimization for Design of a 3D-Printed Constant-Force Compliant Finger. *Liu*, *C.*, +, *TMECH Aug. 2021 1828-1836*

Compressed sensing

Segmentation-Oriented Compressed Sensing for Efficient Impact Damage Detection on CFRP Materials. *Tang, C., +, TMECH Oct. 2021 2528-2537*

Compressors

Intelligent Fault Diagnosis of a Reciprocating Compressor Using Mode Isolation Convolutional Deep Belief Networks. *Zhang, Y.*, +, *TMECH June* 2021 1668-1677

Computational fluid dynamics

Computationally Efficient Practical Method for Solving the Dynamics of Fluid Power Circuits in the Presence of Singularities. *Malysheva*, J., +, *TMECH Oct. 2021 2385-2395*

Computational geometry

- Collaborative Semantic Understanding and Mapping Framework for Autonomous Systems. Yue, Y., +, TMECH April 2021 978-989
- Toolpath Regeneration in Subregional Contour-Parallel Processing Based on Isoscallop Method. Ma, J., +, TMECH April 2021 730-740

Computational modeling

- An Adaptive Fuzzy Trajectory Tracking Control via Improved Cerebellar Model Articulation Controller for Electro-Hydraulic Shovel. *Fan, R.*, +, *TMECH Dec. 2021 2870-2880*
- Constrained Surrogate-Based Engine Calibration Using Lower Confidence Bound. Pal, A., +, TMECH Dec. 2021 3116-3127
- Design and Validation of a Novel Fuzzy-Logic-Based Static Feedback Controller for Tendon-Driven Continuum Robots. *Ba, W.*, +, *TMECH Dec.* 2021 3010-3021

Computer vision

- Camera Orientation Optimization in Stereo Vision Systems for Low Measurement Error. *Liu*, *X.*, +, *TMECH April 2021 1178-1182*
- Nontarget-Based Measurement of 6-DOF Structural Displacement Using Combined RGB Color and Depth Information. *Lee, S.*, +, *TMECH June* 2021 1358-1368

Vision-Based Control of a Knuckle Boom Crane With Online Cable Length Estimation. *Tysse, G.O.*, +, *TMECH Feb. 2021 416-426*

Vision-Based Cutting Control of Deformable Objects With Surface Tracking. Han, L., +, TMECH Aug. 2021 2016-2026

Concrete

Development of a Concrete Floating and Delamination Detection System Using Infrared Thermography. *Chun, P., +, TMECH Dec. 2021 2835-2844*Weakly Supervised Acoustic Defect Detection in Concrete Structures Using Clustering-Based Augmentation. *Kasahara, J.Y.L., +, TMECH Dec. 2021 2826-2834*

Concurrency control

A Surgical Robotic System for Treatment of Pelvic Osteolysis Using an FBG-Equipped Continuum Manipulator and Flexible Instruments. *Sefati, S.*, +, *TMECH Feb. 2021 369-380*

Condition monitoring

- A DC-Biased Scanning Induction Thermographic System for Characterizing Surface Cracks in Ferromagnetic Components. *Wu, J.*, +, *TMECH Oct.* 2021 2782-2790
- A New Position Detection and Status Monitoring System for Joint of SCARA. Lu, W., +, TMECH June 2021 1613-1623
- An Investigation Into Fault Diagnosis of Planetary Gearboxes Using A Bispectrum Convolutional Neural Network. *Pang, X.*, +, *TMECH Aug.* 2021 2027-2037
- Failure Monitoring and Predictive Maintenance of Hydraulic Cylinder— State-of-the-Art Review. Shanbhag, V.V., +, TMECH Dec. 2021 3087-3103
- Geometrical-Based Displacement Measurement With Pseudostereo Monocular Camera on Bidirectional Cascaded Linear Actuator. *Lee, D.*, +, *TMECH Aug. 2021 1923-1931*

Intelligent Fault Diagnosis of a Reciprocating Compressor Using Mode Isolation Convolutional Deep Belief Networks. *Zhang, Y.*, +, *TMECH June* 2021 1668-1677

Conductors

Estimation of the Electrostatic Effects in the LISA-Pathfinder Critical Test Mass Dynamics via the Method of Moments. *Zanoni, C.*, +, *TMECH Dec.* 2021 3022-3030

Connectors

A Hermaphrodite Electromechanical Connector for Self-Reconfigurable Robot Modules. *Tian, X.,* +, *TMECH Dec. 2021 3276-3281*

Slider-Tendon Linear Actuator With Under-Actuation and Fast-Connection for Soft Wearable Robots. *Kim, B.*, +, *TMECH Dec. 2021 2932-2943* Constraint handling

Constraint handling

Construction industry

Development of a Concrete Floating and Delamination Detection System Using Infrared Thermography. Chun, P., +, TMECH Dec. 2021 2835-2844

- Guest Editorial Introduction to the Focused Section on Mechatronics and Automation for Constructions. *Cheah, C.C.*, +, *TMECH Dec. 2021 2819-2825*
- Robot-Assisted Object Detection for Construction Automation: Data and Information-Driven Approach. *Muhammad, I.*, +, *TMECH Dec. 2021* 2845-2856

Weakly Supervised Acoustic Defect Detection in Concrete Structures Using Clustering-Based Augmentation. Kasahara, J.Y.L., +, TMECH Dec. 2021 2826-2834

Continuum mechanics

Construction of Controller Model of Notch Continuum Manipulator for Laryngeal Surgery Based on Hybrid Method. *Wang, H., +, TMECH April* 2021 1022-1032

Control engineering computing

- Amaran: An Unmanned Robotic Coconut Tree Climber and Harvester. Megalingam, R.K., +, TMECH Feb. 2021 288-299
- Covert Attacks Through Adversarial Learning: Study of Lane Keeping Attacks on the Safety of Autonomous Vehicles. *Farivar, F., +, TMECH June 2021 1350-1357*
- Cyber–Physical Codesign of Field-Level Reconfigurations in Networked Motion Controllers. Zhou, N., +, TMECH Aug. 2021 2092-2103

- Design and Rapid Construction of a Cost-Effective Virtual Haptic Device. Wang, F., +, TMECH Feb. 2021 66-77
- Individual Auxiliary and Fault-Tolerant Control of Steer-by-Wire System Considering Different Drivers Steering Characteristics. *Zhao, W.*, +, *TMECH June 2021 1558-1569*
- Optimal Current Allocation Rendering 3-D Magnetic Force Production in Hexapole Electromagnetic Actuation. *Long, F., +, TMECH Oct. 2021* 2408-2417
- Toward Safe and Personalized Autonomous Driving: Decision-Making and Motion Control With DPF and CDT Techniques. *Huang, C.*, +, *TMECH April 2021 611-620*

Control nonlinearities

- Asymptotic Tracking Control of Mechanical Servosystems With Mismatched Uncertainties. *Deng, W.*, +, *TMECH Aug. 2021 2204-2214*
- Event-Triggered-Based Discrete-Time Neural Control for a Quadrotor UAV Using Disturbance Observer. Shao, S., +, TMECH April 2021 689-699
- Iterative Learning Control for Video-Rate Atomic Force Microscopy. Nikooienejad, N., +, TMECH Aug. 2021 2127-2138
- Sliding-Mode-Disturbance-Observer-Based Robust Tracking Control for Omnidirectional Mobile Robots With Kinematic and Dynamic Uncertainties. Jeong, S., +, TMECH April 2021 741-752

Takagi–Sugeno Fuzzy Unknown Input Observers to Estimate Nonlinear Dynamics of Autonomous Ground Vehicles: Theory and Real-Time Verification. *Nguyen, A.*, +, *TMECH June 2021 1328-1338*

Control system analysis

Stability and Robustness of the Disturbance Observer-Based Motion Control Systems in Discrete-Time Domain. Sariyildiz, E., +, TMECH Aug. 2021 2139-2150

Control system synthesis

- A Computational-Effective Field-Oriented Control Strategy for Accurate and Efficient Electric Propulsion of Unmanned Aerial Vehicles. *Bosso, A.*, +, *TMECH June 2021 1501-1511*
- A Generalized Design Method for Learning-Based Disturbance Observer. Zheng, M., +, TMECH Feb. 2021 45-54
- A Lie-Theory-Based Dynamic Parameter Identification Methodology for Serial Manipulators. *Fu*, *Z*., +, *TMECH Oct. 2021 2688-2699*
- A Novel Rotational Actuator With Variable Stiffness Using S-Shaped Springs. Xu, Y, +, TMECH Aug. 2021 2249-2260
- A Phase-Shaping Approach to the Control of Parametric Systems and Its Application. *Shimonomura*, S., +, *TMECH Aug. 2021 2163-2173*
- A Tilting-Rotor Unmanned Aerial Vehicle for Enhanced Aerial Locomotion and Manipulation Capabilities: Design, Control, and Applications. *Ding, C.*, +, *TMECH Aug. 2021 2237-2248*
- A Visual Servo-Based Predictive Control With Echo State Gaussian Process for Soft Bending Actuator. *Cao*, Y, +, *TMECH Feb. 2021 574-585*
- Active Disturbance Rejection Control for a Fluid-Driven Hand Rehabilitation Device. *Li*, *H.*, +, *TMECH April 2021 841-853*
- Adaptive Finite-Time Control for Half-Vehicle Active Suspension Systems With Uncertain Dynamics. *Liu, Y., +, TMECH Feb. 2021 168-178*
- Adaptive Output Feedback Control of Steer-by-Wire Systems With Event-Triggered Communication. *Ma*, *B*., +, *TMECH Aug. 2021 1968-1979*
- Adaptive Robust Finite-Time Nonlinear Control of a Typical Autonomous Underwater Vehicle With Saturated Inputs and Uncertainties. *Sedghi, F.*, +, *TMECH Oct. 2021 2517-2527*
- An Output Feedback Based Robust Saturated Controller Design for Pavement Sweeping Self-Reconfigurable Robot. *Rayguru, M.M.*, +, *TMECH June 2021 1236-1247*
- Analytical Design and Experimental Verification of Geofencing Control for Aerial Applications. *Ghaffari, A., TMECH April 2021 1106-1117*
- Asymptotic Tracking Control of Mechanical Servosystems With Mismatched Uncertainties. *Deng, W.*, +, *TMECH Aug. 2021 2204-2214*
- Closed-Loop Range-Based Control of Dual-Stage Nanopositioning Systems. *Mitrovic, A., +, TMECH June 2021 1412-1421*
- Computationally Improved State-Dependent Riccati Equation Scheme for Nonlinear Benchmark System. *Lin, L., TMECH April 2021 1064-1075*

Constrained Surrogate-Based Engine Calibration Using Lower Confidence Bound. Pal, A., +, TMECH Dec. 2021 3116-3127

- Control Parameters Design Based on Dynamic Characteristics of a Hybrid Robot With Parallelogram Structures. *Liu, Z.*, +, *TMECH April 2021 1140-1150*
- Design and Experimental Validation of a Miniaturized Robotic Tendon-Driven Articulated Surgical Drill for Enhancing Distal Dexterity in Minimally Invasive Spine Fusion. *Wang, Y.*, +, *TMECH Aug. 2021 1858-1866*
- Design and Experimental Validation of Robust Self-Scheduled Fault-Tolerant Control Laws for a Multicopter UAV. Nguyen, D., +, TMECH Oct. 2021 2548-2557
- Development of a Nanopositioning Platform With Large Travel Range Based on Bionic Quadruped Piezoelectric Actuator. *Deng, J.*, +, *TMECH Aug.* 2021 2059-2070
- Distributed Control Algorithm for Leader–Follower Formation Tracking of Multiple Quadrotors: Theory and Experiment. Wang, Z., +, TMECH April 2021 1095-1105
- Distributed Formation Control Using Fuzzy Self-Tuning of Strictly Negative Imaginary Consensus Controllers in Aerial Robotics. *Tran, V.P.*, +, *TMECH Oct. 2021 2306-2315*
- Efficient Cooperative Structured Control for a Multijoint Biomimetic Robotic Fish. Yan, S., +, TMECH Oct. 2021 2506-2516
- Event-Triggered-Based Discrete-Time Neural Control for a Quadrotor UAV Using Disturbance Observer. Shao, S., +, TMECH April 2021 689-699
- Experimental Investigation on Control of an Infinitely Variable Transmission System for Tidal Current Energy Converters. Li, G., +, TMECH Aug. 2021 1960-1967
- Finite-Time Synchronization Control for Bilateral Teleoperation Systems With Asymmetric Time-Varying Delay and Input Dead Zone. *Bao, J.*, +, *TMECH June 2021 1570-1580*
- Fractional-Order Control for Uncertain Teleoperated Cyber-Physical System With Actuator Fault. *Ma*, *Z*., +, *TMECH Oct.* 2021 2472-2482
- Fully Actuated Autonomous Flight of Thruster-Tilting Multirotor. Lee, S.J., +, TMECH April 2021 765-776
- Fully Distributed Cooperative Circumnavigation of Networked Unmanned Aerial Vehicles. Li, D., +, TMECH April 2021 709-718
- Hybrid Control Strategy for Force and Precise End Effector Positioning of a Twisted String Actuator. Rodriguez, A.S., +, TMECH Oct. 2021 2791-2802
- Iterative Learning Control for Video-Rate Atomic Force Microscopy. Nikooienejad, N., +, TMECH Aug. 2021 2127-2138
- Kernel-Orthogonal Control of Tensegrity Systems. Yang, S., TMECH April 2021 1043-1052
- Modeling and Adaptive Fault Compensation for Two Physically Linked 2WD Mobile Robots. *Ma*, *Y*, +, *TMECH April 2021 1161-1171*
- Modeling and Motion Control of Industrial Tractor-Trailers Vehicles Using Force Compensation. Zhao, H., +, TMECH April 2021 645-656
- Modeling Quadrotor Dynamics in a Wind Field. Jeon, H., +, TMECH June 2021 1401-1411
- Online Compensation of Mechanical Load Defects With Composite Control in PMSM Drives. Kommuri, S.K., +, TMECH June 2021 1392-1400
- Parallel Compliance Design for Increasing Robustness and Efficiency in Legged Locomotion–Theoretical Background and Applications. Sharbafi, M.A., +, TMECH Feb. 2021 335-346
- Path Following of Wheeled Mobile Robots Using Online-Optimization-Based Guidance Vector Field. Chen, J., +, TMECH Aug. 2021 1737-1744
- Phase-Relaxed-Passive Full State Feedback Gain Limits for Series Elastic Actuators. *Thomas, G.C.,* +, *TMECH Feb. 2021 586-591*
- Position-Tracking Control of Dual-Rope Winch Robot With Rope Slip Compensation. Yoo, S., +, TMECH Aug. 2021 1754-1762
- Practical Fixed-Time Position Tracking Control of Permanent Magnet DC Torque Motor Systems. *Wu, Y.*, +, *TMECH Feb. 2021 563-573*
- Practical Terminal Sliding Mode Control of Nonlinear Uncertain Active Suspension Systems With Adaptive Disturbance Observer. *Wang, G.*, +, *TMECH April 2021 789-797*
- Precise Linear-Motor Synchronization Control via Cross-Coupled Second-Order Discrete-Time Fractional-Order Sliding Mode. Kuang, Z., +, TMECH Feb. 2021 358-368

- Proportional-Integral Approximation-Free Control of Robotic Systems With Unknown Dynamics. *Zhang, C., +, TMECH Aug. 2021 2226-2236*
- Quasi-Synchronization Control of Multiple Electrohydraulic Actuators With Load Disturbance and Uncertain Parameters. *Guo, Q.*, +, *TMECH Aug.* 2021 2048-2058
- Robust Adaptive Tracking Control of Underwater Vehicles: Design, Stability Analysis, and Experiments. *Tijjani, A.S.*, +, *TMECH April 2021 897-907*
- Robust Concurrent Design of a 2-DOF Collaborative Robot (Cobot). Mendoza-Trejo, O., +, TMECH Feb. 2021 347-357
- Robust Tracking Control of a Quadrotor Unmanned Aerial Vehicle-Suspended Payload System. Xian, B., +, TMECH Oct. 2021 2653-2663
- Rotor Position Tracking Control for Low Speed Operation of Direct-Drive PMSM Servo System. *Bu*, *F*, +, *TMECH April 2021 1129-1139*
- Self-Sensing and Control of Soft Electrothermal Actuator. Cao, Y., +, TMECH April 2021 854-863
- Sliding Mode Control With Model-Based Switching Functions Applied on a 7-DOF Exoskeleton Arm. Fallaha, C., +, TMECH Feb. 2021 539-550
- Sliding-Mode-Disturbance-Observer-Based Robust Tracking Control for Omnidirectional Mobile Robots With Kinematic and Dynamic Uncertainties. *Jeong, S.*, +, *TMECH April 2021 741-752*
- Stability and Robustness of the Disturbance Observer-Based Motion Control Systems in Discrete-Time Domain. *Sariyildiz, E., +, TMECH Aug. 2021* 2139-2150
- Swing-Reducing Flight Control System for an Underactuated Indoor Miniature Autonomous Blimp. *Tao*, *Q*., +, *TMECH Aug*. 2021 1895-1904
- Takagi–Sugeno Fuzzy Unknown Input Observers to Estimate Nonlinear Dynamics of Autonomous Ground Vehicles: Theory and Real-Time Verification. Nguyen, A., +, TMECH June 2021 1328-1338
- Takagi–Sugeno Fuzzy-Based Robust H∞ Integrated Lane-Keeping and Direct Yaw Moment Controller of Unmanned Electric Vehicles. Guo, J., +, TMECH Aug. 2021 2151-2162
- Tracking Accuracy Improvement Based on Adaptive Nonlinear Sliding Mode Control. *Tsai*, W., +, *TMECH Feb. 2021 179-190*

Controllability

- Robust Concurrent Design of a 2-DOF Collaborative Robot (Cobot). Mendoza-Trejo, O., +, TMECH Feb. 2021 347-357
- **Convex programming**
 - A Lie-Theory-Based Dynamic Parameter Identification Methodology for Serial Manipulators. *Fu*, *Z*., +, *TMECH Oct. 2021 2688-2699*
- Conveyors
 - Modeling and Experimental Validation of a Planar Microconveyor Based on a 2 × 2 Array of Digital Electromagnetic Actuators. *Tisnes, S.D.*, +, *TMECH June 2021 1422-1432*

Convolutional neural nets

- Self-Balancing Two-Wheeled Robot Featuring Intelligent End-to-End Deep Visual-Steering. Li, C.G., +, TMECH Oct. 2021 2263-2273
- Terrain Identification for Humanoid Robots Applying Convolutional Neural Networks. *Venancio, M.M.*, +, *TMECH June 2021 1433-1444*
- Weighted Entropy Minimization Based Deep Conditional Adversarial Diagnosis Approach Under Variable Working Conditions. She, D., +, TMECH Oct. 2021 2440-2450

Cooling

Thermal Modeling and Characterization of Twisted Coiled Actuators for Upper Limb Wearable Devices. *Edmonds, B.P.R.*, +, *TMECH April 2021* 966-977

Couplings

- A Constrained DMPs Framework for Robot Skills Learning and Generalization From Human Demonstrations. *Lu*, *Z*., +, *TMECH Dec. 2021 3265-3275*
- Design and Validation of a Novel Fuzzy-Logic-Based Static Feedback Controller for Tendon-Driven Continuum Robots. *Ba, W.*, +, *TMECH Dec.* 2021 3010-3021
- Energy-Based Modeling of Ionic Polymer–Metal Composite Actuators Dedicated to the Control of Flexible Structures. *Liu, N.*, +, *TMECH Dec. 2021* 3139-3150
- Similitude Analysis Method of the Dynamics of a Hybrid Spray-Painting Robot Considering Electromechanical Coupling Effect. *Song, Y.*, +, *TMECH Dec. 2021 2986-2997*

Crack detection

A DC-Biased Scanning Induction Thermographic System for Characterizing Surface Cracks in Ferromagnetic Components. *Wu, J.*, +, *TMECH Oct.* 2021 2782-2790

Cracks

- A DC-Biased Scanning Induction Thermographic System for Characterizing Surface Cracks in Ferromagnetic Components. *Wu, J.*, +, *TMECH Oct.* 2021 2782-2790
- An Investigation Into Fault Diagnosis of Planetary Gearboxes Using A Bispectrum Convolutional Neural Network. *Pang, X.*, +, *TMECH Aug.* 2021 2027-2037

Cranes

Vision-Based Control of a Knuckle Boom Crane With Online Cable Length Estimation. *Tysse, G.O.*, +, *TMECH Feb. 2021 416-426*

Curve fitting

Construction of Controller Model of Notch Continuum Manipulator for Laryngeal Surgery Based on Hybrid Method. *Wang, H.*, +, *TMECH April* 2021 1022-1032

Cutting

- Generative Adversarial Network for Prediction of Workpiece Surface Topography in Machining Stage. *Cao, L., +, TMECH Feb. 2021 480-490* Toolpath Regeneration in Subregional Contour-Parallel Processing Based on Isoscallop Method. *Ma, J., +, TMECH April 2021 730-740*
- Vision-Based Cutting Control of Deformable Objects With Surface Tracking. Han, L., +, TMECH Aug. 2021 2016-2026

Cutting tools

- Generative Adversarial Network for Prediction of Workpiece Surface Topography in Machining Stage. *Cao, L., +, TMECH Feb. 2021 480-490* Toolpath Regeneration in Subregional Contour-Parallel Processing Based on
- Isoscallop Method. Ma, J., +, TMECH April 2021 730-740

D

Damping

- Global Optimization of the Hydraulic-Electromagnetic Energy-Harvesting Shock Absorber for Road Vehicles With Human-Knowledge-Integrated Particle Swarm Optimization Scheme. *Zhou, Q.*, +, *TMECH June 2021* 1225-1235
- Intelligent Vibration Control for Semiactive Suspension Systems Without Prior Knowledge of Dynamical Nonlinear Damper Behaviors Based on Improved Extreme Learning Machine. *Huang, W.*, +, *TMECH Aug. 2021* 2071-2079
- Mechanism and Controller Design of a Transfemoral Prosthesis With Electrohydraulic Knee and Motor-Driven Ankle. *Gao*, *S.*, +, *TMECH Oct.* 2021 2429-2439
- Semiactively Controllable Vehicle Seat Suspension System With Negative Stiffness Magnetic Spring. *Tu, L.*, +, *TMECH Feb. 2021 156-167*
- Shock Isolation Capability of an Electromagnetic Variable Stiffness Isolator With Bidirectional Stiffness Regulation. Zhao, J., +, TMECH Aug. 2021 2038-2047

Vibration Reduction of Flexible Rope-Driven Mobile Robot for Safe Façade Operation. Seo, M., +, TMECH Aug. 2021 1812-1819

Data analysis

Development of a Resonant Scanner to Improve the Imaging Rate of Astigmatic Optical Profilometers. *Liao, H., +, TMECH April 2021 1172-1177*

Data fusion

Radial Coverage Strength for Optimization of Monocular Multicamera Deployment. Lei, Z., +, TMECH Dec. 2021 3221-3231

Data models

Automatic Construction of Three-Dimensional Ground Model by Data Processing. *Takeyama*, *T.*, +, *TMECH Dec. 2021 2881-2887*

DC motors

Practical Fixed-Time Position Tracking Control of Permanent Magnet DC Torque Motor Systems. *Wu*, *Y*, +, *TMECH Feb. 2021 563-573*

Decentralized control

Formation Reconstruction and Trajectory Replanning for Multi-UAV Patrol. Wang, Y., +, TMECH April 2021 719-729

Decision making

Toward Safe and Personalized Autonomous Driving: Decision-Making and Motion Control With DPF and CDT Techniques. *Huang, C.*, +, *TMECH April 2021 611-620*

Deep learning

Edge-Dependent Efficient Grasp Rectangle Search in Robotic Grasp Detection. Chen, L., +, TMECH Dec. 2021 2922-2931

Deep learning (artificial intelligence)

Weighted Entropy Minimization Based Deep Conditional Adversarial Diagnosis Approach Under Variable Working Conditions. She, D., +, TMECH Oct. 2021 2440-2450

Deformation

- An Integrated Design and Fabrication Strategy for Planar Soft Dielectric Elastomer Actuators. *Chen, F., +, TMECH Oct. 2021 2629-2640*
- Modeling and Analysis of Soft Pneumatic Network Bending Actuators. *Liu*, *Z.*, +, *TMECH Aug. 2021 2195-2203*
- Sensing and Reconstruction of 3-D Deformation on Pneumatic Soft Robots. Scharff, R.B.N., +, TMECH Aug. 2021 1877-1885
- Tendon-Inspired Piezoelectric Sensor for Biometric Application. Kim, H., +, TMECH Oct. 2021 2538-2547
- Topology Optimization for Design of a 3D-Printed Constant-Force Compliant Finger. *Liu*, *C.*, +, *TMECH Aug. 2021 1828-1836*
- Topology Optimization of Skeleton-Reinforced Soft Pneumatic Actuators for Desired Motions. Chen, S., +, TMECH Aug. 2021 1745-1753

Delamination

- Development of a Concrete Floating and Delamination Detection System Using Infrared Thermography. *Chun, P.,* +, *TMECH Dec. 2021 2835-2844* Delays
 - Artificial-Delay Adaptive Control for Underactuated Euler-Lagrange Robotics. Roy, S., +, TMECH Dec. 2021 3064-3075
 - Experimental Investigation on Control of an Infinitely Variable Transmission System for Tidal Current Energy Converters. Li, G., +, TMECH Aug. 2021 1960-1967
 - Finite-Time Synchronization Control for Bilateral Teleoperation Systems With Asymmetric Time-Varying Delay and Input Dead Zone. *Bao, J.*, +, *TMECH June 2021 1570-1580*
 - Online Delayed Reference Generation for a Humanoid Imitating Human Walking Motion. *Oh, J.*, +, *TMECH Feb. 2021 102-112*
 - Optimized Power Modulation in Wave-Based Bilateral Teleoperation. *Ferraguti*, F., +, *TMECH Feb. 2021 276-287*

Design engineering

- A Method for Mass Flow and Displacement Estimation in a Pneumatic Actuation System Using Valve-Based Pressure Sensing. Vailati, L.G., +, TMECH Feb. 2021 235-245
- A Novel Wolfrom-Based Gearbox for Robotic Actuators. Crispel, S., +, TMECH Aug. 2021 1980-1988
- An Efficient Design Solution for a Low-Cost High-G Centrifuge System. Mohajer, N., +, TMECH Feb. 2021 134-145
- An Integrated Design and Fabrication Strategy for Planar Soft Dielectric Elastomer Actuators. Chen, F., +, TMECH Oct. 2021 2629-2640
- Biomimetic Realization of a Robotic Penguin Wing: Design and Thrust Characteristics. Shen, Y., +, TMECH Oct. 2021 2350-2361
- Curvature-Induced Buckling for Flapping-Wing Vehicles. Sharifzadeh, M., +, TMECH Feb. 2021 503-514
- Design and Control of Soft Unmanned Aerial Vehicle "S-CLOUD". Song, S.H., +, TMECH Feb. 2021 267-275
- Design and Experimental Validation of a Novel High-Speed Omnidirectional Underwater Propulsion Mechanism. *Njaka, T., +, TMECH Oct. 2021* 2339-2349
- Electrical Parameter Identification of Medium-Frequency DC Resistance Spot Welding System Using Intelligent Algorithm. *Wang, X.*, +, *TMECH Aug. 2021 1791-1802*
- Façade Cleaning Robot With Manipulating and Sensing Devices Equipped on a Gondola. *Chae*, H., +, *TMECH Aug. 2021 1719-1727*
- Global Optimization of the Hydraulic-Electromagnetic Energy-Harvesting Shock Absorber for Road Vehicles With Human-Knowledge-Integrated Particle Swarm Optimization Scheme. *Zhou, Q., +, TMECH June 2021 1225-1235*

- Integral Design and Manufacturing Methodology of a Reduced-Scale Servo Press. Olaizola, J., +, TMECH Oct. 2021 2418-2428
- Thermal Modeling and Characterization of Twisted Coiled Actuators for Upper Limb Wearable Devices. *Edmonds, B.P.R.*, +, *TMECH April 2021* 966-977
- Topology Optimization for Design of a 3D-Printed Constant-Force Compliant Finger. *Liu*, *C.*, +, *TMECH Aug. 2021 1828-1836*

Dexterous manipulators

- A Hybrid Active and Passive Cable-Driven Segmented Redundant Manipulator: Design, Kinematics, and Planning. *Liu*, *T.*, +, *TMECH April 2021 930-942*
- A Novel Cable-Driven 7-DOF Anthropomorphic Manipulator. *Huang, Y.*, +, *TMECH Aug. 2021 2174-2185*
- A Surgical Robotic System for Treatment of Pelvic Osteolysis Using an FBG-Equipped Continuum Manipulator and Flexible Instruments. *Sefati, S.*, +, *TMECH Feb.* 2021 369-380
- A Tilting-Rotor Unmanned Aerial Vehicle for Enhanced Aerial Locomotion and Manipulation Capabilities: Design, Control, and Applications. *Ding*, *C*., +, *TMECH Aug. 2021 2237-2248*
- A Two-Finger Soft-Robotic Gripper With Enveloping and Pinching Grasping Modes. *Liu*, S., +, *TMECH Feb. 2021 146-155*
- Design and Experimental Validation of a Miniaturized Robotic Tendon-Driven Articulated Surgical Drill for Enhancing Distal Dexterity in Minimally Invasive Spine Fusion. Wang, Y., +, TMECH Aug. 2021 1858-1866
- Design, Modeling, and Control of a 3D Printed Monolithic Soft Robotic Finger With Embedded Pneumatic Sensing Chambers. Tawk, C., +, TMECH April 2021 876-887
- Development of Embedded Sensor System for 5-DOF Finger-Wearable Tactile Interface. *Lim, B., +, TMECH Aug. 2021 1728-1736*
- Mechanical Aspects of Robot Hands, Active Hand Orthoses, and Prostheses: A Comparative Review. Vertongen, J., +, TMECH April 2021 955-965
- Otariidae-Inspired Soft-Robotic Supernumerary Flippers by Fabric Kirigami and Origami. *Liu, S.*, +, *TMECH Oct. 2021 2747-2757*
- Sliding Mode Control With Model-Based Switching Functions Applied on a 7-DOF Exoskeleton Arm. *Fallaha*, *C.*, +, *TMECH Feb. 2021 539-550*
- The MUSHA Hand II:A Multifunctional Hand for Robot-Assisted Laparoscopic Surgery. *Liu, H.*, +, *TMECH Feb. 2021 393-404*

Diesel engines

Adaptive Harmonic and Disturbance Estimators for Rotary Machines With Applications to Engines. *Vadamalu, R.S.*, +, *TMECH Feb. 2021 381-392*

Diffusion

Global Parameter Sensitivity Analysis of Electrochemical Model for Lithium-Ion Batteries Considering Aging. *Gao, Y.*, +, *TMECH June 2021 1283-1294*

Discrete time systems

Adaptive Robust Finite-Time Nonlinear Control of a Typical Autonomous Underwater Vehicle With Saturated Inputs and Uncertainties. *Sedghi, F*, +, *TMECH Oct. 2021 2517-2527*

Event-Triggered-Based Discrete-Time Neural Control for a Quadrotor UAV Using Disturbance Observer. Shao, S., +, TMECH April 2021 689-699

Diseases

- Automated Retinal Vein Cannulation on Silicone Phantoms Using Optical-Coherence-Tomography-Guided Robotic Manipulations. *Gerber, M.J.*, +, *TMECH Oct. 2021 2758-2769*
- Blindly Controlled Magnetically Actuated Capsule for Noninvasive Sampling of the Gastrointestinal Microbiome. *Shokrollahi*, P., +, *TMECH Oct.* 2021 2616-2628
- On-Body RF Sensor Toward Tremor Detection in Parkinson's Disease. Abirami B, S., +, TMECH Oct. 2021 2814-2817
- Robotized Catheter With Enhanced Distal Targeting for Peripheral Pulmonary Biopsy. *Kato, T.*, +, *TMECH Oct. 2021 2451-2461*

Displacement control

Modeling and Experimental Validation of a Planar Microconveyor Based on a 2 × 2 Array of Digital Electromagnetic Actuators. *Tisnes, S.D.*, +, *TMECH June 2021 1422-1432*

Displacement measurement

- Geometrical-Based Displacement Measurement With Pseudostereo Monocular Camera on Bidirectional Cascaded Linear Actuator. *Lee, D.*, +, *TMECH Aug. 2021 1923-1931*
- Nontarget-Based Measurement of 6-DOF Structural Displacement Using Combined RGB Color and Depth Information. *Lee, S.*, +, *TMECH June* 2021 1358-1368

UltraLow Noise, High Bandwidth, Low Latency, No Overload 6-Axis Optical Force Sensor. *Hosseinabadi, A.H.H.*, +, *TMECH Oct. 2021 2581-2592*

Distance measurement

Loop-Closure Detection With a Multiresolution Point Cloud Histogram Mode in Lidar Odometry and Mapping for Intelligent Vehicles. *Meng*, *Q*., +, *TMECH June 2021 1307-1317*

Distortion

Similitude Analysis Method of the Dynamics of a Hybrid Spray-Painting Robot Considering Electromechanical Coupling Effect. Song, Y., +, TMECH Dec. 2021 2986-2997

Distributed control

- Distributed Control Algorithm for Leader–Follower Formation Tracking of Multiple Quadrotors: Theory and Experiment. *Wang, Z.*, +, *TMECH April* 2021 1095-1105
- Distributed Formation Control Using Fuzzy Self-Tuning of Strictly Negative Imaginary Consensus Controllers in Aerial Robotics. *Tran, V.P.*, +, *TMECH Oct. 2021 2306-2315*
- Fully Distributed Cooperative Circumnavigation of Networked Unmanned Aerial Vehicles. Li, D., +, TMECH April 2021 709-718
- Nonlinear Model Predictive Control for Integrated Energy-Efficient Torque-Vectoring and Anti-Roll Moment Distribution. *Dalboni, M.*, +, *TMECH June 2021 1212-1224*

Drag

- Longitudinal Motion Modeling and Experimental Verification of a Microrobot Subject to Liquid Laminar Flow. *Demircali, A.A.*, +, *TMECH Dec.* 2021 2956-2966
- Modeling Quadrotor Dynamics in a Wind Field. Jeon, H., +, TMECH June 2021 1401-1411

Drilling

Design and Experimental Validation of a Miniaturized Robotic Tendon-Driven Articulated Surgical Drill for Enhancing Distal Dexterity in Minimally Invasive Spine Fusion. Wang, Y., +, TMECH Aug. 2021 1858-1866

Driver information systems

Toward Safe and Personalized Autonomous Driving: Decision-Making and Motion Control With DPF and CDT Techniques. *Huang, C.*, +, *TMECH April 2021 611-620*

Drives

Steady-State Characteristics Study of a Power Split Hydraulic Transmission. Wang, F, +, TMECH Feb. 2021 78-89

Drug delivery systems

- Measurement of Peristaltic Forces Exerted by Living Intestine on Robotic Capsule. *Rehan, M.*, +, *TMECH Aug. 2021 1803-1811*
- Optimal Design and Implementation of a Novel Two-Dimensional Electromagnetic Navigation System That Allows Focused Heating of Magnetic Nanoparticles. *Le, T., +, TMECH Feb. 2021 551-562*

Drugs

Automated Retinal Vein Cannulation on Silicone Phantoms Using Optical-Coherence-Tomography-Guided Robotic Manipulations. *Gerber, M.J.*, +, *TMECH Oct. 2021 2758-2769*

Dynamic programming

Real-Time Integrated Power and Thermal Management of Connected HEVs Based on Hierarchical Model Predictive Control. *Gong, X.*, +, *TMECH June 2021 1271-1282*

- Robust Concurrent Design of a 2-DOF Collaborative Robot (Cobot). Mendoza-Trejo, O., +, TMECH Feb. 2021 347-357
- Takagi–Sugeno Fuzzy-Based Robust H∞ Integrated Lane-Keeping and Direct Yaw Moment Controller of Unmanned Electric Vehicles. Guo, J., +, TMECH Aug. 2021 2151-2162

Dynamic response

A Monolithic Force Sensing Integrated Flexure Bonder Dedicated to Flip-Chip Active Soft-Landing Interconnection. Tang, H., +, TMECH Feb. 2021 323-334

Dynamics

- Data-Driven Iterative Trajectory Shaping for Precision Control of Flexible Feed Drives. Dumanli, A., +, TMECH Oct. 2021 2735-2746
- Reconstructing Walking Dynamics From Two Shank-Mounted Inertial Measurement Units. Li, T., +, TMECH Dec. 2021 3040-3050

Е

Eddy current testing

A DC-Biased Scanning Induction Thermographic System for Characterizing Surface Cracks in Ferromagnetic Components. Wu, J., +, TMECH Oct. 2021 2782-2790

Eddy currents

Static Pull-In Behavior of Hybrid Levitation Microactuators: Simulation, Modeling, and Experimental Study. Poletkin, K.V., TMECH April 2021 753-764

Edge detection

Autonomous Vision-Guided Object Collection From Water Surfaces With a Customized Multirotor. Mishra, S., +, TMECH Aug. 2021 1914-1922

Eigenvalues and eigenfunctions

Modeling and Adaptive Fault Compensation for Two Physically Linked 2WD Mobile Robots. Ma, Y., +, TMECH April 2021 1161-1171

Elastic moduli

Modeling of One-Ply and Two-Ply Twisted and Coiled Polymer Artificial Muscles. Karami, F., +, TMECH Feb. 2021 300-310

Elasticity

- A Novel Rotational Actuator With Variable Stiffness Using S-Shaped Springs. Xu, Y., +, TMECH Aug. 2021 2249-2260
- Diversified and Untethered Motion Generation Via Crease Patterning from Magnetically Actuated Caterpillar-Inspired Origami Robot. Cai, C.J., +, TMECH June 2021 1678-1688
- Modeling and Analysis of Soft Pneumatic Network Bending Actuators. Liu, Z., +, TMECH Aug. 2021 2195-2203
- Phase-Relaxed-Passive Full State Feedback Gain Limits for Series Elastic Actuators. Thomas, G.C., +, TMECH Feb. 2021 586-591
- Tendon-Inspired Piezoelectric Sensor for Biometric Application. Kim, H., +, TMECH Oct. 2021 2538-2547

Elastomers

- An Integrated Design and Fabrication Strategy for Planar Soft Dielectric Elastomer Actuators. Chen, F., +, TMECH Oct. 2021 2629-2640
- Haptic Display Responsive to Touch Driven by Soft Actuator and Soft Sensor. Phung, H., +, TMECH Oct. 2021 2495-2505
- Identification of a Nonlinear Dielectric Elastomer Actuator Based on the Harmonic Balance Method. Bernat, J., +, TMECH Oct. 2021 2664-2675
- Modeling and Analysis of Soft Pneumatic Network Bending Actuators. Liu, Z., +, TMECH Aug. 2021 2195-2203

Topology Optimization for Design of a 3D-Printed Constant-Force Compliant Finger. Liu, C., +, TMECH Aug. 2021 1828-1836

Electric actuators

Mechanism and Controller Design of a Transfemoral Prosthesis With Electrohydraulic Knee and Motor-Driven Ankle. Gao, S., +, TMECH Oct. 2021 2429-2439

Electric conduits

Dynamic Modeling and State Estimation of Cable-Conduit Actuation During Interaction With Nonpassive Environments. Buchanan, S., +, TMECH Oct. 2021 2462-2471

Electric current control

- Efficiency Optimization Strategy for Switched Reluctance Generator System With Position Sensorless Control. Chen, H., +, TMECH Feb. 2021 469-479
- Optimal Current Allocation Rendering 3-D Magnetic Force Production in Hexapole Electromagnetic Actuation. Long, F., +, TMECH Oct. 2021 2408-2417

Electric impedance imaging

An Electrical Impedance Tomography Based Interface for Human-Robot Collaboration. Zheng, E., +, TMECH Oct. 2021 2373-2384

Electric machines

Adaptive Harmonic and Disturbance Estimators for Rotary Machines With Applications to Engines. Vadamalu, R.S., +, TMECH Feb. 2021 381-392 **Electric motors**

- Design Process and Verification of SPMSM for a Wearable Robot Considering Thermal Characteristics Through LPTN. Hwang, S., +, TMECH April 2021 1033-1042
- Thermal Modeling and Characterization of Twisted Coiled Actuators for Upper Limb Wearable Devices. Edmonds, B.P.R., +, TMECH April 2021 966-977

Electric potential

- A Computational-Effective Field-Oriented Control Strategy for Accurate and Efficient Electric Propulsion of Unmanned Aerial Vehicles. Bosso, A., +, TMECH June 2021 1501-1511
- A Novel Wireless 5-D Electromagnetic Tracking System Based on Nine-Channel Sinusoidal Signals. Yang, W., +, TMECH Feb. 2021 246-254 Study on a Double-Sided Permanent-Magnet Linear Synchronous Motor With Reversed Slots. Zhao, J., +, TMECH Feb. 2021 3-12

Electric propulsion

A Computational-Effective Field-Oriented Control Strategy for Accurate and Efficient Electric Propulsion of Unmanned Aerial Vehicles. Bosso, A., +, TMECH June 2021 1501-1511

Electric vehicles

- Design Method for Reducing AC Resistance of Traction Motor Using High Fill Factor Coil to Improve the Fuel Economy of eBus. Cha, K., +, TMECH June 2021 1260-1270
- Guest Editorial: Focused Section on Mechatronics in Road Mobility Systems. Ivanov, V., +, TMECH June 2021 1195-1200
- Individual Auxiliary and Fault-Tolerant Control of Steer-by-Wire System Considering Different Drivers Steering Characteristics. Zhao, W., +, TMECH June 2021 1558-1569
- Nonlinear Model Predictive Control for Integrated Energy-Efficient Torque-Vectoring and Anti-Roll Moment Distribution. Dalboni, M., +, TMECH June 2021 1212-1224
- Takagi-Sugeno Fuzzy-Based Robust Hoo Integrated Lane-Keeping and Direct Yaw Moment Controller of Unmanned Electric Vehicles. Guo, J., +, TMECH Aug. 2021 2151-2162

Electroactive polymer actuators

- An Integrated Design and Fabrication Strategy for Planar Soft Dielectric Elastomer Actuators. Chen, F., +, TMECH Oct. 2021 2629-2640
- Design and Characterization of a Bellows-Driven Soft Pneumatic Actuator. Hashem, R., +, TMECH Oct. 2021 2327-2338
- Development of a Small and Lightweight Missile Fin Control Actuation System Driven by Novel Dielectric Elastomer Actuators. Jung, H.S., +, TMECH April 2021 1002-1012
- Identification of a Nonlinear Dielectric Elastomer Actuator Based on the Harmonic Balance Method. Bernat, J., +, TMECH Oct. 2021 2664-2675
- Modeling of One-Ply and Two-Ply Twisted and Coiled Polymer Artificial Muscles. Karami, F., +, TMECH Feb. 2021 300-310

Electrochemical processes

A Hermaphrodite Electromechanical Connector for Self-Reconfigurable Robot Modules. Tian, X., +, TMECH Dec. 2021 3276-3281

Electrodes

- Feature Analyses and Modeling of Lithium-Ion Battery Manufacturing Based on Random Forest Classification. Liu, K., +, TMECH Dec. 2021 2944-2955
- On the Mechanical Power Output Comparisons of Cone Dielectric Elastomer Actuators. Cao, C., +, TMECH Dec. 2021 3151-3162

Robotic Prototyping of Paper-Based Field-Effect Transistors With Rolled-Up Semiconductor Microtubes. Dong, X., +, TMECH Feb. 2021 427-436

Electroencephalography

Brain-Machine Interface Using Functional Electrical Stimulation and Motion-Related Cortical Potentials Identified by a Support Vector Machine. Miura, S., +, TMECH April 2021 1013-1021

Electrohydraulic control equipment

- Novel Structure for Waveform Control of Twin Rotary Flowrate Valve Controlled Vibration Exciter. *Wang, T.*, +, *TMECH April 2021 1183-1188*
- Quasi-Synchronization Control of Multiple Electrohydraulic Actuators With Load Disturbance and Uncertain Parameters. *Guo, Q.*, +, *TMECH Aug.* 2021 2048-2058

Electrohydraulics

An Adaptive Fuzzy Trajectory Tracking Control via Improved Cerebellar Model Articulation Controller for Electro-Hydraulic Shovel. *Fan, R.*, +, *TMECH Dec. 2021 2870-2880*

Electromagnetic actuators

- Flux-Biased, Energy-Efficient Electromagnetic Micropumps Utilizing Bistable Magnetic Latching and Energy-Storage Springs. *Bhushan*, B.M., +, TMECH Oct. 2021 2362-2372
- Magnetically Levitated Linear Drive Using an Active Gravity Compensation Based on Hybrid Shape Memory Actuators. *Raab, M.*, +, *TMECH June* 2021 1380-1391
- Modeling and Experimental Validation of a Planar Microconveyor Based on a 2 × 2 Array of Digital Electromagnetic Actuators. *Tisnes, S.D.*, +, *TMECH June 2021 1422-1432*
- Optimal Current Allocation Rendering 3-D Magnetic Force Production in Hexapole Electromagnetic Actuation. *Long, F., +, TMECH Oct. 2021* 2408-2417
- Optimal Design and Implementation of a Novel Two-Dimensional Electromagnetic Navigation System That Allows Focused Heating of Magnetic Nanoparticles. *Le, T.,* +, *TMECH Feb. 2021 551-562*
- Thermal Modeling and Characterization of Twisted Coiled Actuators for Upper Limb Wearable Devices. *Edmonds, B.P.R.*, +, *TMECH April 2021* 966-977

Electromagnetic coupling

Similitude Analysis Method of the Dynamics of a Hybrid Spray-Painting Robot Considering Electromechanical Coupling Effect. *Song, Y.*, +, *TMECH Dec. 2021 2986-2997*

Electromagnetic devices

A Novel Wireless 5-D Electromagnetic Tracking System Based on Nine-Channel Sinusoidal Signals. *Yang, W., +, TMECH Feb. 2021 246-254* Optimal Design and Implementation of a Novel Two-Dimensional Electromagnetic Navigation System That Allows Focused Heating of Magnetic Nanoparticles. *Le, T., +, TMECH Feb. 2021 551-562*

Electromagnetic fields

A Novel Wireless 5-D Electromagnetic Tracking System Based on Nine-Channel Sinusoidal Signals. *Yang, W.*, +, *TMECH Feb. 2021 246-254*

Electromagnetic induction

Static Pull-In Behavior of Hybrid Levitation Microactuators: Simulation, Modeling, and Experimental Study. Poletkin, K.V., TMECH April 2021 753-764

Electromagnetic waves

Global Optimization of the Hydraulic-Electromagnetic Energy-Harvesting Shock Absorber for Road Vehicles With Human-Knowledge-Integrated Particle Swarm Optimization Scheme. *Zhou, Q., +, TMECH June 2021* 1225-1235

Electromagnets

Optimal Current Allocation Rendering 3-D Magnetic Force Production in Hexapole Electromagnetic Actuation. *Long, F.*, +, *TMECH Oct. 2021* 2408-2417

Electromechanical systems

Sensorless Unbalance Diagnosis of Affiliated Rotating Chamber Based on Driving Current of Permanent Magnet Synchronous Motor. *Huo, X.*, +, *TMECH Dec. 2021 2899-2909*

Electromyography

Markovian Robust Filtering and Control Applied to Rehabilitation Robotics. Escalante, F.M., +, TMECH Feb. 2021 491-502

Wearable Knee Assistive Devices for Kneeling Tasks in Construction. *Chen, S.*, +, *TMECH Aug. 2021 1989-1996*

Electrostatics

Estimation of the Electrostatic Effects in the LISA-Pathfinder Critical Test Mass Dynamics via the Method of Moments. *Zanoni, C.*, +, *TMECH Dec.* 2021 3022-3030

Elemental semiconductors

Testing of a Strained Silicon Based 3-D Stress Sensor for Out-of-Plane Stress Measurements. *Balbola, A.A.*, +, *TMECH April 2021 1076-1083* Elongation

Tendon-Inspired Piezoelectric Sensor for Biometric Application. Kim, H., +, TMECH Oct. 2021 2538-2547

Embedded systems

Cyber–Physical Codesign of Field-Level Reconfigurations in Networked Motion Controllers. *Zhou*, *N*., +, *TMECH Aug. 2021 2092-2103* Encoding

A New Position Detection and Status Monitoring System for Joint of

SCARA. Lu, W., +, TMECH June 2021 1613-1623

- End effectors
 - A Hybrid Active and Passive Cable-Driven Segmented Redundant Manipulator: Design, Kinematics, and Planning. *Liu*, *T.*, +, *TMECH April 2021* 930-942
 - A Mechanism-Image Fusion Approach to Calibration of an Ultrasound-Guided Dual-Arm Robotic Brachytherapy System. *Xiong, J.*, +, *TMECH Dec. 2021 3211-3220*
 - Coordinated Dynamic Control in the Task Space for Redundantly Actuated Cable-Driven Parallel Robots. Zhang, B., +, TMECH Oct. 2021 2396-2407
 - Dynamic Path Correction of an Industrial Robot Using a Distance Sensor and an ADRC Controller. *Khaled, T.A.*, +, *TMECH June 2021 1646-1656*
 - Hybrid Control Strategy for Force and Precise End Effector Positioning of a Twisted String Actuator. Rodriguez, A.S., +, TMECH Oct. 2021 2791-2802
 - Modified Configuration Control With Potential Field for Inverse Kinematic Solution of Redundant Manipulator. *Kim, J.*, +, *TMECH Aug. 2021 1782-1790*
 - Nonprehensile Manipulation: A Trajectory-Planning Perspective. Acharya, P., +, TMECH Feb. 2021 527-538
 - Slider-Tendon Linear Actuator With Under-Actuation and Fast-Connection for Soft Wearable Robots. *Kim, B., +, TMECH Dec. 2021 2932-2943*
 - Topology Optimization for Design of a 3D-Printed Constant-Force Compliant Finger. *Liu*, *C*., +, *TMECH Aug. 2021 1828-1836*

Endoscopes

- Blindly Controlled Magnetically Actuated Capsule for Noninvasive Sampling of the Gastrointestinal Microbiome. *Shokrollahi, P.*, +, *TMECH Oct.* 2021 2616-2628
- Image Processing Metrics for Phase Identification of a Multiaxis MEMS Scanner Used in Single Pixel Imaging. *Birla, M.*, +, *TMECH June 2021* 1445-1454
- Measurement of Peristaltic Forces Exerted by Living Intestine on Robotic Capsule. *Rehan, M.*, +, *TMECH Aug. 2021 1803-1811*

Energy conservation

Global Optimization of the Hydraulic-Electromagnetic Energy-Harvesting Shock Absorber for Road Vehicles With Human-Knowledge-Integrated Particle Swarm Optimization Scheme. *Zhou, Q., +, TMECH June 2021 1225-1235*

Energy consumption

Integrated Predictive Powertrain Control for a Multimode Plug-in Hybrid Electric Vehicle. *Oncken, J.*, +, *TMECH June 2021 1248-1259*

Energy efficiency

Plate-Springed Parallel Elastic Actuator for Efficient Snake Robot Movement. Kakogawa, A., +, TMECH Dec. 2021 3051-3063

Energy harvesting

- Characterization of a Packaged Triboelectric Harvester Under Simulated Gait Loading for Total Knee Replacement. *Hossain, N.A.*, +, *TMECH Dec.* 2021 2967-2976
- Characterization of a Packaged Triboelectric Harvester Under Simulated Gait Loading for Total Knee Replacement. *Hossain, N.A.*, +, *TMECH Dec.* 2021 2967-2976
- Design, Modeling, and Experiments of Electromagnetic Energy Harvester Embedded in Smart Watch and Wristband as Power Source. *Cai*, *M.*, +, *TMECH Aug. 2021 2104-2114*
- Global Optimization of the Hydraulic-Electromagnetic Energy-Harvesting Shock Absorber for Road Vehicles With Human-Knowledge-Integrated Particle Swarm Optimization Scheme. *Zhou, Q.*, +, *TMECH June 2021* 1225-1235

Structural Failure Detection Using Wireless Transmission Rate From Piezoelectric Energy Harvesters. Jung, H.J., +, TMECH Aug. 2021 1708-1718

- Engines Constrained Surrogate-Based Engine Calibration Using Lower Confidence Bound. Pal, A., +, TMECH Dec. 2021 3116-3127
 - Integrated Predictive Powertrain Control for a Multimode Plug-in Hybrid Electric Vehicle. Oncken, J., +, TMECH June 2021 1248-1259

Entropy

Weighted Entropy Minimization Based Deep Conditional Adversarial Diagnosis Approach Under Variable Working Conditions. She, D., +, TMECH Oct. 2021 2440-2450

Ergonomics

- Human-in-the-Loop Control of a Wearable Lower Limb Exoskeleton for Stable Dynamic Walking. *Li*, *Z*., +, *TMECH Oct. 2021 2700-2711*
- Semiactively Controllable Vehicle Seat Suspension System With Negative Stiffness Magnetic Spring. *Tu, L., +, TMECH Feb. 2021 156-167*
- Wearable Knee Assistive Devices for Kneeling Tasks in Construction. *Chen, S.*, +, *TMECH Aug. 2021 1989-1996*

Error analysis

- Four-Point Method in the Measurement and Separation of Spindle Rotation Error. *Liu*, *F*., +, *TMECH Feb. 2021 113-123*
- Pose Error Estimation Using a Cylinder in Scanner-Based Robotic Belt Grinding. Xie, H., +, TMECH Feb. 2021 515-526

Error compensation

- A Laser-Guided Solution to Manipulate Mobile Robot Arm Terminals Within a Large Workspace. *Li*, *F*, +, *TMECH Oct. 2021 2676-2687*
- A Novel Rotational Actuator With Variable Stiffness Using S-Shaped Springs. Xu, Y, +, TMECH Aug. 2021 2249-2260
- Efficiency Optimization Strategy for Switched Reluctance Generator System With Position Sensorless Control. *Chen, H., +, TMECH Feb. 2021* 469-479
- Pose Error Estimation Using a Cylinder in Scanner-Based Robotic Belt Grinding. Xie, H., +, TMECH Feb. 2021 515-526
- Proportional-Integral Approximation-Free Control of Robotic Systems With Unknown Dynamics. Zhang, C., +, TMECH Aug. 2021 2226-2236

Estimation

- Artificial-Delay Adaptive Control for Underactuated Euler–Lagrange Robotics. Roy, S., +, TMECH Dec. 2021 3064-3075
- Estimation of the Electrostatic Effects in the LISA-Pathfinder Critical Test Mass Dynamics via the Method of Moments. *Zanoni, C.*, +, *TMECH Dec.* 2021 3022-3030
- Prediction-Model-Based Contouring Error Iterative Precompensation Scheme for Precision Multiaxis Motion Systems. *Wang, Z.*, +, *TMECH Oct.* 2021 2274-2284
- Reconstructing Walking Dynamics From Two Shank-Mounted Inertial Measurement Units. Li, T., +, TMECH Dec. 2021 3040-3050

Estimation theory

A Generalized Design Method for Learning-Based Disturbance Observer. Zheng, M., +, TMECH Feb. 2021 45-54

Excavators

Sensor-Fault-Tolerant Operation for the Independent Metering Control System. Ding, R., +, TMECH Oct. 2021 2558-2569

Expectation-maximization algorithms

Collaborative Semantic Understanding and Mapping Framework for Autonomous Systems. Yue, Y, +, TMECH April 2021 978-989

Eye

- Automated Retinal Vein Cannulation on Silicone Phantoms Using Optical-Coherence-Tomography-Guided Robotic Manipulations. *Gerber, M.J.*, +, *TMECH Oct. 2021 2758-2769*
- Stochastic Force-Based Insertion Depth and Tip Position Estimations of Flexible FBG-Equipped Instruments in Robotic Retinal Surgery. *Ebrahimi, A.*, +, *TMECH June 2021 1512-1523*

F

- Factory automation
 - Modeling and Experimental Validation of a Planar Microconveyor Based on a 2 × 2 Array of Digital Electromagnetic Actuators. *Tisnes, S.D.*, +, *TMECH June 2021 1422-1432*

Failure analysis

Failure Monitoring and Predictive Maintenance of Hydraulic Cylinder— State-of-the-Art Review. *Shanbhag, V.V.*, +, *TMECH Dec. 2021 3087-3103* Fasteners

rasteners

A Microgripper With a Large Magnification Ratio and High Structural Stiffness Based on a Flexure-Enabled Mechanism. *Shi*, C., +, *TMECH Dec.* 2021 3076-3086

Automated In Situ Placing of Metal Components Into 3-D Printed FFF Objects. Ahlers, D., +, TMECH Aug. 2021 1886-1894

Fault diagnosis

- A Method for Mass Flow and Displacement Estimation in a Pneumatic Actuation System Using Valve-Based Pressure Sensing. *Vailati, L.G.*, +, *TMECH Feb. 2021 235-245*
- A Two-Stage Transfer Adversarial Network for Intelligent Fault Diagnosis of Rotating Machinery With Multiple New Faults. *Li*, *J.*, +, *TMECH June 2021 1591-1601*
- An Investigation Into Fault Diagnosis of Planetary Gearboxes Using A Bispectrum Convolutional Neural Network. *Pang, X.*, +, *TMECH Aug.* 2021 2027-2037
- Design and Experimental Validation of Robust Self-Scheduled Fault-Tolerant Control Laws for a Multicopter UAV. Nguyen, D., +, TMECH Oct. 2021 2548-2557
- Individual Auxiliary and Fault-Tolerant Control of Steer-by-Wire System Considering Different Drivers Steering Characteristics. *Zhao, W.*, +, *TMECH June 2021 1558-1569*
- Intelligent Fault Diagnosis of a Reciprocating Compressor Using Mode Isolation Convolutional Deep Belief Networks. *Zhang, Y.*, +, *TMECH June* 2021 1668-1677
- Modeling and Adaptive Fault Compensation for Two Physically Linked 2WD Mobile Robots. *Ma*, *Y*, +, *TMECH April 2021 1161-1171*
- Sensor-Fault-Tolerant Operation for the Independent Metering Control System. Ding, R., +, TMECH Oct. 2021 2558-2569
- Static Position Sensor Bias Fault Diagnosis in Permanent Magnet Synchronous Machines via Current Estimation. Kuruppu, S.S., +, TMECH April 2021 888-896
- Takagi–Sugeno Fuzzy Unknown Input Observers to Estimate Nonlinear Dynamics of Autonomous Ground Vehicles: Theory and Real-Time Verification. *Nguyen, A.*, +, *TMECH June 2021 1328-1338*
- Unsupervised Cross-Domain Fault Diagnosis Using Feature Representation Alignment Networks for Rotating Machinery. *Chen, J.*, +, *TMECH Oct.* 2021 2770-2781
- Weighted Entropy Minimization Based Deep Conditional Adversarial Diagnosis Approach Under Variable Working Conditions. She, D., +, TMECH Oct. 2021 2440-2450

Fault tolerance

- Design and Experimental Validation of Robust Self-Scheduled Fault-Tolerant Control Laws for a Multicopter UAV. Nguyen, D., +, TMECH Oct. 2021 2548-2557
- Individual Auxiliary and Fault-Tolerant Control of Steer-by-Wire System Considering Different Drivers Steering Characteristics. *Zhao, W.*, +, *TMECH June 2021 1558-1569*
- Modeling and Adaptive Fault Compensation for Two Physically Linked 2WD Mobile Robots. *Ma*, *Y*, +, *TMECH April 2021 1161-1171*

Fault tolerant control

- A Method for Mass Flow and Displacement Estimation in a Pneumatic Actuation System Using Valve-Based Pressure Sensing. Vailati, L.G., +, TMECH Feb. 2021 235-245
- Design and Experimental Validation of Robust Self-Scheduled Fault-Tolerant Control Laws for a Multicopter UAV. *Nguyen, D.*, +, *TMECH Oct.* 2021 2548-2557

Sensor-Fault-Tolerant Operation for the Independent Metering Control System. *Ding*, *R.*, +, *TMECH Oct. 2021 2558-2569*

Feature extraction

A Delaunay Triangulation-Based Matching Area Selection Algorithm for Underwater Gravity-Aided Inertial Navigation. Wang, C., +, TMECH April 2021 908-917

- An Integrated Terrain Identification Framework for Mobile Robots: System Development, Analysis, and Verification. *Zeng, R.*, +, *TMECH June 2021* 1581-1590
- Edge-Dependent Efficient Grasp Rectangle Search in Robotic Grasp Detection. Chen, L., +, TMECH Dec. 2021 2922-2931
- General Discharge Voltage Information Enabled Health Evaluation for Lithium-Ion Batteries. Deng, Z., +, TMECH June 2021 1295-1306
- Generative Adversarial Network for Prediction of Workpiece Surface Topography in Machining Stage. Cao, L., +, TMECH Feb. 2021 480-490
- Geometrical-Based Displacement Measurement With Pseudostereo Monocular Camera on Bidirectional Cascaded Linear Actuator. *Lee, D.*, +, *TMECH Aug. 2021 1923-1931*
- Intelligent Fault Diagnosis of a Reciprocating Compressor Using Mode Isolation Convolutional Deep Belief Networks. *Zhang, Y.*, +, *TMECH June* 2021 1668-1677
- OrthographicNet: A Deep Transfer Learning Approach for 3-D Object Recognition in Open-Ended Domains. *Kasaei, S.H., TMECH Dec. 2021 2910-2921*
- Segmentation-Oriented Compressed Sensing for Efficient Impact Damage Detection on CFRP Materials. *Tang, C.*, +, *TMECH Oct. 2021 2528-2537*
- Unsupervised Cross-Domain Fault Diagnosis Using Feature Representation Alignment Networks for Rotating Machinery. *Chen, J.*, +, *TMECH Oct.* 2021 2770-2781
- Vision-Based Cutting Control of Deformable Objects With Surface Tracking. Han, L., +, TMECH Aug. 2021 2016-2026
- Weighted Entropy Minimization Based Deep Conditional Adversarial Diagnosis Approach Under Variable Working Conditions. She, D., +, TMECH Oct. 2021 2440-2450

Feedback

- A Visual Servo-Based Predictive Control With Echo State Gaussian Process for Soft Bending Actuator. *Cao*, Y., +, *TMECH Feb. 2021* 574-585
- Adaptive Output Feedback Control of Steer-by-Wire Systems With Event-Triggered Communication. *Ma*, *B*., +, *TMECH Aug. 2021 1968-1979*
- An Output Feedback Based Robust Saturated Controller Design for Pavement Sweeping Self-Reconfigurable Robot. *Rayguru, M.M.*, +, *TMECH June 2021 1236-1247*
- Analytical Harmonic Method for Modeling High-Frequency Oscillation With Applications to Aircraft Piston Pump Vibration Analysis. *Li*, *L.*, +, *TMECH April 2021 918-929*
- Asymptotic Tracking Control of Mechanical Servosystems With Mismatched Uncertainties. *Deng, W.*, +, *TMECH Aug. 2021 2204-2214*
- Closed-Loop Range-Based Control of Dual-Stage Nanopositioning Systems. *Mitrovic, A., +, TMECH June 2021 1412-1421*
- Coordinated Dynamic Control in the Task Space for Redundantly Actuated Cable-Driven Parallel Robots. Zhang, B., +, TMECH Oct. 2021 2396-2407
- Design and Control of Soft Unmanned Aerial Vehicle "S-CLOUD". Song, S.H., +, TMECH Feb. 2021 267-275
- Development of Embedded Sensor System for 5-DOF Finger-Wearable Tactile Interface. *Lim, B., +, TMECH Aug. 2021 1728-1736*
- Dynamic Control of Multisection Three-Dimensional Continuum Manipulators Based on Virtual Discrete-Jointed Robot Models. *Wang, C.*, +, *TMECH April 2021 777-788*
- Experimental Investigation on Control of an Infinitely Variable Transmission System for Tidal Current Energy Converters. Li, G., +, TMECH Aug. 2021 1960-1967
- Fractional-Order Control for Uncertain Teleoperated Cyber-Physical System With Actuator Fault. *Ma*, *Z*., +, *TMECH Oct.* 2021 2472-2482
- Iterative Learning Control for Video-Rate Atomic Force Microscopy. Nikooienejad, N., +, TMECH Aug. 2021 2127-2138
- Markovian Robust Filtering and Control Applied to Rehabilitation Robotics. Escalante, F.M., +, TMECH Feb. 2021 491-502
- Model-Free Control of Flexible Manipulator Based on Intrinsic Design. Jiang, N., +, TMECH Oct. 2021 2641-2652
- Nonlinear Model Predictive Control for Integrated Energy-Efficient Torque-Vectoring and Anti-Roll Moment Distribution. *Dalboni, M.*, +, *TMECH June 2021 1212-1224*

- Online Compensation of Mechanical Load Defects With Composite Control in PMSM Drives. *Kommuri, S.K.*, +, *TMECH June 2021 1392-1400*
- Optimal Current Allocation Rendering 3-D Magnetic Force Production in Hexapole Electromagnetic Actuation. *Long, F., +, TMECH Oct. 2021* 2408-2417
- Practical Terminal Sliding Mode Control of Nonlinear Uncertain Active Suspension Systems With Adaptive Disturbance Observer. *Wang, G.*, +, *TMECH April 2021 789-797*
- Rotor Position Tracking Control for Low Speed Operation of Direct-Drive PMSM Servo System. Bu, F., +, TMECH April 2021 1129-1139
- Sliding-Mode-Disturbance-Observer-Based Robust Tracking Control for Omnidirectional Mobile Robots With Kinematic and Dynamic Uncertainties. Jeong, S., +, TMECH April 2021 741-752
- Takagi–Sugeno Fuzzy-Based Robust *H*∞ Integrated Lane-Keeping and Direct Yaw Moment Controller of Unmanned Electric Vehicles. *Guo*, *J*., +, *TMECH Aug. 2021 2151-2162*
- Topology Optimization for Design of a 3D-Printed Constant-Force Compliant Finger. Liu, C., +, TMECH Aug. 2021 1828-1836
- Virtual Landmark-Based Control of Docking Support for Assistive Mobility Devices. Chen, Y., +, TMECH Aug. 2021 2007-2015

Vision-Based Cutting Control of Deformable Objects With Surface Tracking. Han, L., +, TMECH Aug. 2021 2016-2026

Feedforward

Iterative Learning Control for Video-Rate Atomic Force Microscopy. Nikooienejad, N., +, TMECH Aug. 2021 2127-2138

- Online Compensation of Mechanical Load Defects With Composite Control in PMSM Drives. *Kommuri, S.K.*, +, *TMECH June 2021 1392-1400*
- Position-Tracking Control of Dual-Rope Winch Robot With Rope Slip Compensation. Yoo, S., +, TMECH Aug. 2021 1754-1762
- Feedforward neural networks

Generative Adversarial Network for Prediction of Workpiece Surface Topography in Machining Stage. Cao, L., +, TMECH Feb. 2021 480-490

Feedforward systems

- Development of FW and MTPV Control for SynRM via Feedforward Voltage Angle Control. Chen, S., +, TMECH Dec. 2021 3254-3264
- Kinematic Modeling and Control of Variable Curvature Soft Continuum Robots. *Huang, X.*, +, *TMECH Dec. 2021 3175-3185*

Feeds

Data-Driven Iterative Trajectory Shaping for Precision Control of Flexible Feed Drives. *Dumanli*, A., +, *TMECH Oct. 2021 2735-2746*

Fiber optic sensors

A Surgical Robotic System for Treatment of Pelvic Osteolysis Using an FBG-Equipped Continuum Manipulator and Flexible Instruments. *Sefati, S.*, +, *TMECH Feb. 2021 369-380*

Field effect transistors

Robotic Prototyping of Paper-Based Field-Effect Transistors With Rolled-Up Semiconductor Microtubes. *Dong, X., +, TMECH Feb. 2021 427-436*

Field programmable gate arrays

- A Lightweight Wireless Overpressure Node Based Efficient Monitoring for Shock Waves. *Gao*, S., +, *TMECH Feb*. 2021 448-457
- Optimal Current Allocation Rendering 3-D Magnetic Force Production in Hexapole Electromagnetic Actuation. *Long, F.*, +, *TMECH Oct. 2021* 2408-2417

UltraLow Noise, High Bandwidth, Low Latency, No Overload 6-Axis Optical Force Sensor. *Hosseinabadi, A.H.H.*, +, *TMECH Oct. 2021 2581-2592*

Finite element analysis

- A Microgripper With a Large Magnification Ratio and High Structural Stiffness Based on a Flexure-Enabled Mechanism. *Shi*, *C.*, +, *TMECH Dec.* 2021 3076-3086
- A Monolithic Force Sensing Integrated Flexure Bonder Dedicated to Flip-Chip Active Soft-Landing Interconnection. *Tang, H., +, TMECH Feb.* 2021 323-334
- A Piezoelectric Microultrasonic Motor With High *Q* and Good Mode Match. *Zhou, W.*, +, *TMECH Aug. 2021 1773-1781*
- A Two-Finger Soft-Robotic Gripper With Enveloping and Pinching Grasping Modes. *Liu*, *S.*, +, *TMECH Feb. 2021 146-155*
- An Integrated Design and Fabrication Strategy for Planar Soft Dielectric Elastomer Actuators. Chen, F., +, TMECH Oct. 2021 2629-2640

- Curvature-Induced Buckling for Flapping-Wing Vehicles. Sharifzadeh, M., +, TMECH Feb. 2021 503-514
- Design Process and Verification of SPMSM for a Wearable Robot Considering Thermal Characteristics Through LPTN. Hwang, S., +, TMECH April 2021 1033-1042
- Design, Modeling, and Control of a 3D Printed Monolithic Soft Robotic Finger With Embedded Pneumatic Sensing Chambers. Tawk, C., +, TMECH April 2021 876-887
- Design, Modeling, and Experiments of Electromagnetic Energy Harvester Embedded in Smart Watch and Wristband as Power Source. *Cai, M.*, +, *TMECH Aug. 2021 2104-2114*
- Estimation of the Electrostatic Effects in the LISA-Pathfinder Critical Test Mass Dynamics via the Method of Moments. *Zanoni, C.*, +, *TMECH Dec.* 2021 3022-3030
- Magnetically Levitated Linear Stage With Linear Bearingless Slice Hysteresis Motors. Zhou, L., +, TMECH April 2021 1084-1094
- Measurement of Peristaltic Forces Exerted by Living Intestine on Robotic Capsule. Rehan, M., +, TMECH Aug. 2021 1803-1811
- Modeling and Analysis of Soft Pneumatic Network Bending Actuators. *Liu*, *Z*, +, *TMECH Aug. 2021 2195-2203*
- Static Pull-In Behavior of Hybrid Levitation Microactuators: Simulation, Modeling, and Experimental Study. Poletkin, K.V., TMECH April 2021 753-764
- Study on a Double-Sided Permanent-Magnet Linear Synchronous Motor With Reversed Slots. Zhao, J., +, TMECH Feb. 2021 3-12
- Testing of a Strained Silicon Based 3-D Stress Sensor for Out-of-Plane Stress Measurements. *Balbola, A.A.*, +, *TMECH April 2021 1076-1083*
- Topology Optimization of Skeleton-Reinforced Soft Pneumatic Actuators for Desired Motions. *Chen, S.*, +, *TMECH Aug. 2021 1745-1753*

Flash memories

- A Lightweight Wireless Overpressure Node Based Efficient Monitoring for Shock Waves. *Gao*, S., +, *TMECH Feb*. 2021 448-457
- Flaw detection
 - A DC-Biased Scanning Induction Thermographic System for Characterizing Surface Cracks in Ferromagnetic Components. *Wu, J.*, +, *TMECH Oct.* 2021 2782-2790
 - Segmentation-Oriented Compressed Sensing for Efficient Impact Damage Detection on CFRP Materials. *Tang, C., +, TMECH Oct. 2021 2528-2537*

Flexible electronics

Robotic Prototyping of Paper-Based Field-Effect Transistors With Rolled-Up Semiconductor Microtubes. *Dong, X., +, TMECH Feb. 2021 427-436*

Flexible manipulators

- Dynamic Control of Multisection Three-Dimensional Continuum Manipulators Based on Virtual Discrete-Jointed Robot Models. *Wang, C.*, +, *TMECH April 2021* 777-788
- Model-Free Control of Flexible Manipulator Based on Intrinsic Design. Jiang, N., +, TMECH Oct. 2021 2641-2652
- Optimization of Generalized S-Curve Trajectories for Residual Vibration Suppression and Compliance With Kinematic Bounds. *Biagiotti, L.*, +, *TMECH Oct. 2021 2724-2734*

Whole-Body Control of an Autonomous Mobile Manipulator Using Series Elastic Actuators. *Liu*, *Y*, +, *TMECH April 2021 657-667*

Flip-chip devices

A Monolithic Force Sensing Integrated Flexure Bonder Dedicated to Flip-Chip Active Soft-Landing Interconnection. *Tang, H.*, +, *TMECH Feb.* 2021 323-334

Flow control

Design and Control of Soft Unmanned Aerial Vehicle "S-CLOUD". Song, S.H., +, TMECH Feb. 2021 267-275

Fluid flow

Longitudinal Motion Modeling and Experimental Verification of a Microrobot Subject to Liquid Laminar Flow. *Demircali, A.A.*, +, *TMECH Dec.* 2021 2956-2966

Fluids

Failure Monitoring and Predictive Maintenance of Hydraulic Cylinder-State-of-the-Art Review. Shanbhag, V.V., +, TMECH Dec. 2021 3087-3103

Fluorescence

Image Processing Metrics for Phase Identification of a Multiaxis MEMS Scanner Used in Single Pixel Imaging. *Birla, M.*, +, *TMECH June 2021* 1445-1454

Force

- A Microgripper With a Large Magnification Ratio and High Structural Stiffness Based on a Flexure-Enabled Mechanism. *Shi*, *C.*, +, *TMECH Dec.* 2021 3076-3086
- Intelligent Vibration Control for Semiactive Suspension Systems Without Prior Knowledge of Dynamical Nonlinear Damper Behaviors Based on Improved Extreme Learning Machine. *Huang, W.*, +, *TMECH Aug. 2021* 2071-2079
- Investigation on a New Approach for Designing Articulated Soft Robots With Discrete Variable Stiffness. *Zhong, Y.*, +, *TMECH Dec. 2021 2998-3009*
- Longitudinal Motion Modeling and Experimental Verification of a Microrobot Subject to Liquid Laminar Flow. *Demircali, A.A.*, +, *TMECH Dec.* 2021 2956-2966
- Modified Stiffness-Based Soft Optical Waveguide Integrated Pneumatic Artificial Muscle (PAM) Actuators for Contraction and Force Sensing. *Jamil, B.*, +, *TMECH Dec. 2021 3243-3253*
- Optimized Interaction Control for Robot Manipulator Interacting With Flexible Environment. *Liu*, X., +, *TMECH Dec.* 2021 2888-2898
- Plate-Springed Parallel Elastic Actuator for Efficient Snake Robot Movement. Kakogawa, A., +, TMECH Dec. 2021 3051-3063
- Simultaneous State Estimation and Tire Model Learning for Autonomous Vehicle Applications. *Jeon, W.*, +, *TMECH Aug. 2021 1941-1950*

Force control

- A Monolithic Force Sensing Integrated Flexure Bonder Dedicated to Flip-Chip Active Soft-Landing Interconnection. *Tang, H., +, TMECH Feb.* 2021 323-334
- An Electrical Impedance Tomography Based Interface for Human–Robot Collaboration. Zheng, E., +, TMECH Oct. 2021 2373-2384
- Design, Modeling, and Control of a 3D Printed Monolithic Soft Robotic Finger With Embedded Pneumatic Sensing Chambers. *Tawk, C.*, +, *TMECH April 2021 876-887*
- Dynamic Modeling and State Estimation of Cable-Conduit Actuation During Interaction With Nonpassive Environments. *Buchanan, S.*, +, *TMECH Oct.* 2021 2462-2471
- Human-in-the-Loop Control of a Wearable Lower Limb Exoskeleton for Stable Dynamic Walking. Li, Z., +, TMECH Oct. 2021 2700-2711
- Optimized Power Modulation in Wave-Based Bilateral Teleoperation. *Ferraguti*, *F*, +, *TMECH Feb. 2021 276-287*
- Proportional-Integral Approximation-Free Control of Robotic Systems With Unknown Dynamics. *Zhang, C., +, TMECH Aug. 2021 2226-2236*
- Soft Robotic Palm With Tunable Stiffness Using Dual-Layered Particle Jamming Mechanism. Lee, J., +, TMECH Aug. 2021 1820-1827
- Topology Optimization for Design of a 3D-Printed Constant-Force Compliant Finger. *Liu, C., +, TMECH Aug. 2021 1828-1836*
- Unified Motion/Force/Impedance Control for Manipulators in Unknown Contact Environments Based on Robust Model-Reaching Approach. *Lin*, *Y*, +, *TMECH Aug. 2021 1905-1913*

Force measurement

- A High Range-to-Resolution Multiaxis μForce and Torque Sensing Platform. *Tiwari*, B., +, *TMECH Aug. 2021 1837-1845*
- A Suction-Based Peripheral Nerve Gripper Capable of Controlling the Suction Force. Jang, N., +, TMECH Aug. 2021 1867-1876
- Characterization of a Packaged Triboelectric Harvester Under Simulated Gait Loading for Total Knee Replacement. *Hossain, N.A.*, +, *TMECH Dec.* 2021 2967-2976
- Design and Testing of a New Force-Sensing Cell Microinjector Based on Small-Stiffness Compliant Mechanism. *Wei, Y., +, TMECH April 2021 818-829*
- Modeling and Motion Control of Industrial Tractor–Trailers Vehicles Using Force Compensation. Zhao, H., +, TMECH April 2021 645-656

- Stochastic Force-Based Insertion Depth and Tip Position Estimations of Flexible FBG-Equipped Instruments in Robotic Retinal Surgery. *Ebrahimi, A.*, +, *TMECH June 2021 1512-1523*
- UltraLow Noise, High Bandwidth, Low Latency, No Overload 6-Axis Optical Force Sensor. Hosseinabadi, A.H.H., +, TMECH Oct. 2021 2581-2592

Force sensors

- A High Range-to-Resolution Multiaxis μForce and Torque Sensing Platform. *Tiwari*, B., +, *TMECH Aug.* 2021 1837-1845
- A Monolithic Force Sensing Integrated Flexure Bonder Dedicated to Flip-Chip Active Soft-Landing Interconnection. *Tang, H.*, +, *TMECH Feb.* 2021 323-334
- A Suction-Based Peripheral Nerve Gripper Capable of Controlling the Suction Force. Jang, N., +, TMECH Aug. 2021 1867-1876
- Design and Testing of a New Force-Sensing Cell Microinjector Based on Small-Stiffness Compliant Mechanism. *Wei, Y.*, +, *TMECH April 2021* 818-829
- Development of Embedded Sensor System for 5-DOF Finger-Wearable Tactile Interface. *Lim, B., +, TMECH Aug. 2021 1728-1736*
- MEMS-Enabled Retrofitting of Automobile Wheel Balancer for Automatic Unbalance Detection. *Pozzato, G.,* +, *TMECH April 2021 830-840*
- Modeling and Motion Control of Industrial Tractor–Trailers Vehicles Using Force Compensation. Zhao, H., +, TMECH April 2021 645-656
- The MUSHA Hand II:A Multifunctional Hand for Robot-Assisted Laparoscopic Surgery. Liu, H., +, TMECH Feb. 2021 393-404
- UltraLow Noise, High Bandwidth, Low Latency, No Overload 6-Axis Optical Force Sensor. Hosseinabadi, A.H.H., +, TMECH Oct. 2021 2581-2592

Fourier analysis

A High Range-to-Resolution Multiaxis µForce and Torque Sensing Platform. *Tiwari*, B., +, *TMECH Aug. 2021 1837-1845*

Fourier series

A Lie-Theory-Based Dynamic Parameter Identification Methodology for Serial Manipulators. Fu, Z., +, TMECH Oct. 2021 2688-2699

Frequency response

- Development of a Small and Lightweight Missile Fin Control Actuation System Driven by Novel Dielectric Elastomer Actuators. Jung, H.S., +, TMECH April 2021 1002-1012
- Identification of a Nonlinear Dielectric Elastomer Actuator Based on the Harmonic Balance Method. *Bernat, J.*, +, *TMECH Oct. 2021 2664-2675*

Frequency-domain analysis

Phase-Relaxed-Passive Full State Feedback Gain Limits for Series Elastic Actuators. *Thomas, G.C.,* +, *TMECH Feb. 2021 586-591*

Friction

- A Lie-Theory-Based Dynamic Parameter Identification Methodology for Serial Manipulators. Fu, Z., +, TMECH Oct. 2021 2688-2699
- A Piezoelectric Microultrasonic Motor With High Q and Good Mode Match. Zhou, W., +, TMECH Aug. 2021 1773-1781
- Data-Driven Iterative Trajectory Shaping for Precision Control of Flexible Feed Drives. *Dumanli, A.*, +, *TMECH Oct. 2021 2735-2746*
- Edge-Dependent Efficient Grasp Rectangle Search in Robotic Grasp Detection. Chen, L., +, TMECH Dec. 2021 2922-2931
- Localized Property Design and Gradient Processing of a Hydraulic Valve Body Using Selective Laser Melting. *Zhu, Y.*, +, *TMECH April 2021 1151-1160*
- Nonlinear Model Predictive Control for Integrated Energy-Efficient Torque-Vectoring and Anti-Roll Moment Distribution. *Dalboni, M.*, +, *TMECH June 2021 1212-1224*
- Position-Tracking Control of Dual-Rope Winch Robot With Rope Slip Compensation. Yoo, S., +, TMECH Aug. 2021 1754-1762
- Tracking Accuracy Improvement Based on Adaptive Nonlinear Sliding Mode Control. *Tsai*, W., +, *TMECH Feb. 2021 179-190*

Fuel economy

- Design Method for Reducing AC Resistance of Traction Motor Using High Fill Factor Coil to Improve the Fuel Economy of eBus. *Cha, K.*, +, *TMECH June 2021 1260-1270*
- Real-Time Integrated Power and Thermal Management of Connected HEVs Based on Hierarchical Model Predictive Control. *Gong, X.*, +, *TMECH June 2021 1271-1282*

Function approximation

- Proportional-Integral Approximation-Free Control of Robotic Systems With Unknown Dynamics. Zhang, C., +, TMECH Aug. 2021 2226-2236
- Fuzzy control
 - Adaptive Output Feedback Control of Steer-by-Wire Systems With Event-Triggered Communication. *Ma*, *B*., +, *TMECH Aug. 2021 1968-1979*
 - Development of Embedded Sensor System for 5-DOF Finger-Wearable Tactile Interface. *Lim, B.,* +, *TMECH Aug. 2021 1728-1736*
 - Distributed Formation Control Using Fuzzy Self-Tuning of Strictly Negative Imaginary Consensus Controllers in Aerial Robotics. Tran, V.P., +, TMECH Oct. 2021 2306-2315
 - Fractional-Order Control for Uncertain Teleoperated Cyber-Physical System With Actuator Fault. Ma, Z., +, TMECH Oct. 2021 2472-2482
 - Quasi-LPV Interconnected Observer Design for Full Vehicle Dynamics Estimation With Hardware Experiments. *Fouka*, M., +, *TMECH Aug. 2021* 1763-1772
 - Takagi–Sugeno Fuzzy Unknown Input Observers to Estimate Nonlinear Dynamics of Autonomous Ground Vehicles: Theory and Real-Time Verification. *Nguyen, A., +, TMECH June 2021 1328-1338*
 - Takagi–Sugeno Fuzzy-Based Robust $H\infty$ Integrated Lane-Keeping and Direct Yaw Moment Controller of Unmanned Electric Vehicles. *Guo*, *J.*, +, *TMECH Aug. 2021 2151-2162*
 - Tracking Accuracy Improvement Based on Adaptive Nonlinear Sliding Mode Control. *Tsai*, W., +, *TMECH Feb. 2021 179-190*

Fuzzy logic

On-Body RF Sensor Toward Tremor Detection in Parkinson's Disease. Abirami B, S., +, TMECH Oct. 2021 2814-2817

Fuzzy set theory

Gait analysis

Incorporating the Qualitative Variable Comfort Into the Design of a Wearable Body Sensor System. Falch, L., +, TMECH Feb. 2021 124-133

G

- A Compact Ankle Exoskeleton With a Multiaxis Parallel Linkage Mechanism. Lee, M., +, TMECH Feb. 2021 191-202
- Human-in-the-Loop Control of a Wearable Lower Limb Exoskeleton for Stable Dynamic Walking. *Li*, *Z*, +, *TMECH Oct. 2021 2700-2711*
- Mech-Walker: A Novel Single-DOF Linkage Device With Movable Frame for Gait Rehabilitation. *Haghjoo*, *M.R.*, +, *TMECH Feb. 2021 13-23*
- Mechanism and Controller Design of a Transfemoral Prosthesis With Electrohydraulic Knee and Motor-Driven Ankle. *Gao, S.*, +, *TMECH Oct. 2021* 2429-2439
- Parallel Compliance Design for Increasing Robustness and Efficiency in Legged Locomotion–Theoretical Background and Applications. Sharbafi, M.A., +, TMECH Feb. 2021 335-346
- Wearable Knee Assistive Devices for Kneeling Tasks in Construction. *Chen, S.*, +, *TMECH Aug. 2021 1989-1996*

Gaussian distribution

Basic Input–Output Gain Tuning System Based on Control Input Histogram Leveling for Human-Operated Machines. Kamezaki, M., +, TMECH Dec. 2021 2857-2869

Gaussian processes

- A Visual Servo-Based Predictive Control With Echo State Gaussian Process for Soft Bending Actuator. *Cao, Y.*, +, *TMECH Feb. 2021 574-585*
- General Discharge Voltage Information Enabled Health Evaluation for Lithium-Ion Batteries. Deng, Z., +, TMECH June 2021 1295-1306
- Time/Space-Separation-Based Gaussian Process Modeling for the Cross-Coupling Effect of a 2-DOF Nanopositioning Stage. *Tao, Y.*, +, *TMECH Aug. 2021 2186-2194*

Gears

- A New Position Detection and Status Monitoring System for Joint of SCARA. Lu, W., +, TMECH June 2021 1613-1623
- A Novel Rotational Actuator With Variable Stiffness Using S-Shaped Springs. Xu, Y, +, TMECH Aug. 2021 2249-2260
- A Novel Wolfrom-Based Gearbox for Robotic Actuators. Crispel, S., +, TMECH Aug. 2021 1980-1988

- An Investigation Into Fault Diagnosis of Planetary Gearboxes Using A Bispectrum Convolutional Neural Network. *Pang, X.*, +, *TMECH Aug.* 2021 2027-2037
- Design Principles for Compact, Backdrivable Actuation in Partial-Assist Powered Knee Orthoses. Zhu, H., +, TMECH Dec. 2021 3104-3115
- Experimental Investigation on Control of an Infinitely Variable Transmission System for Tidal Current Energy Converters. Li, G., +, TMECH Aug. 2021 1960-1967
- Thermal Modeling and Characterization of Twisted Coiled Actuators for Upper Limb Wearable Devices. *Edmonds, B.P.R.*, +, *TMECH April 2021* 966-977

Genetic algorithms

- A Monolithic Force Sensing Integrated Flexure Bonder Dedicated to Flip-Chip Active Soft-Landing Interconnection. *Tang, H.*, +, *TMECH Feb.* 2021 323-334
- Multiobjective Scheduling Strategy With Genetic Algorithm and Time-Enhanced A* Planning for Autonomous Parking Robotics in High-Density Unmanned Parking Lots. *Chen, G.,* +, *TMECH June 2021 1547-1557*

Genomics

Blindly Controlled Magnetically Actuated Capsule for Noninvasive Sampling of the Gastrointestinal Microbiome. *Shokrollahi*, P., +, *TMECH Oct.* 2021 2616-2628

Geology

Automatic Construction of Three-Dimensional Ground Model by Data Processing. *Takeyama*, *T.*, +, *TMECH Dec.* 2021 2881-2887

Geometry

- A Laser-Guided Solution to Manipulate Mobile Robot Arm Terminals Within a Large Workspace. *Li*, *F*., +, *TMECH Oct. 2021 2676-2687*
- Generative Adversarial Network for Prediction of Workpiece Surface Topography in Machining Stage. Cao, L., +, TMECH Feb. 2021 480-490
- Geometrical-Based Displacement Measurement With Pseudostereo Monocular Camera on Bidirectional Cascaded Linear Actuator. *Lee, D.*, +, *TMECH Aug. 2021 1923-1931*

Global Positioning System

- Covert Attacks Through Adversarial Learning: Study of Lane Keeping Attacks on the Safety of Autonomous Vehicles. *Farivar, F., +, TMECH June 2021 1350-1357*
- Optimal Design and Implementation of a Novel Two-Dimensional Electromagnetic Navigation System That Allows Focused Heating of Magnetic Nanoparticles. *Le, T.,* +, *TMECH Feb. 2021 551-562*

Gradient methods

Topology Optimization of Skeleton-Reinforced Soft Pneumatic Actuators for Desired Motions. *Chen, S.,* +, *TMECH Aug. 2021 1745-1753*

Graph theory

- Efficient Bathymetric SLAM With Invalid Loop Closure Identification. Teng, M., +, TMECH Oct. 2021 2570-2580
- Interactive Behavior Prediction for Heterogeneous Traffic Participants in the Urban Road: A Graph-Neural-Network-Based Multitask Learning Framework. Li, Z., +, TMECH June 2021 1339-1349

Grasping

- A Microgripper With a Large Magnification Ratio and High Structural Stiffness Based on a Flexure-Enabled Mechanism. *Shi*, C., +, *TMECH Dec.* 2021 3076-3086
- Edge-Dependent Efficient Grasp Rectangle Search in Robotic Grasp Detection. Chen, L., +, TMECH Dec. 2021 2922-2931

Gravity

- A Delaunay Triangulation-Based Matching Area Selection Algorithm for Underwater Gravity-Aided Inertial Navigation. *Wang, C.*, +, *TMECH April 2021 908-917*
- Magnetically Levitated Linear Drive Using an Active Gravity Compensation Based on Hybrid Shape Memory Actuators. *Raab, M.*, +, *TMECH June* 2021 1380-1391

Grinding

Pose Error Estimation Using a Cylinder in Scanner-Based Robotic Belt Grinding. Xie, H., +, TMECH Feb. 2021 515-526

Grippers

- A Microgripper With a Large Magnification Ratio and High Structural Stiffness Based on a Flexure-Enabled Mechanism. *Shi*, *C.*, +, *TMECH Dec.* 2021 3076-3086
- A Monolithic Force Sensing Integrated Flexure Bonder Dedicated to Flip-Chip Active Soft-Landing Interconnection. *Tang, H., +, TMECH Feb.* 2021 323-334
- A Suction-Based Peripheral Nerve Gripper Capable of Controlling the Suction Force. Jang, N., +, TMECH Aug. 2021 1867-1876
- A Two-Finger Soft-Robotic Gripper With Enveloping and Pinching Grasping Modes. *Liu*, *S.*, +, *TMECH Feb. 2021 146-155*
- Compliant Bistable Grippers Enable Passive Perching for Micro Aerial Vehicles. *Zhang, H.,* +, *TMECH Oct. 2021 2316-2326*
- Soft Robotic Palm With Tunable Stiffness Using Dual-Layered Particle Jamming Mechanism. Lee, J., +, TMECH Aug. 2021 1820-1827
- Topology Optimization for Design of a 3D-Printed Constant-Force Compliant Finger. *Liu*, *C.*, +, *TMECH Aug. 2021 1828-1836*

Gyroscopes

- MEMS-Enabled Retrofitting of Automobile Wheel Balancer for Automatic Unbalance Detection. *Pozzato, G., +, TMECH April 2021 830-840*
- Passivity-Based Nonlinear Control Approach for Tracking Task of an Underactuated CMG. *Toriumi, F.Y.*, +, *TMECH Oct. 2021 2285-2293*

Η

\mathbf{H}^{∞} control

A Generalized Design Method for Learning-Based Disturbance Observer. Zheng, M., +, TMECH Feb. 2021 45-54

Handicapped aids

Virtual Landmark-Based Control of Docking Support for Assistive Mobility Devices. *Chen, Y.*, +, *TMECH Aug. 2021 2007-2015*

Haptic interfaces

- Design and Rapid Construction of a Cost-Effective Virtual Haptic Device. Wang, F., +, TMECH Feb. 2021 66-77
- Development of Embedded Sensor System for 5-DOF Finger-Wearable Tactile Interface. *Lim, B., +, TMECH Aug. 2021 1728-1736*
- Haptic Display Responsive to Touch Driven by Soft Actuator and Soft Sensor. *Phung, H., +, TMECH Oct. 2021 2495-2505*
- Kernel Principal Components Analysis of Lateral Force Data for Quantitative Evaluation of 3D Features Rendering Fidelity. *Liu, G.*, +, *TMECH June 2021 1602-1612*

Hardness

Localized Property Design and Gradient Processing of a Hydraulic Valve Body Using Selective Laser Melting. *Zhu, Y.*, +, *TMECH April 2021 1151-1160*

Harmonic analysis

- Adaptive Harmonic and Disturbance Estimators for Rotary Machines With Applications to Engines. Vadamalu, R.S., +, TMECH Feb. 2021 381-392
- Design Process and Verification of SPMSM for a Wearable Robot Considering Thermal Characteristics Through LPTN. Hwang, S., +, TMECH April 2021 1033-1042

Heat transfer

Actuation Frequency Modeling and Prediction for Shape Memory Alloy Actuators. *Liu*, X., +, *TMECH June 2021 1536-1546*

Helicopters

- A Tilting-Rotor Unmanned Aerial Vehicle for Enhanced Aerial Locomotion and Manipulation Capabilities: Design, Control, and Applications. *Ding*, *C.*, +, *TMECH Aug*, 2021 2237-2248
- Compliant Bistable Grippers Enable Passive Perching for Micro Aerial Vehicles. Zhang, H., +, TMECH Oct. 2021 2316-2326
- Design and Experimental Validation of Robust Self-Scheduled Fault-Tolerant Control Laws for a Multicopter UAV. Nguyen, D., +, TMECH Oct. 2021 2548-2557
- Distributed Control Algorithm for Leader–Follower Formation Tracking of Multiple Quadrotors: Theory and Experiment. *Wang, Z.*, +, *TMECH April* 2021 1095-1105

Hemodynamics

Automated Retinal Vein Cannulation on Silicone Phantoms Using Optical-Coherence-Tomography-Guided Robotic Manipulations. Gerber, M.J., +, TMECH Oct. 2021 2758-2769

Histograms

Basic Input–Output Gain Tuning System Based on Control Input Histogram Leveling for Human-Operated Machines. Kamezaki, M., +, TMECH Dec. 2021 2857-2869

Human computer interaction

- Kernel Principal Components Analysis of Lateral Force Data for Quantitative Evaluation of 3D Features Rendering Fidelity. *Liu, G.*, +, *TMECH June 2021 1602-1612*
- Pulling Illusion Based on the Phase Difference of the Frequency Components of Asymmetric Vibrations. *Tanabe, T.*, +, *TMECH Feb. 2021 203-213*

Human-robot interaction

- A Novel Cable-Driven 7-DOF Anthropomorphic Manipulator. *Huang, Y.*, +, *TMECH Aug, 2021 2174-2185*
- Amaran:An Unmanned Robotic Coconut Tree Climber and Harvester. Megalingam, R.K., +, TMECH Feb. 2021 288-299
- An Electrical Impedance Tomography Based Interface for Human–Robot Collaboration. Zheng, E., +, TMECH Oct. 2021 2373-2384
- Dynamic Modeling and State Estimation of Cable-Conduit Actuation During Interaction With Nonpassive Environments. *Buchanan, S.*, +, *TMECH Oct.* 2021 2462-2471
- Human–Robot Cooperation Control Based on Trajectory Deformation Algorithm for a Lower Limb Rehabilitation Robot. *Zhou, J.*, +, *TMECH Dec.* 2021 3128-3138
- Human-in-the-Loop Control of a Wearable Lower Limb Exoskeleton for Stable Dynamic Walking. Li, Z., +, TMECH Oct. 2021 2700-2711
- Markovian Robust Filtering and Control Applied to Rehabilitation Robotics. Escalante, F.M., +, TMECH Feb. 2021 491-502
- Optimized Interaction Control for Robot Manipulator Interacting With Flexible Environment. *Liu*, X., +, *TMECH Dec. 2021 2888-2898*
- Otariidae-Inspired Soft-Robotic Supernumerary Flippers by Fabric Kirigami and Origami. Liu, S., +, TMECH Oct. 2021 2747-2757

Humanoid robots

- A Novel Cable-Driven 7-DOF Anthropomorphic Manipulator. *Huang, Y*, +, *TMECH Aug. 2021 2174-2185*
- Dual Fast Marching Tree Algorithm for Human-Like Motion Planning of Anthropomorphic Arms With Task Constraints. *Xia, J., +, TMECH Oct.* 2021 2803-2813
- Dynamic Torso Compliance Control for Standing and Walking Balance of Position-Controlled Humanoid Robots. *Li*, *Q*., +, *TMECH April 2021 679-688*
- Human-in-the-Loop Control of a Wearable Lower Limb Exoskeleton for Stable Dynamic Walking. Li, Z., +, TMECH Oct. 2021 2700-2711
- Online Delayed Reference Generation for a Humanoid Imitating Human Walking Motion. *Oh, J.*, +, *TMECH Feb. 2021 102-112*
- Phase-Relaxed-Passive Full State Feedback Gain Limits for Series Elastic Actuators. *Thomas, G.C.,* +, *TMECH Feb. 2021 586-591*
- Terrain Identification for Humanoid Robots Applying Convolutional Neural Networks. *Venancio, M.M.*, +, *TMECH June 2021 1433-1444*

Hybrid electric vehicles

Real-Time Integrated Power and Thermal Management of Connected HEVs Based on Hierarchical Model Predictive Control. *Gong, X.*, +, *TMECH June 2021 1271-1282*

Hydraulic systems

- Accurate Motion Control of a Direct-Drive Hydraulic System With an Adaptive Nonlinear Pump Flow Compensation. *Helian, B.*, +, *TMECH Oct.* 2021 2593-2603
- An Adaptive Fuzzy Trajectory Tracking Control via Improved Cerebellar Model Articulation Controller for Electro-Hydraulic Shovel. *Fan, R.*, +, *TMECH Dec. 2021 2870-2880*
- Analytical Harmonic Method for Modeling High-Frequency Oscillation With Applications to Aircraft Piston Pump Vibration Analysis. *Li*, *L.*, +, *TMECH April 2021 918-929*

- Failure Monitoring and Predictive Maintenance of Hydraulic Cylinder— State-of-the-Art Review. Shanbhag, V.V., +, TMECH Dec. 2021 3087-3103
- Mechanism and Controller Design of a Transfemoral Prosthesis With Electrohydraulic Knee and Motor-Driven Ankle. *Gao, S.*, +, *TMECH Oct. 2021* 2429-2439
- Steady-State Characteristics Study of a Power Split Hydraulic Transmission. Wang, F., +, TMECH Feb. 2021 78-89

Hydrodynamics

- Biomimetic Realization of a Robotic Penguin Wing: Design and Thrust Characteristics. Shen, Y., +, TMECH Oct. 2021 2350-2361
- Design and Experimental Validation of a Novel High-Speed Omnidirectional Underwater Propulsion Mechanism. Njaka, T., +, TMECH Oct. 2021 2339-2349

Hydrostatics

Steady-State Characteristics Study of a Power Split Hydraulic Transmission. Wang, F, +, TMECH Feb. 2021 78-89

Hyperthermia

Optimal Design and Implementation of a Novel Two-Dimensional Electromagnetic Navigation System That Allows Focused Heating of Magnetic Nanoparticles. *Le*, *T*., +, *TMECH Feb. 2021 551-562*

Ι

IEEE transactions

- Intelligent Vibration Control for Semiactive Suspension Systems Without Prior Knowledge of Dynamical Nonlinear Damper Behaviors Based on Improved Extreme Learning Machine. *Huang, W.*, +, *TMECH Aug. 2021* 2071-2079
- Prediction-Model-Based Contouring Error Iterative Precompensation Scheme for Precision Multiaxis Motion Systems. *Wang, Z.*, +, *TMECH Oct. 2021 2274-2284*

Image classification

Efficient Anomaly Detection in a Laser-Surface Heat-Treatment Process via Laser-Spot Tracking. *Atienza*, *D.*, +, *TMECH Feb. 2021 405-415*

Image color analysis

- Nontarget-Based Measurement of 6-DOF Structural Displacement Using Combined RGB Color and Depth Information. *Lee, S.*, +, *TMECH June* 2021 1358-1368
- Self-Balancing Two-Wheeled Robot Featuring Intelligent End-to-End Deep Visual-Steering. Li, C.G., +, TMECH Oct. 2021 2263-2273

Image edge detection

Edge-Dependent Efficient Grasp Rectangle Search in Robotic Grasp Detection. Chen, L., +, TMECH Dec. 2021 2922-2931

Image fusion

Collaborative Semantic Understanding and Mapping Framework for Autonomous Systems. Yue, Y, +, TMECH April 2021 978-989

Image matching

A Delaunay Triangulation-Based Matching Area Selection Algorithm for Underwater Gravity-Aided Inertial Navigation. Wang, C., +, TMECH April 2021 908-917

Image motion analysis

Efficient Anomaly Detection in a Laser-Surface Heat-Treatment Process via Laser-Spot Tracking. *Atienza*, D., +, *TMECH Feb. 2021 405-415*

Image processing

Image Processing Metrics for Phase Identification of a Multiaxis MEMS Scanner Used in Single Pixel Imaging. *Birla, M.*, +, *TMECH June 2021* 1445-1454

Image reconstruction

Image Processing Metrics for Phase Identification of a Multiaxis MEMS Scanner Used in Single Pixel Imaging. *Birla, M.*, +, *TMECH June 2021* 1445-1454

Image registration

Image Processing Metrics for Phase Identification of a Multiaxis MEMS Scanner Used in Single Pixel Imaging. *Birla, M.*, +, *TMECH June 2021* 1445-1454

Image resolution

Development of a Resonant Scanner to Improve the Imaging Rate of Astigmatic Optical Profilometers. *Liao, H., +, TMECH April 2021 1172-1177*

- Image Processing Metrics for Phase Identification of a Multiaxis MEMS Scanner Used in Single Pixel Imaging. *Birla, M.*, +, *TMECH June 2021* 1445-1454
- Iterative Learning Control for Video-Rate Atomic Force Microscopy. Nikooienejad, N., +, TMECH Aug. 2021 2127-2138

Image restoration

Image Processing Metrics for Phase Identification of a Multiaxis MEMS Scanner Used in Single Pixel Imaging. *Birla, M.*, +, *TMECH June 2021* 1445-1454

Image scanners

Development of a Resonant Scanner to Improve the Imaging Rate of Astigmatic Optical Profilometers. *Liao, H., +, TMECH April 2021 1172-1177*

Image segmentation

- Geometrical-Based Displacement Measurement With Pseudostereo Monocular Camera on Bidirectional Cascaded Linear Actuator. Lee, D., +, TMECH Aug. 2021 1923-1931
- Segmentation-Oriented Compressed Sensing for Efficient Impact Damage Detection on CFRP Materials. *Tang, C., +, TMECH Oct. 2021 2528-2537*
- Vision-Based Cutting Control of Deformable Objects With Surface Tracking. Han, L., +, TMECH Aug. 2021 2016-2026

Image texture

Generative Adversarial Network for Prediction of Workpiece Surface Topography in Machining Stage. Cao, L., +, TMECH Feb. 2021 480-490

Imaging

Autonomous Navigation of Magnetic Microrobots in a Large Workspace Using Mobile-Coil System. Yang, Z., +, TMECH Dec. 2021 3163-3174

Impedance

Human–Robot Cooperation Control Based on Trajectory Deformation Algorithm for a Lower Limb Rehabilitation Robot. *Zhou, J.*, +, *TMECH Dec.* 2021 3128-3138

Implants

Characterization of a Packaged Triboelectric Harvester Under Simulated Gait Loading for Total Knee Replacement. *Hossain, N.A.*, +, *TMECH Dec.* 2021 2967-2976

Induction motors

- Sensorless Unbalance Diagnosis of Affiliated Rotating Chamber Based on Driving Current of Permanent Magnet Synchronous Motor. *Huo, X.*, +, *TMECH Dec. 2021 2899-2909*
- Stability and Sommerfeld Effect of a Vibrating System With Two Vibrators Driven Separately by Induction Motors. *Zhang, X.*, +, *TMECH April 2021* 807-817

Industrial manipulators

- A New Position Detection and Status Monitoring System for Joint of SCARA. Lu, W., +, TMECH June 2021 1613-1623
- Globally Optimal Symbolic Hand-Eye Calibration. Wu, J., +, TMECH June 2021 1369-1379

Industrial robots

- A Novel Clustering-Based Algorithm for Solving Spatially Constrained Robotic Task Sequencing Problems. *Wong, C.*, +, *TMECH Oct. 2021 2294-2305*
- Automated In Situ Placing of Metal Components Into 3-D Printed FFF Objects. Ahlers, D., +, TMECH Aug. 2021 1886-1894
- Control Parameters Design Based on Dynamic Characteristics of a Hybrid Robot With Parallelogram Structures. *Liu*, *Z*., +, *TMECH April 2021 1140-1150*
- Dynamic Path Correction of an Industrial Robot Using a Distance Sensor and an ADRC Controller. *Khaled*, T.A., +, *TMECH June 2021 1646-1656*
- Pose Error Estimation Using a Cylinder in Scanner-Based Robotic Belt Grinding. Xie, H., +, TMECH Feb. 2021 515-526

Inertial navigation

A Delaunay Triangulation-Based Matching Area Selection Algorithm for Underwater Gravity-Aided Inertial Navigation. Wang, C., +, TMECH April 2021 908-917

Infrared imaging

A DC-Biased Scanning Induction Thermographic System for Characterizing Surface Cracks in Ferromagnetic Components. *Wu, J.*, +, *TMECH Oct.* 2021 2782-2790 Efficient Anomaly Detection in a Laser-Surface Heat-Treatment Process via Laser-Spot Tracking. *Atienza*, *D.*, +, *TMECH Feb. 2021 405-415*

Injuries

Wearable Knee Assistive Devices for Kneeling Tasks in Construction. *Chen*, S., +, *TMECH Aug. 2021 1989-1996*

Ink jet printing

- Robotic Prototyping of Paper-Based Field-Effect Transistors With Rolled-Up Semiconductor Microtubes. *Dong, X.*, +, *TMECH Feb. 2021 427-436* Inspection
 - Development of a Concrete Floating and Delamination Detection System Using Infrared Thermography. *Chun, P., +, TMECH Dec. 2021 2835-2844* Geometrical-Based Displacement Measurement With Pseudostereo Mon-
 - ocular Camera on Bidirectional Cascaded Linear Actuator. Lee, D., +, TMECH Aug. 2021 1923-1931
 - Guest Editorial Introduction to the Focused Section on Mechatronics and Automation for Constructions. *Cheah, C.C.*, +, *TMECH Dec. 2021 2819-2825*
 - Robot-Assisted Object Detection for Construction Automation: Data and Information-Driven Approach. *Muhammad, I.*, +, *TMECH Dec. 2021* 2845-2856
 - Weakly Supervised Acoustic Defect Detection in Concrete Structures Using Clustering-Based Augmentation. *Kasahara, J.Y.L.*, +, *TMECH Dec. 2021* 2826-2834

Integrated optics

Ultraviolet Beam Lithography System for Digital Fabrication of Roller Molds. Yang, S., +, TMECH Feb. 2021 226-234

Integration

Computationally Efficient Practical Method for Solving the Dynamics of Fluid Power Circuits in the Presence of Singularities. *Malysheva*, J., +, *TMECH Oct. 2021 2385-2395*

Identification of a Nonlinear Dielectric Elastomer Actuator Based on the Harmonic Balance Method. *Bernat*, J., +, *TMECH Oct. 2021 2664-2675*

Intelligent actuators

Development and Test of a Two-Dimensional Stacked Terfenol-D Actuator With High Bandwidth and Large Stroke. *Chen, L.*, +, *TMECH Aug. 2021* 1951-1959

Intelligent materials

Development and Test of a Two-Dimensional Stacked Terfenol-D Actuator With High Bandwidth and Large Stroke. *Chen, L.*, +, *TMECH Aug. 2021* 1951-1959

Intelligent transportation systems

Unmanned System Safety Decision-Making Support: Analysis and Assessment of Road Traffic Accidents. *Xie, G., +, TMECH April 2021 633-644*

Interactive systems

OrthographicNet: A Deep Transfer Learning Approach for 3-D Object Recognition in Open-Ended Domains. *Kasaei, S.H., TMECH Dec. 2021 2910-2921*

Internet

Covert Attacks Through Adversarial Learning: Study of Lane Keeping Attacks on the Safety of Autonomous Vehicles. *Farivar, F., +, TMECH June 2021 1350-1357*

Interpolation

A High Range-to-Resolution Multiaxis μForce and Torque Sensing Platform. *Tiwari*, B., +, *TMECH Aug. 2021 1837-1845*

Inverse problems

Low Impedance-Guaranteed Gain-Scheduled GESO for Torque-Controlled VSA With Application of Exoskeleton-Assisted Sit-to-Stand. *Liu, L.*, +, *TMECH Aug. 2021 2080-2091*

ISO standards

Global Optimization of the Hydraulic-Electromagnetic Energy-Harvesting Shock Absorber for Road Vehicles With Human-Knowledge-Integrated Particle Swarm Optimization Scheme. *Zhou, Q.*, +, *TMECH June 2021* 1225-1235

Iterative learning control

- A Generalized Design Method for Learning-Based Disturbance Observer. Zheng, M., +, TMECH Feb. 2021 45-54
- Iterative Learning Control for Video-Rate Atomic Force Microscopy. Nikooienejad, N., +, TMECH Aug. 2021 2127-2138

Iterative methods

- A Generalized Design Method for Learning-Based Disturbance Observer. Zheng, M., +, TMECH Feb. 2021 45-54
- Actuation Frequency Modeling and Prediction for Shape Memory Alloy Actuators. *Liu, X., +, TMECH June 2021 1536-1546*
- Dynamic Modeling and State Estimation of Cable-Conduit Actuation During Interaction With Nonpassive Environments. *Buchanan, S.*, +, *TMECH Oct.* 2021 2462-2471
- Globally Optimal Symbolic Hand-Eye Calibration. *Wu*, *J.*, +, *TMECH June* 2021 1369-1379
- Pose Error Estimation Using a Cylinder in Scanner-Based Robotic Belt Grinding. Xie, H., +, TMECH Feb. 2021 515-526

J

Jacobian matrices

- Design and Validation of a Novel Fuzzy-Logic-Based Static Feedback Controller for Tendon-Driven Continuum Robots. *Ba, W.*, +, *TMECH Dec.* 2021 3010-3021
- 2021 3010-3021 Vibration Reduction of Flexible Rope-Driven Mobile Robot for Safe Façade

Operation. Seo, M., +, TMECH Aug. 2021 1812-1819

Jitter

Cyber–Physical Codesign of Field-Level Reconfigurations in Networked Motion Controllers. *Zhou*, *N*., +, *TMECH Aug. 2021 2092-2103*

Κ

Kalman filters

- An Adaptive Fault-Tolerant EKF for Vehicle State Estimation With Partial Missing Measurements. *Wang, Y*, +, *TMECH June 2021 1318-1327*
- Dimensionless Model-Based System Tracking Via Augmented Kalman Filter for Multiscale Unmanned Ground Vehicles. *Sun, C.*, +, *TMECH April* 2021 600-610
- Markovian Robust Filtering and Control Applied to Rehabilitation Robotics. Escalante, F.M., +, TMECH Feb. 2021 491-502
- Real-Time Avoidance Strategy of Dynamic Obstacles via Half Model-Free Detection and Tracking With 2D Lidar for Mobile Robots. *Dong, H.*, +, *TMECH Aug. 2021 2215-2225*
- Stochastic Force-Based Insertion Depth and Tip Position Estimations of Flexible FBG-Equipped Instruments in Robotic Retinal Surgery. *Ebrahimi, A.*, +, *TMECH June 2021 1512-1523*
- Vision-Based Control of a Knuckle Boom Crane With Online Cable Length Estimation. *Tysse, G.O.*, +, *TMECH Feb. 2021 416-426*

Kinematics

- Design and Validation of a Novel Fuzzy-Logic-Based Static Feedback Controller for Tendon-Driven Continuum Robots. *Ba, W.*, +, *TMECH Dec.* 2021 3010-3021
- Integral Design and Manufacturing Methodology of a Reduced-Scale Servo Press. Olaizola, J., +, TMECH Oct. 2021 2418-2428
- Kinematic Modeling and Control of Variable Curvature Soft Continuum Robots. *Huang, X.*, +, *TMECH Dec. 2021 3175-3185*

Knee

Characterization of a Packaged Triboelectric Harvester Under Simulated Gait Loading for Total Knee Replacement. *Hossain, N.A.*, +, *TMECH Dec.* 2021 2967-2976

 \mathbf{L}

Lab-on-chip

Longitudinal Motion Modeling and Experimental Verification of a Microrobot Subject to Liquid Laminar Flow. *Demircali, A.A.*, +, *TMECH Dec.* 2021 2956-2966

Laparoscopes

Development of a Soft Robot Based Photodynamic Therapy for Pancreatic Cancer. *Li*, *Y*, +, *TMECH Dec. 2021 2977-2985*

Laser materials processing

Localized Property Design and Gradient Processing of a Hydraulic Valve Body Using Selective Laser Melting. *Zhu, Y.*, +, *TMECH April 2021 1151-1160*

Layout

- A Hermaphrodite Electromechanical Connector for Self-Reconfigurable Robot Modules. *Tian, X.*, +, *TMECH Dec. 2021 3276-3281*
- Overcoming the Torque/Stiffness Range Tradeoff in Antagonistic Variable Stiffness Actuators. *Mengacci, R., +, TMECH Dec. 2021 3186-3197*

Learning (artificial intelligence)

- A Two-Stage Transfer Adversarial Network for Intelligent Fault Diagnosis of Rotating Machinery With Multiple New Faults. *Li*, *J.*, +, *TMECH June* 2021 1591-1601
- A Visual Servo-Based Predictive Control With Echo State Gaussian Process for Soft Bending Actuator. *Cao*, Y., +, *TMECH Feb. 2021* 574-585
- An Investigation Into Fault Diagnosis of Planetary Gearboxes Using A Bispectrum Convolutional Neural Network. *Pang, X.*, +, *TMECH Aug.* 2021 2027-2037
- Construction of Controller Model of Notch Continuum Manipulator for Laryngeal Surgery Based on Hybrid Method. *Wang, H.*, +, *TMECH April* 2021 1022-1032
- Covert Attacks Through Adversarial Learning: Study of Lane Keeping Attacks on the Safety of Autonomous Vehicles. *Farivar, F., +, TMECH June 2021 1350-1357*
- Efficient Anomaly Detection in a Laser-Surface Heat-Treatment Process via Laser-Spot Tracking. *Atienza*, D., +, *TMECH Feb. 2021 405-415*
- Efficient Cooperative Structured Control for a Multijoint Biomimetic Robotic Fish. Yan, S., +, TMECH Oct. 2021 2506-2516
- Generative Adversarial Network for Prediction of Workpiece Surface Topography in Machining Stage. Cao, L., +, TMECH Feb. 2021 480-490
- Global Optimization of the Hydraulic-Electromagnetic Energy-Harvesting Shock Absorber for Road Vehicles With Human-Knowledge-Integrated Particle Swarm Optimization Scheme. *Zhou, Q., +, TMECH June 2021 1225-1235*
- Interactive Behavior Prediction for Heterogeneous Traffic Participants in the Urban Road: A Graph-Neural-Network-Based Multitask Learning Framework. *Li*, *Z*., +, *TMECH June 2021 1339-1349*
- Learning Communication for Cooperation in Dynamic Agent-Number Environment. Liu, W., +, TMECH Aug. 2021 1846-1857
- Sensing and Reconstruction of 3-D Deformation on Pneumatic Soft Robots. Scharff, R.B.N., +, TMECH Aug. 2021 1877-1885

Least squares approximations

Incorporating the Qualitative Variable Comfort Into the Design of a Wearable Body Sensor System. Falch, L., +, TMECH Feb. 2021 124-133

Legged locomotion

- Development of a Nanopositioning Platform With Large Travel Range Based on Bionic Quadruped Piezoelectric Actuator. *Deng, J.*, +, *TMECH Aug.* 2021 2059-2070
- Dynamic Torso Compliance Control for Standing and Walking Balance of Position-Controlled Humanoid Robots. *Li*, *Q*., +, *TMECH April 2021 679-688*
- Efficient Cooperative Structured Control for a Multijoint Biomimetic Robotic Fish. Yan, S., +, TMECH Oct. 2021 2506-2516
- Efficient Motion Planning Based on Kinodynamic Model for Quadruped Robots Following Persons in Confined Spaces. *Zhang, Z.*, +, *TMECH Aug.* 2021 1997-2006
- Evaluation of Locomotion Performances for a Mecanum-Wheeled Hybrid Hexapod Robot. Orozco-Magdaleno, E.C., +, TMECH June 2021 1657-1667
- Human-in-the-Loop Control of a Wearable Lower Limb Exoskeleton for Stable Dynamic Walking. *Li*, *Z*., +, *TMECH Oct. 2021 2700-2711*
- Parallel Compliance Design for Increasing Robustness and Efficiency in Legged Locomotion–Theoretical Background and Applications. Sharbafi, M.A., +, TMECH Feb. 2021 335-346
- Planning Three-Dimensional Collision-Free Optimized Climbing Path for Biped Wall-Climbing Robots. *Zhu, H.*, +, *TMECH Oct. 2021 2712-2723*
- Reconstructing Walking Dynamics From Two Shank-Mounted Inertial Measurement Units. Li, T., +, TMECH Dec. 2021 3040-3050
- Roller-Skating of Mammalian Quadrupedal Robot With Passive Wheels Inspired by Human. *Chen, J.*, +, *TMECH June 2021 1624-1634*

Terrain Identification for Humanoid Robots Applying Convolutional Neural Networks. *Venancio, M.M.*, +, *TMECH June 2021 1433-1444*

Light emitting diodes

- UltraLow Noise, High Bandwidth, Low Latency, No Overload 6-Axis Optical Force Sensor. *Hosseinabadi, A.H.H.*, +, *TMECH Oct. 2021 2581-2592*
- Lightweight structures Curvature-Induced Buckling for Flapping-Wing Vehicles. Sharifzadeh, M.,
 - +, *TMECH Feb. 2021 503-514* Localized Property Design and Gradient Processing of a Hydraulic Valve Body Using Selective Laser Melting. *Zhu, Y.*, +, *TMECH April 2021 1151*-

1160

Linear matrix inequalities

- A Lie-Theory-Based Dynamic Parameter Identification Methodology for Serial Manipulators. Fu, Z., +, TMECH Oct. 2021 2688-2699
- A Phase-Shaping Approach to the Control of Parametric Systems and Its Application. *Shimonomura, S.,* +, *TMECH Aug. 2021 2163-2173*
- Takagi–Sugeno Fuzzy Unknown Input Observers to Estimate Nonlinear Dynamics of Autonomous Ground Vehicles: Theory and Real-Time Verification. Nguyen, A., +, TMECH June 2021 1328-1338

Linear motors

- Magnetically Levitated Linear Drive Using an Active Gravity Compensation Based on Hybrid Shape Memory Actuators. *Raab, M.*, +, *TMECH June* 2021 1380-1391
- Magnetically Levitated Linear Stage With Linear Bearingless Slice Hysteresis Motors. *Zhou, L.*, +, *TMECH April 2021 1084-1094*
- Precise Linear-Motor Synchronization Control via Cross-Coupled Second-Order Discrete-Time Fractional-Order Sliding Mode. Kuang, Z., +, TMECH Feb. 2021 358-368
- Tracking Accuracy Improvement Based on Adaptive Nonlinear Sliding Mode Control. *Tsai, W.*, +, *TMECH Feb. 2021 179-190*

Linear parameter varying systems

- Low Impedance-Guaranteed Gain-Scheduled GESO for Torque-Controlled VSA With Application of Exoskeleton-Assisted Sit-to-Stand. *Liu, L.*, +, *TMECH Aug. 2021 2080-2091*
- Quasi-LPV Interconnected Observer Design for Full Vehicle Dynamics Estimation With Hardware Experiments. Fouka, M., +, TMECH Aug. 2021 1763-1772

Linear programming

A Microgripper With a Large Magnification Ratio and High Structural Stiffness Based on a Flexure-Enabled Mechanism. *Shi*, C., +, *TMECH Dec.* 2021 3076-3086

Linear quadratic control

- Markovian Robust Filtering and Control Applied to Rehabilitation Robotics. Escalante, F.M., +, TMECH Feb. 2021 491-502
- Modeling Quadrotor Dynamics in a Wind Field. Jeon, H., +, TMECH June 2021 1401-1411

Linear synchronous motors

Study on a Double-Sided Permanent-Magnet Linear Synchronous Motor With Reversed Slots. Zhao, J., +, TMECH Feb. 2021 3-12

Linear systems

- Markovian Robust Filtering and Control Applied to Rehabilitation Robotics. Escalante, F.M., +, TMECH Feb. 2021 491-502
- Vision-Based Control of a Knuckle Boom Crane With Online Cable Length Estimation. *Tysse, G.O.*, +, *TMECH Feb. 2021 416-426*

Linearization techniques

Dynamic Modeling and State Estimation of Cable-Conduit Actuation During Interaction With Nonpassive Environments. *Buchanan, S.*, +, *TMECH Oct.* 2021 2462-2471

Lithium compounds

- General Discharge Voltage Information Enabled Health Evaluation for Lithium-Ion Batteries. Deng, Z., +, TMECH June 2021 1295-1306
- Global Parameter Sensitivity Analysis of Electrochemical Model for Lithium-Ion Batteries Considering Aging. *Gao, Y.*, +, *TMECH June 2021 1283-1294*

Lithium ion batteries

Feature Analyses and Modeling of Lithium-Ion Battery Manufacturing Based on Random Forest Classification. *Liu, K.*, +, *TMECH Dec. 2021* 2944-2955

Local area networks

Cyber–Physical Codesign of Field-Level Reconfigurations in Networked Motion Controllers. Zhou, N., +, TMECH Aug. 2021 2092-2103

Losses

Design Method for Reducing AC Resistance of Traction Motor Using High Fill Factor Coil to Improve the Fuel Economy of eBus. *Cha, K.*, +, *TMECH June 2021 1260-1270*

Lumped parameter networks

Design Process and Verification of SPMSM for a Wearable Robot Considering Thermal Characteristics Through LPTN. *Hwang, S.*, +, *TMECH April* 2021 1033-1042

Lung

Robotized Catheter With Enhanced Distal Targeting for Peripheral Pulmonary Biopsy. *Kato*, *T*., +, *TMECH Oct. 2021 2451-2461*

Lyapunov methods

- A Binary Tree Based Coordination Scheme for Target Enclosing With Micro Aerial Vehicles. *Duan, H., +, TMECH Feb. 2021 458-468*
- A Constrained DMPs Framework for Robot Skills Learning and Generalization From Human Demonstrations. *Lu*, *Z.*, +, *TMECH Dec. 2021 3265-3275*
- A Novel Rotational Actuator With Variable Stiffness Using S-Shaped Springs. Xu, Y, +, TMECH Aug. 2021 2249-2260
- Adaptive Finite-Time Control for Half-Vehicle Active Suspension Systems With Uncertain Dynamics. *Liu*, *Y*, +, *TMECH Feb. 2021 168-178*
- Adaptive Output Feedback Control of Steer-by-Wire Systems With Event-Triggered Communication. *Ma, B.,* +, *TMECH Aug. 2021 1968-1979*
- Adaptive Robust Finite-Time Nonlinear Control of a Typical Autonomous Underwater Vehicle With Saturated Inputs and Uncertainties. *Sedghi, F.,* +, *TMECH Oct. 2021 2517-2527*
- An Observer-Based Neural Adaptive\$PID^2\$ Controller for Robot Manipulators Including Motor Dynamics With a Prescribed Performance. *Shojaei*, *K.*, +, *TMECH June 2021 1689-1699*
- An Output Feedback Based Robust Saturated Controller Design for Pavement Sweeping Self-Reconfigurable Robot. *Rayguru, M.M.*, +, *TMECH June 2021 1236-1247*
- Asymptotic Tracking Control of Mechanical Servosystems With Mismatched Uncertainties. Deng, W., +, TMECH Aug. 2021 2204-2214
- Distributed Control Algorithm for Leader–Follower Formation Tracking of Multiple Quadrotors: Theory and Experiment. Wang, Z., +, TMECH April 2021 1095-1105
- Event-Triggered-Based Discrete-Time Neural Control for a Quadrotor UAV Using Disturbance Observer. Shao, S., +, TMECH April 2021 689-699
- Finite-Time Synchronization Control for Bilateral Teleoperation Systems With Asymmetric Time-Varying Delay and Input Dead Zone. *Bao, J.*, +, *TMECH June 2021 1570-1580*
- Fractional-Order Control for Uncertain Teleoperated Cyber-Physical System With Actuator Fault. *Ma*, *Z*., +, *TMECH Oct.* 2021 2472-2482
- Model-Free Control of Flexible Manipulator Based on Intrinsic Design. *Jiang, N.*, +, *TMECH Oct. 2021 2641-2652*
- Modeling and Motion Control of Industrial Tractor–Trailers Vehicles Using Force Compensation. Zhao, H., +, TMECH April 2021 645-656
- Parallel Compliance Design for Increasing Robustness and Efficiency in Legged Locomotion–Theoretical Background and Applications. *Sharbafi, M.A.*, +, *TMECH Feb. 2021 335-346*
- Passivity-Based Nonlinear Control Approach for Tracking Task of an Underactuated CMG. *Toriumi, F.Y.*, +, *TMECH Oct. 2021 2285-2293*
- Practical Terminal Sliding Mode Control of Nonlinear Uncertain Active Suspension Systems With Adaptive Disturbance Observer. *Wang, G.*, +, *TMECH April 2021 789-797*
- Proportional-Integral Approximation-Free Control of Robotic Systems With Unknown Dynamics. *Zhang, C.,* +, *TMECH Aug. 2021 2226-2236*
- Quasi-LPV Interconnected Observer Design for Full Vehicle Dynamics Estimation With Hardware Experiments. *Fouka*, M., +, *TMECH Aug. 2021* 1763-1772
- Quasi-Synchronization Control of Multiple Electrohydraulic Actuators With Load Disturbance and Uncertain Parameters. *Guo, Q.*, +, *TMECH Aug.* 2021 2048-2058

Robust Adaptive Tracking Control of Underwater Vehicles: Design, Stability Analysis, and Experiments. *Tijjani, A.S.*, +, *TMECH April 2021 897-907*

Robust Tracking Control of a Quadrotor Unmanned Aerial Vehicle-Suspended Payload System. Xian, B., +, TMECH Oct. 2021 2653-2663

Takagi–Sugeno Fuzzy Unknown Input Observers to Estimate Nonlinear Dynamics of Autonomous Ground Vehicles: Theory and Real-Time Verification. Nguyen, A., +, TMECH June 2021 1328-1338

- Tracking Accuracy Improvement Based on Adaptive Nonlinear Sliding Mode Control. Tsai, W., +, TMECH Feb. 2021 179-190
- Vision-Based Cutting Control of Deformable Objects With Surface Tracking. Han, L., +, TMECH Aug. 2021 2016-2026

Whole-Body Control of an Autonomous Mobile Manipulator Using Series Elastic Actuators. *Liu*, *Y*., +, *TMECH April 2021 657-667*

М

Machine bearings

Geometrical-Based Displacement Measurement With Pseudostereo Monocular Camera on Bidirectional Cascaded Linear Actuator. *Lee, D.*, +, *TMECH Aug. 2021 1923-1931*

- Machine control
 - Experimental Investigation on Control of an Infinitely Variable Transmission System for Tidal Current Energy Converters. Li, G., +, TMECH Aug. 2021 1960-1967
 - Magnetically Levitated Linear Stage With Linear Bearingless Slice Hysteresis Motors. Zhou, L., +, TMECH April 2021 1084-1094
 - Online Compensation of Mechanical Load Defects With Composite Control in PMSM Drives. *Kommuri, S.K.*, +, *TMECH June 2021 1392-1400*
 - Practical Fixed-Time Position Tracking Control of Permanent Magnet DC Torque Motor Systems. *Wu, Y.*, +, *TMECH Feb. 2021 563-573*
 - Precise Linear-Motor Synchronization Control via Cross-Coupled Second-Order Discrete-Time Fractional-Order Sliding Mode. Kuang, Z., +, TMECH Feb. 2021 358-368
 - Rotor Position Tracking Control for Low Speed Operation of Direct-Drive PMSM Servo System. Bu, F., +, TMECH April 2021 1129-1139
 - Static Position Sensor Bias Fault Diagnosis in Permanent Magnet Synchronous Machines via Current Estimation. Kuruppu, S.S., +, TMECH April 2021 888-896
 - Tracking Accuracy Improvement Based on Adaptive Nonlinear Sliding Mode Control. Tsai, W., +, TMECH Feb. 2021 179-190

Machine testing

Static Position Sensor Bias Fault Diagnosis in Permanent Magnet Synchronous Machines via Current Estimation. Kuruppu, S.S., +, TMECH April 2021 888-896

Machine tool spindles

Four-Point Method in the Measurement and Separation of Spindle Rotation Error. Liu, F., +, TMECH Feb. 2021 113-123

Machine tools

- Four-Point Method in the Measurement and Separation of Spindle Rotation Error. *Liu*, *F*., +, *TMECH Feb. 2021 113-123*
- Pose Error Estimation Using a Cylinder in Scanner-Based Robotic Belt Grinding. Xie, H., +, TMECH Feb. 2021 515-526
- Study on a Double-Sided Permanent-Magnet Linear Synchronous Motor With Reversed Slots. Zhao, J., +, TMECH Feb. 2021 3-12

Machine windings

Design Method for Reducing AC Resistance of Traction Motor Using High Fill Factor Coil to Improve the Fuel Economy of eBus. *Cha, K.*, +, *TMECH June 2021 1260-1270*

Design Process and Verification of SPMSM for a Wearable Robot Considering Thermal Characteristics Through LPTN. Hwang, S., +, TMECH April 2021 1033-1042

Machinery

A Two-Stage Transfer Adversarial Network for Intelligent Fault Diagnosis of Rotating Machinery With Multiple New Faults. *Li*, *J.*, +, *TMECH June 2021 1591-1601*

Machining

Four-Point Method in the Measurement and Separation of Spindle Rotation Error. *Liu*, *F*., +, *TMECH Feb. 2021 113-123* Generative Adversarial Network for Prediction of Workpiece Surface Topography in Machining Stage. *Cao, L., +, TMECH Feb. 2021 480-490* Toolpath Regeneration in Subregional Contour-Parallel Processing Based on

Isoscallop Method. Ma, J., +, TMECH April 2021 730-740

Maglev vehicles

Analysis of Quasi-Zero Power Characteristic for a Permanent Magnetic Levitation System With a Variable Flux Path Control Mechanism. *Zhao, C.*, +, *TMECH Feb. 2021 437-447*

Magnetic actuators

- Blindly Controlled Magnetically Actuated Capsule for Noninvasive Sampling of the Gastrointestinal Microbiome. *Shokrollahi*, P., +, *TMECH Oct.* 2021 2616-2628
- Diversified and Untethered Motion Generation Via Crease Patterning from Magnetically Actuated Caterpillar-Inspired Origami Robot. *Cai, C.J.*, +, *TMECH June 2021 1678-1688*

Magnetic bearings

- Magnetically Levitated Linear Drive Using an Active Gravity Compensation Based on Hybrid Shape Memory Actuators. *Raab, M.*, +, *TMECH June* 2021 1380-1391
- Magnetically Levitated Linear Stage With Linear Bearingless Slice Hysteresis Motors. Zhou, L., +, TMECH April 2021 1084-1094

Magnetic fields

- Design and Real-Time Optimization for a Magnetic Actuation System With Enhanced Flexibility. *Du*, *X.*, +, *TMECH June 2021 1524-1535*
- Optimal Current Allocation Rendering 3-D Magnetic Force Production in Hexapole Electromagnetic Actuation. *Long, F.*, +, *TMECH Oct. 2021* 2408-2417

Magnetic fluids

Ferrofluidic Manipulator: Automatic Manipulation of Nonmagnetic Microparticles at the Air–Ferrofluid Interface. Cenev, Z., +, TMECH Aug. 2021 1932-1940

Magnetic flux

A Position Sensorless Torque Control Strategy for Switched Reluctance Machines With Fewer Current Sensors. *Gan, C.*, +, *TMECH April 2021* 1118-1128

Magnetic forces

Optimal Current Allocation Rendering 3-D Magnetic Force Production in Hexapole Electromagnetic Actuation. *Long, F., +, TMECH Oct. 2021* 2408-2417

Magnetic hysteresis

Magnetically Levitated Linear Stage With Linear Bearingless Slice Hysteresis Motors. Zhou, L., +, TMECH April 2021 1084-1094

Magnetic levitation

- Analysis of Quasi-Zero Power Characteristic for a Permanent Magnetic Levitation System With a Variable Flux Path Control Mechanism. *Zhao, C.*, +, *TMECH Feb. 2021 437-447*
- Longitudinal Motion Modeling and Experimental Verification of a Microrobot Subject to Liquid Laminar Flow. *Demircali, A.A.*, +, *TMECH Dec.* 2021 2956-2966
- Magnetically Levitated Linear Drive Using an Active Gravity Compensation Based on Hybrid Shape Memory Actuators. *Raab, M.*, +, *TMECH June* 2021 1380-1391
- Magnetically Levitated Linear Stage With Linear Bearingless Slice Hysteresis Motors. Zhou, L., +, TMECH April 2021 1084-1094
- Rotor Balancing for Magnetically Levitated TMPs Integrated With Vibration Self-Sensing of Magnetic Bearings. *Zheng, S.*, +, *TMECH Dec. 2021* 3031-3039
- Static Pull-In Behavior of Hybrid Levitation Microactuators: Simulation, Modeling, and Experimental Study. Poletkin, K.V., TMECH April 2021 753-764

Magnetic particles

- Ferrofluidic Manipulator: Automatic Manipulation of Nonmagnetic Microparticles at the Air–Ferrofluid Interface. *Cenev, Z.*, +, *TMECH Aug. 2021* 1932-1940
- Optimal Current Allocation Rendering 3-D Magnetic Force Production in Hexapole Electromagnetic Actuation. *Long, F.*, +, *TMECH Oct. 2021* 2408-2417

Optimal Design and Implementation of a Novel Two-Dimensional Electromagnetic Navigation System That Allows Focused Heating of Magnetic Nanoparticles. *Le, T.*, +, *TMECH Feb. 2021 551-562*

Magnetic resonance imaging

Autonomous Navigation of Magnetic Microrobots in a Large Workspace Using Mobile-Coil System. Yang, Z., +, TMECH Dec. 2021 3163-3174

Longitudinal Motion Modeling and Experimental Verification of a Microrobot Subject to Liquid Laminar Flow. *Demircali, A.A.*, +, *TMECH Dec.* 2021 2956-2966

Magnetic sensors

Optimal Design and Implementation of a Novel Two-Dimensional Electromagnetic Navigation System That Allows Focused Heating of Magnetic Nanoparticles. Le, T., +, TMECH Feb. 2021 551-562

Magnetic traps

Optimal Current Allocation Rendering 3-D Magnetic Force Production in Hexapole Electromagnetic Actuation. *Long, F.*, +, *TMECH Oct. 2021* 2408-2417

Magnetization

Ferrofluidic Manipulator: Automatic Manipulation of Nonmagnetic Microparticles at the Air–Ferrofluid Interface. Cenev, Z., +, TMECH Aug. 2021 1932-1940

Magnetomechanical effects

Longitudinal Motion Modeling and Experimental Verification of a Microrobot Subject to Liquid Laminar Flow. *Demircali, A.A.*, +, *TMECH Dec.* 2021 2956-2966

Rotor Balancing for Magnetically Levitated TMPs Integrated With Vibration Self-Sensing of Magnetic Bearings. Zheng, S., +, TMECH Dec. 2021 3031-3039

Magnetostrictive devices

Development and Test of a Two-Dimensional Stacked Terfenol-D Actuator With High Bandwidth and Large Stroke. *Chen, L.*, +, *TMECH Aug. 2021* 1951-1959

Maintenance engineering

 Failure Monitoring and Predictive Maintenance of Hydraulic Cylinder— State-of-the-Art Review. Shanbhag, V.V., +, TMECH Dec. 2021 3087-3103
MEMS-Enabled Retrofitting of Automobile Wheel Balancer for Automatic Unbalance Detection. Pozzato, G., +, TMECH April 2021 830-840

Manganese

Estimation of the Electrostatic Effects in the LISA-Pathfinder Critical Test Mass Dynamics via the Method of Moments. *Zanoni, C.*, +, *TMECH Dec.* 2021 3022-3030

Manipulator dynamics

A Hybrid Active and Passive Cable-Driven Segmented Redundant Manipulator: Design, Kinematics, and Planning. *Liu*, *T*, +, *TMECH April 2021* 930-942

- A Lie-Theory-Based Dynamic Parameter Identification Methodology for Serial Manipulators. Fu, Z., +, TMECH Oct. 2021 2688-2699
- A Novel Clustering-Based Algorithm for Solving Spatially Constrained Robotic Task Sequencing Problems. *Wong, C.*, +, *TMECH Oct. 2021 2294-2305*

An Observer-Based Neural Adaptive\$PID^2\$ Controller for Robot Manipulators Including Motor Dynamics With a Prescribed Performance. *Shojaei*, *K.*, +, *TMECH June 2021 1689-1699*

- Coordinated Dynamic Control in the Task Space for Redundantly Actuated Cable-Driven Parallel Robots. Zhang, B., +, TMECH Oct. 2021 2396-2407
- Dynamic Control of Multisection Three-Dimensional Continuum Manipulators Based on Virtual Discrete-Jointed Robot Models. *Wang, C.*, +, *TMECH April 2021 777-788*
- Model-Free Control of Flexible Manipulator Based on Intrinsic Design. Jiang, N., +, TMECH Oct. 2021 2641-2652
- Novel Joint-Drift-Free Scheme at Acceleration Level for Robotic Redundancy Resolution With Tracking Error Theoretically Eliminated. *Jin, L.*, +, *TMECH Feb. 2021 90-101*
- Optimized Interaction Control for Robot Manipulator Interacting With Flexible Environment. *Liu*, X., +, *TMECH Dec.* 2021 2888-2898

Soft Robotic Palm With Tunable Stiffness Using Dual-Layered Particle Jamming Mechanism. Lee, J., +, TMECH Aug. 2021 1820-1827

- Unified Motion/Force/Impedance Control for Manipulators in Unknown Contact Environments Based on Robust Model-Reaching Approach. *Lin*, *Y*, +, *TMECH Aug. 2021 1905-1913*
- Vibration Reduction of Flexible Rope-Driven Mobile Robot for Safe Façade Operation. Seo, M., +, TMECH Aug. 2021 1812-1819
- Whole-Body Control of an Autonomous Mobile Manipulator Using Series Elastic Actuators. *Liu*, *Y*, +, *TMECH April 2021 657-667*

Manipulator kinematics

- A Hybrid Active and Passive Cable-Driven Segmented Redundant Manipulator: Design, Kinematics, and Planning. *Liu*, *T*, +, *TMECH April 2021* 930-942
- A Laser-Guided Solution to Manipulate Mobile Robot Arm Terminals Within a Large Workspace. *Li, F.*, +, *TMECH Oct. 2021 2676-2687*
- A Novel Clustering-Based Algorithm for Solving Spatially Constrained Robotic Task Sequencing Problems. *Wong, C.*, +, *TMECH Oct. 2021 2294-2305*
- Construction of Controller Model of Notch Continuum Manipulator for Laryngeal Surgery Based on Hybrid Method. *Wang, H.*, +, *TMECH April* 2021 1022-1032
- Design and Experimental Validation of a Novel High-Speed Omnidirectional Underwater Propulsion Mechanism. *Njaka, T., +, TMECH Oct. 2021* 2339-2349
- Dynamic Control of Multisection Three-Dimensional Continuum Manipulators Based on Virtual Discrete-Jointed Robot Models. *Wang, C.*, +, *TMECH April 2021 777-788*
- Modified Configuration Control With Potential Field for Inverse Kinematic Solution of Redundant Manipulator. *Kim, J.*, +, *TMECH Aug. 2021 1782-1790*
- On Perpendicular Curve-Based Model-Less Control Considering Incomplete Orientation Constraint. Li, G., +, TMECH June 2021 1479-1489
- Optimization of Generalized S-Curve Trajectories for Residual Vibration Suppression and Compliance With Kinematic Bounds. *Biagiotti, L.*, +, *TMECH Oct. 2021 2724-2734*

Manipulators

- A Circadian Rhythms Neural Network for Solving the Redundant Robot Manipulators Tracking Problem Perturbed by Periodic Noise. *Zhang, Z.*, +, *TMECH Dec. 2021 3232-3242*
- A Fully Actuated Robotic Assistant for MRI-Guided Precision Conformal Ablation of Brain Tumors. *Li*, *G.*, +, *TMECH Feb. 2021 255-266*
- Basic Input–Output Gain Tuning System Based on Control Input Histogram Leveling for Human-Operated Machines. Kamezaki, M., +, TMECH Dec. 2021 2857-2869

Coordinated Dynamic Control in the Task Space for Redundantly Actuated Cable-Driven Parallel Robots. Zhang, B., +, TMECH Oct. 2021 2396-2407

- Design and Validation of a Novel Fuzzy-Logic-Based Static Feedback Controller for Tendon-Driven Continuum Robots. *Ba, W.*, +, *TMECH Dec.* 2021 3010-3021
- Dual Fast Marching Tree Algorithm for Human-Like Motion Planning of Anthropomorphic Arms With Task Constraints. *Xia, J.*, +, *TMECH Oct.* 2021 2803-2813
- Façade Cleaning Robot With Manipulating and Sensing Devices Equipped on a Gondola. Chae, H., +, TMECH Aug. 2021 1719-1727
- Ferrofluidic Manipulator: Automatic Manipulation of Nonmagnetic Microparticles at the Air–Ferrofluid Interface. *Cenev, Z.*, +, *TMECH Aug. 2021* 1932-1940
- Human-in-the-Loop Control of a Wearable Lower Limb Exoskeleton for Stable Dynamic Walking. *Li*, *Z*., +, *TMECH Oct. 2021 2700-2711*
- Proportional-Integral Approximation-Free Control of Robotic Systems With Unknown Dynamics. *Zhang, C., +, TMECH Aug. 2021 2226-2236*
- Regularized Hierarchical Quadratic Program for Real-Time Whole-Body Motion Generation. *Hong, S.*, +, *TMECH Aug. 2021 2115-2126*
- Sea Mining Exploration With an UVMS: Experimental Validation of the Control and Perception Framework. *Simetti, E., +, TMECH June 2021* 1635-1645
- The MUSHA Hand II:A Multifunctional Hand for Robot-Assisted Laparoscopic Surgery. Liu, H., +, TMECH Feb. 2021 393-404

Whole-Body Control of an Autonomous Mobile Manipulator Using Series Elastic Actuators. *Liu*, Y., +, *TMECH April 2021 657-667*

Manufacturing

Data-Driven Iterative Trajectory Shaping for Precision Control of Flexible Feed Drives. *Dumanli, A.*, +, *TMECH Oct. 2021 2735-2746*

Feature Analyses and Modeling of Lithium-Ion Battery Manufacturing Based on Random Forest Classification. *Liu, K.*, +, *TMECH Dec. 2021* 2944-2955

Manufacturing processes

Integral Design and Manufacturing Methodology of a Reduced-Scale Servo Press. Olaizola, J., +, TMECH Oct. 2021 2418-2428

Marine propulsion

Design and Experimental Validation of a Novel High-Speed Omnidirectional Underwater Propulsion Mechanism. *Njaka, T., +, TMECH Oct. 2021* 2339-2349

Marine vehicles

Coordinated Trajectory-Tracking Control of a Marine Aerial-Surface Heterogeneous System. Wang, N., +, TMECH Dec. 2021 3198-3210

Markov processes

Markovian Robust Filtering and Control Applied to Rehabilitation Robotics. Escalante, F.M., +, TMECH Feb. 2021 491-502

Materials science computing

Segmentation-Oriented Compressed Sensing for Efficient Impact Damage Detection on CFRP Materials. *Tang, C., +, TMECH Oct. 2021 2528-2537* Mathematical model

- A Circadian Rhythms Neural Network for Solving the Redundant Robot Manipulators Tracking Problem Perturbed by Periodic Noise. *Zhang, Z.*, +, *TMECH Dec. 2021 3232-3242*
- Accurate Motion Control of a Direct-Drive Hydraulic System With an Adaptive Nonlinear Pump Flow Compensation. *Helian, B.*, +, *TMECH Oct.* 2021 2593-2603
- An Adaptive Fuzzy Trajectory Tracking Control via Improved Cerebellar Model Articulation Controller for Electro-Hydraulic Shovel. *Fan, R.*, +, *TMECH Dec. 2021 2870-2880*
- Constrained Surrogate-Based Engine Calibration Using Lower Confidence Bound. Pal, A., +, TMECH Dec. 2021 3116-3127
- Similitude Analysis Method of the Dynamics of a Hybrid Spray-Painting Robot Considering Electromechanical Coupling Effect. *Song, Y.*, +, *TMECH Dec. 2021 2986-2997*
- Simultaneous State Estimation and Tire Model Learning for Autonomous Vehicle Applications. *Jeon, W.*, +, *TMECH Aug. 2021 1941-1950*

Matrix algebra

- Computationally Improved State-Dependent Riccati Equation Scheme for Nonlinear Benchmark System. *Lin, L., TMECH April 2021 1064-1075*
- Modeling and Adaptive Fault Compensation for Two Physically Linked 2WD Mobile Robots. *Ma*, *Y*, +, *TMECH April 2021 1161-1171*
- Terrain Identification for Humanoid Robots Applying Convolutional Neural Networks. *Venancio, M.M.*, +, *TMECH June 2021 1433-1444*

Mean square error methods

- Closed-Loop Range-Based Control of Dual-Stage Nanopositioning Systems. *Mitrovic, A., +, TMECH June 2021 1412-1421*
- Development and Test of a Two-Dimensional Stacked Terfenol-D Actuator With High Bandwidth and Large Stroke. *Chen, L.*, +, *TMECH Aug. 2021* 1951-1959
- General Discharge Voltage Information Enabled Health Evaluation for Lithium-Ion Batteries. Deng, Z., +, TMECH June 2021 1295-1306
- Robust Adaptive Tracking Control of Underwater Vehicles: Design, Stability Analysis, and Experiments. *Tijjani, A.S.*, +, *TMECH April 2021 897-907*

Measurement errors

- Camera Orientation Optimization in Stereo Vision Systems for Low Measurement Error. *Liu*, *X.*, +, *TMECH April 2021 1178-1182*
- Four-Point Method in the Measurement and Separation of Spindle Rotation Error. *Liu*, *F*, +, *TMECH Feb. 2021 113-123*

Measurement systems

Four-Point Method in the Measurement and Separation of Spindle Rotation Error. Liu, F., +, TMECH Feb. 2021 113-123

Mechanical engineering computing

- An Investigation Into Fault Diagnosis of Planetary Gearboxes Using A Bispectrum Convolutional Neural Network. *Pang, X.*, +, *TMECH Aug.* 2021 2027-2037
- Generative Adversarial Network for Prediction of Workpiece Surface Topography in Machining Stage. Cao, L., +, TMECH Feb. 2021 480-490
- Geometrical-Based Displacement Measurement With Pseudostereo Monocular Camera on Bidirectional Cascaded Linear Actuator. *Lee, D.*, +, *TMECH Aug. 2021 1923-1931*
- Kinematic Modeling, Analysis, and Verification of an Essboard-Like Robot. *Guan, Y.*, +, *TMECH April 2021 864-875*
- Unsupervised Cross-Domain Fault Diagnosis Using Feature Representation Alignment Networks for Rotating Machinery. *Chen, J.*, +, *TMECH Oct.* 2021 2770-2781
- Weighted Entropy Minimization Based Deep Conditional Adversarial Diagnosis Approach Under Variable Working Conditions. She, D., +, TMECH Oct. 2021 2440-2450

Mechanical power transmission

- Guest Editorial: Focused Section on Mechatronics in Road Mobility Systems. Ivanov, V., +, TMECH June 2021 1195-1200
- Integrated Predictive Powertrain Control for a Multimode Plug-in Hybrid Electric Vehicle. *Oncken, J.*, +, *TMECH June 2021 1248-1259*

Mechanical stability

Stability and Sommerfeld Effect of a Vibrating System With Two Vibrators Driven Separately by Induction Motors. *Zhang, X.*, +, *TMECH April 2021* 807-817

Mechanical variables control

A Novel Rotational Actuator With Variable Stiffness Using S-Shaped Springs. Xu, Y., +, TMECH Aug. 2021 2249-2260

Mechatronics

- Accurate Motion Control of a Direct-Drive Hydraulic System With an Adaptive Nonlinear Pump Flow Compensation. *Helian, B.*, +, *TMECH Oct.* 2021 2593-2603
- Compliant Bistable Grippers Enable Passive Perching for Micro Aerial Vehicles. Zhang, H., +, TMECH Oct. 2021 2316-2326
- Control Parameters Design Based on Dynamic Characteristics of a Hybrid Robot With Parallelogram Structures. *Liu, Z.*, +, *TMECH April 2021 1140-1150*
- Exploring the Pareto Fronts of Actuation Technologies for High Performance Mechatronic Systems. Csencsics, E., +, TMECH April 2021 1053-1063
- Focused Section on the Second Edition of TMECH/AIM Emerging Topics. Chen, X., +, TMECH Aug. 2021 1705-1707
- Guest Editorial Focused Section on Mechatronics in Unmanned Systems. *He, W.*, +, *TMECH April 2021 595-599*
- Guest Editorial Introduction to the Focused Section on Mechatronics and Automation for Constructions. *Cheah, C.C.*, +, *TMECH Dec. 2021 2819-*2825
- Guest Editorial: Focused Section on Mechatronics in Road Mobility Systems. *Ivanov, V.*, +, *TMECH June 2021 1195-1200*
- Neurodynamics-Based Model Predictive Control of Continuous-Time Under-Actuated Mechatronic Systems. *Wang, J.*, +, *TMECH Feb. 2021* 311-322
- Prediction-Model-Based Contouring Error Iterative Precompensation Scheme for Precision Multiaxis Motion Systems. *Wang, Z.*, +, *TMECH Oct. 2021 2274-2284*
- Sea Mining Exploration With an UVMS: Experimental Validation of the Control and Perception Framework. *Simetti, E., +, TMECH June 2021* 1635-1645
- Segmentation-Oriented Compressed Sensing for Efficient Impact Damage Detection on CFRP Materials. *Tang, C.*, +, *TMECH Oct. 2021 2528-2537*
- Self-Sensing and Control of Soft Electrothermal Actuator. Cao, Y., +, TMECH April 2021 854-863
- Sensorless Unbalance Diagnosis of Affiliated Rotating Chamber Based on Driving Current of Permanent Magnet Synchronous Motor. *Huo, X.*, +, *TMECH Dec. 2021 2899-2909*
- Swing-Reducing Flight Control System for an Underactuated Indoor Miniature Autonomous Blimp. *Tao*, *Q*., +, *TMECH Aug. 2021 1895-1904*

UltraLow Noise, High Bandwidth, Low Latency, No Overload 6-Axis Optical Force Sensor. *Hosseinabadi, A.H.H.*, +, *TMECH Oct. 2021 2581-2592*

- Medical computing
 - Design and Rapid Construction of a Cost-Effective Virtual Haptic Device. Wang, F., +, TMECH Feb. 2021 66-77
 - Optimal Design and Implementation of a Novel Two-Dimensional Electromagnetic Navigation System That Allows Focused Heating of Magnetic Nanoparticles. *Le, T.,* +, *TMECH Feb. 2021 551-562*
 - The MUSHA Hand II:A Multifunctional Hand for Robot-Assisted Laparoscopic Surgery. Liu, H., +, TMECH Feb. 2021 393-404

Medical control systems

Brain–Machine Interface Using Functional Electrical Stimulation and Motion-Related Cortical Potentials Identified by a Support Vector Machine. *Miura*, S., +, *TMECH April 2021 1013-1021*

Medical image processing

- A Piezoelectric Robotic System for MRI Targeting Assessments of Therapeutics During Dipole Field Navigation. *Shi*, Y., +, *TMECH Feb. 2021* 214-225
- A Tubular Dual-Roller Bending Mechanism Toward Robotic Transurethral Prostate Biopsy. Xiao, X., +, TMECH Oct. 2021 2483-2494
- Automated Retinal Vein Cannulation on Silicone Phantoms Using Optical-Coherence-Tomography-Guided Robotic Manipulations. Gerber, M.J., +, TMECH Oct. 2021 2758-2769
- Image Processing Metrics for Phase Identification of a Multiaxis MEMS Scanner Used in Single Pixel Imaging. *Birla, M.*, +, *TMECH June 2021* 1445-1454
- Investigation of Micromotion Kinematics of Continuum Robots for Volumetric OCT and OCT-Guided Visual Servoing. *Giudice, G.D.*, +, *TMECH* Oct. 2021 2604-2615

Medical robotics

- A Compact Ankle Exoskeleton With a Multiaxis Parallel Linkage Mechanism. Lee, M., +, TMECH Feb. 2021 191-202
- A Fully Actuated Robotic Assistant for MRI-Guided Precision Conformal Ablation of Brain Tumors. *Li*, *G.*, +, *TMECH Feb. 2021 255-266*
- A New Ankle Robotic System Enabling Whole-Stage Compliance Rehabilitation Training. Dong, M., +, TMECH June 2021 1490-1500
- A Suction-Based Peripheral Nerve Gripper Capable of Controlling the Suction Force. Jang, N., +, TMECH Aug. 2021 1867-1876
- A Surgical Robotic System for Treatment of Pelvic Osteolysis Using an FBG-Equipped Continuum Manipulator and Flexible Instruments. *Sefati, S.*, +, *TMECH Feb.* 2021 369-380
- A Tubular Dual-Roller Bending Mechanism Toward Robotic Transurethral Prostate Biopsy. *Xiao, X.*, +, *TMECH Oct. 2021 2483-2494*
- Active Disturbance Rejection Control for a Fluid-Driven Hand Rehabilitation Device. *Li*, *H.*, +, *TMECH April 2021 841-853*
- Automated Retinal Vein Cannulation on Silicone Phantoms Using Optical-Coherence-Tomography-Guided Robotic Manipulations. Gerber, M.J., +, TMECH Oct. 2021 2758-2769
- Blindly Controlled Magnetically Actuated Capsule for Noninvasive Sampling of the Gastrointestinal Microbiome. *Shokrollahi*, P., +, *TMECH Oct.* 2021 2616-2628
- Brain–Machine Interface Using Functional Electrical Stimulation and Motion-Related Cortical Potentials Identified by a Support Vector Machine. *Miura*, S., +, *TMECH April 2021 1013-1021*
- Construction of Controller Model of Notch Continuum Manipulator for Laryngeal Surgery Based on Hybrid Method. *Wang, H.*, +, *TMECH April* 2021 1022-1032
- Design and Experimental Validation of a Miniaturized Robotic Tendon-Driven Articulated Surgical Drill for Enhancing Distal Dexterity in Minimally Invasive Spine Fusion. Wang. Y., +, TMECH Aug. 2021 1858-1866
- Design and Rapid Construction of a Cost-Effective Virtual Haptic Device. Wang, F., +, TMECH Feb. 2021 66-77
- Design Principles for Compact, Backdrivable Actuation in Partial-Assist Powered Knee Orthoses. Zhu, H., +, TMECH Dec. 2021 3104-3115
- Focused Section on the Second Edition of TMECH/AIM Emerging Topics. Chen, X., +, TMECH Aug. 2021 1705-1707

- Human–Robot Cooperation Control Based on Trajectory Deformation Algorithm for a Lower Limb Rehabilitation Robot. *Zhou, J.*, +, *TMECH Dec.* 2021 3128-3138
- Human-in-the-Loop Control of a Wearable Lower Limb Exoskeleton for Stable Dynamic Walking. Li, Z., +, TMECH Oct. 2021 2700-2711
- Investigation of Micromotion Kinematics of Continuum Robots for Volumetric OCT and OCT-Guided Visual Servoing. *Giudice, G.D.*, +, *TMECH Oct.* 2021 2604-2615
- Locomotion Analysis of a Clamper-Based Capsule Robot in a Compliant Tube. *Gao*, J., +, *TMECH Feb. 2021 55-65*
- Low Impedance-Guaranteed Gain-Scheduled GESO for Torque-Controlled VSA With Application of Exoskeleton-Assisted Sit-to-Stand. *Liu, L.*, +, *TMECH Aug. 2021 2080-2091*
- Markovian Robust Filtering and Control Applied to Rehabilitation Robotics. Escalante, F.M., +, TMECH Feb. 2021 491-502
- Measurement of Peristaltic Forces Exerted by Living Intestine on Robotic Capsule. Rehan, M., +, TMECH Aug. 2021 1803-1811
- Mech-Walker: A Novel Single-DOF Linkage Device With Movable Frame for Gait Rehabilitation. *Haghjoo*, *M.R.*, +, *TMECH Feb. 2021 13-23*
- Mechanical Aspects of Robot Hands, Active Hand Orthoses, and Prostheses: A Comparative Review. *Vertongen, J.*, +, *TMECH April 2021 955-965*
- Mechanism and Controller Design of a Transfemoral Prosthesis With Electrohydraulic Knee and Motor-Driven Ankle. *Gao, S.*, +, *TMECH Oct. 2021* 2429-2439
- Needle Deflection Modeling and Preoperative Trajectory Planning During Insertion Into Multilayered Tissues. *Zhao, B., +, TMECH April 2021 943-954*
- Robotized Catheter With Enhanced Distal Targeting for Peripheral Pulmonary Biopsy. Kato, T., +, TMECH Oct. 2021 2451-2461
- Stochastic Force-Based Insertion Depth and Tip Position Estimations of Flexible FBG-Equipped Instruments in Robotic Retinal Surgery. *Ebrahimi*, A., +, *TMECH June 2021 1512-1523*
- The MUSHA Hand II:A Multifunctional Hand for Robot-Assisted Laparoscopic Surgery. Liu, H., +, TMECH Feb. 2021 393-404
- Vision-Based Cutting Control of Deformable Objects With Surface Tracking. Han, L., +, TMECH Aug. 2021 2016-2026
- Wearable Knee Assistive Devices for Kneeling Tasks in Construction. *Chen*, *S.*, +, *TMECH Aug. 2021 1989-1996*
- Medical signal processing
 - An Electrical Impedance Tomography Based Interface for Human–Robot Collaboration. Zheng, E., +, TMECH Oct. 2021 2373-2384
 - Brain–Machine Interface Using Functional Electrical Stimulation and Motion-Related Cortical Potentials Identified by a Support Vector Machine. *Miura*, S., +, *TMECH April 2021 1013-1021*

On-Body RF Sensor Toward Tremor Detection in Parkinson's Disease. Abirami B, S., +, TMECH Oct. 2021 2814-2817

Mel frequency cepstral coefficient

Weakly Supervised Acoustic Defect Detection in Concrete Structures Using Clustering-Based Augmentation. Kasahara, J.Y.L., +, TMECH Dec. 2021 2826-2834

Melting

- Electrical Parameter Identification of Medium-Frequency DC Resistance Spot Welding System Using Intelligent Algorithm. *Wang, X.*, +, *TMECH Aug. 2021 1791-1802*
- Localized Property Design and Gradient Processing of a Hydraulic Valve Body Using Selective Laser Melting. *Zhu, Y.*, +, *TMECH April 2021 1151-1160*

Membranes

Modeling and Analysis of Soft Pneumatic Network Bending Actuators. *Liu*, *Z*., +, *TMECH Aug. 2021 2195-2203*

Mesh generation

- A Delaunay Triangulation-Based Matching Area Selection Algorithm for Underwater Gravity-Aided Inertial Navigation. Wang, C., +, TMECH April 2021 908-917
- Toward Safe and Personalized Autonomous Driving: Decision-Making and Motion Control With DPF and CDT Techniques. *Huang, C.*, +, *TMECH April 2021 611-620*

Generative Adversarial Network for Prediction of Workpiece Surface Topography in Machining Stage. *Cao, L.*, +, *TMECH Feb. 2021 480-490* Method of moments

Estimation of the Electrostatic Effects in the LISA-Pathfinder Critical Test Mass Dynamics via the Method of Moments. Zanoni, C., +, TMECH Dec. 2021 3022-3030

Micro-optomechanical devices

Self-Sensing and Control of Soft Electrothermal Actuator. Cao, Y, +, TMECH April 2021 854-863

Microactuators

A Monolithic Force Sensing Integrated Flexure Bonder Dedicated to Flip-Chip Active Soft-Landing Interconnection. *Tang, H.*, +, *TMECH Feb.* 2021 323-334

- Self-Sensing and Control of Soft Electrothermal Actuator. Cao, Y, +, TMECH April 2021 854-863
- Static Pull-In Behavior of Hybrid Levitation Microactuators: Simulation, Modeling, and Experimental Study. Poletkin, K.V., TMECH April 2021 753-764

Microchannel flow

Flux-Biased, Energy-Efficient Electromagnetic Micropumps Utilizing Bistable Magnetic Latching and Energy-Storage Springs. *Bhushan*, B.M., +, TMECH Oct. 2021 2362-2372

Microfabrication

Ultraviolet Beam Lithography System for Digital Fabrication of Roller Molds. Yang, S., +, TMECH Feb. 2021 226-234

Microlenses

Ultraviolet Beam Lithography System for Digital Fabrication of Roller Molds. Yang, S., +, TMECH Feb. 2021 226-234

Micromagnetics

Autonomous Navigation of Magnetic Microrobots in a Large Workspace Using Mobile-Coil System. Yang, Z., +, TMECH Dec. 2021 3163-3174

Micromanipulators

A Monolithic Force Sensing Integrated Flexure Bonder Dedicated to Flip-Chip Active Soft-Landing Interconnection. *Tang, H.*, +, *TMECH Feb.* 2021 323-334

Robotic Prototyping of Paper-Based Field-Effect Transistors With Rolled-Up Semiconductor Microtubes. Dong, X., +, TMECH Feb. 2021 427-436

Micromechanical devices

- Image Processing Metrics for Phase Identification of a Multiaxis MEMS Scanner Used in Single Pixel Imaging. *Birla, M.*, +, *TMECH June 2021* 1445-1454
- Iterative Learning Control for Video-Rate Atomic Force Microscopy. Nikooienejad, N., +, TMECH Aug. 2021 2127-2138

Micromirrors

Self-Sensing and Control of Soft Electrothermal Actuator. Cao, Y., +, TMECH April 2021 854-863

Ultraviolet Beam Lithography System for Digital Fabrication of Roller Molds. Yang, S., +, TMECH Feb. 2021 226-234

Micromotors

A Piezoelectric Microultrasonic Motor With High Q and Good Mode Match. Zhou, W., +, TMECH Aug. 2021 1773-1781

Microorganisms

Blindly Controlled Magnetically Actuated Capsule for Noninvasive Sampling of the Gastrointestinal Microbiome. *Shokrollahi*, P., +, *TMECH Oct.* 2021 2616-2628

Micropumps

Flux-Biased, Energy-Efficient Electromagnetic Micropumps Utilizing Bistable Magnetic Latching and Energy-Storage Springs. *Bhushan, B.M.*, +, *TMECH Oct. 2021 2362-2372*

Microrobots

- A Binary Tree Based Coordination Scheme for Target Enclosing With Micro Aerial Vehicles. *Duan, H.*, +, *TMECH Feb. 2021 458-468*
- Design and Real-Time Optimization for a Magnetic Actuation System With Enhanced Flexibility. *Du*, *X.*, +, *TMECH June 2021 1524-1535*
- Diversified and Untethered Motion Generation Via Crease Patterning from Magnetically Actuated Caterpillar-Inspired Origami Robot. Cai, C.J., +, TMECH June 2021 1678-1688

Locomotion Analysis of a Clamper-Based Capsule Robot in a Compliant Tube. *Gao*, J., +, *TMECH Feb. 2021 55-65*

Microsensors

Design and Testing of a New Force-Sensing Cell Microinjector Based on Small-Stiffness Compliant Mechanism. *Wei, Y.*, +, *TMECH April 2021* 818-829

Microwave imaging

Segmentation-Oriented Compressed Sensing for Efficient Impact Damage Detection on CFRP Materials. *Tang, C.*, +, *TMECH Oct. 2021 2528-2537* Military aircraft

An Efficient Design Solution for a Low-Cost High-G Centrifuge System. Mohajer, N., +, TMECH Feb. 2021 134-145

MIMO systems

A Generalized Design Method for Learning-Based Disturbance Observer. Zheng, M., +, TMECH Feb. 2021 45-54

Minimization

- A Generalized Design Method for Learning-Based Disturbance Observer. Zheng, M., +, TMECH Feb. 2021 45-54
- Investigation of Micromotion Kinematics of Continuum Robots for Volumetric OCT and OCT-Guided Visual Servoing. *Giudice, G.D.*, +, *TMECH Oct.* 2021 2604-2615

Weighted Entropy Minimization Based Deep Conditional Adversarial Diagnosis Approach Under Variable Working Conditions. She, D., +, TMECH Oct. 2021 2440-2450

Mining

Sea Mining Exploration With an UVMS: Experimental Validation of the Control and Perception Framework. *Simetti, E., +, TMECH June 2021* 1635-1645

Mirrors

Exploring the Pareto Fronts of Actuation Technologies for High Performance Mechatronic Systems. *Csencsics, E.*, +, *TMECH April 2021 1053-1063*

Missile guidance

Development of a Small and Lightweight Missile Fin Control Actuation System Driven by Novel Dielectric Elastomer Actuators. *Jung, H.S.*, +, *TMECH April 2021 1002-1012*

Mobile robots

- A Binary Tree Based Coordination Scheme for Target Enclosing With Micro Aerial Vehicles. *Duan, H.,* +, *TMECH Feb. 2021 458-468*
- A Hybrid Active and Passive Cable-Driven Segmented Redundant Manipulator: Design, Kinematics, and Planning. *Liu*, *T.*, +, *TMECH April 2021* 930-942
- A Laser-Guided Solution to Manipulate Mobile Robot Arm Terminals Within a Large Workspace. *Li*, *F*., +, *TMECH Oct. 2021 2676-2687*
- A Novel Cable-Driven 7-DOF Anthropomorphic Manipulator. *Huang, Y.*, +, *TMECH Aug. 2021 2174-2185*
- A Novel Clustering-Based Algorithm for Solving Spatially Constrained Robotic Task Sequencing Problems. *Wong, C., +, TMECH Oct. 2021 2294-2305*
- A Tilting-Rotor Unmanned Aerial Vehicle for Enhanced Aerial Locomotion and Manipulation Capabilities: Design, Control, and Applications. *Ding, C.*, +, *TMECH Aug. 2021 2237-2248*
- Amaran: An Unmanned Robotic Coconut Tree Climber and Harvester. Megalingam, R.K., +, TMECH Feb. 2021 288-299
- An Active Sense and Avoid System for Flying Robots in Dynamic Environments. Chen, G., +, TMECH April 2021 668-678
- An Integrated Terrain Identification Framework for Mobile Robots: System Development, Analysis, and Verification. Zeng, R., +, TMECH June 2021 1581-1590
- An Output Feedback Based Robust Saturated Controller Design for Pavement Sweeping Self-Reconfigurable Robot. *Rayguru, M.M.*, +, *TMECH June 2021 1236-1247*
- Autonomous Vision-Guided Object Collection From Water Surfaces With a Customized Multirotor. *Mishra*, S., +, *TMECH Aug*. 2021 1914-1922
- Blindly Controlled Magnetically Actuated Capsule for Noninvasive Sampling of the Gastrointestinal Microbiome. *Shokrollahi, P., +, TMECH Oct.* 2021 2616-2628
- Collaborative Semantic Understanding and Mapping Framework for Autonomous Systems. Yue, Y., +, TMECH April 2021 978-989

- Compliant Bistable Grippers Enable Passive Perching for Micro Aerial Vehicles. Zhang, H., +, TMECH Oct. 2021 2316-2326
- Curvature-Induced Buckling for Flapping-Wing Vehicles. Sharifzadeh, M., +, TMECH Feb. 2021 503-514
- Design and Experimental Validation of a Novel High-Speed Omnidirectional Underwater Propulsion Mechanism. *Njaka, T., +, TMECH Oct. 2021* 2339-2349
- Design and Real-Time Optimization for a Magnetic Actuation System With Enhanced Flexibility. *Du*, *X.*, +, *TMECH June 2021 1524-1535*
- Development and Performance Enhancement of an Overactuated Autonomous Ground Vehicle. *Huang, Y., +, TMECH Feb. 2021 33-44*
- Dimensionless Model-Based System Tracking Via Augmented Kalman Filter for Multiscale Unmanned Ground Vehicles. *Sun, C.*, +, *TMECH April* 2021 600-610
- Distributed Formation Control Using Fuzzy Self-Tuning of Strictly Negative Imaginary Consensus Controllers in Aerial Robotics. *Tran, V.P.*, +, *TMECH Oct. 2021 2306-2315*
- Diversified and Untethered Motion Generation Via Crease Patterning from Magnetically Actuated Caterpillar-Inspired Origami Robot. Cai, C.J., +, TMECH June 2021 1678-1688
- Efficient Bathymetric SLAM With Invalid Loop Closure Identification. Teng, M., +, TMECH Oct. 2021 2570-2580
- Efficient Cooperative Structured Control for a Multijoint Biomimetic Robotic Fish. Yan, S., +, TMECH Oct. 2021 2506-2516
- Evaluation of Locomotion Performances for a Mecanum-Wheeled Hybrid Hexapod Robot. Orozco-Magdaleno, E.C., +, TMECH June 2021 1657-1667
- Façade Cleaning Robot With Manipulating and Sensing Devices Equipped on a Gondola. Chae, H., +, TMECH Aug. 2021 1719-1727
- Formation Reconstruction and Trajectory Replanning for Multi-UAV Patrol. Wang, Y., +, TMECH April 2021 719-729
- Fully Actuated Autonomous Flight of Thruster-Tilting Multirotor. Lee, S.J., +, TMECH April 2021 765-776
- Fully Distributed Cooperative Circumnavigation of Networked Unmanned Aerial Vehicles. *Li*, *D.*, +, *TMECH April 2021 709-718*
- Human-in-the-Loop Control of a Wearable Lower Limb Exoskeleton for Stable Dynamic Walking. *Li*, *Z*., +, *TMECH Oct. 2021 2700-2711*
- Kinematic Modeling, Analysis, and Verification of an Essboard-Like Robot. *Guan, Y.*, +, *TMECH April 2021 864-875*
- Locomotion Analysis of a Clamper-Based Capsule Robot in a Compliant Tube. Gao, J., +, TMECH Feb. 2021 55-65
- Loop-Closure Detection With a Multiresolution Point Cloud Histogram Mode in Lidar Odometry and Mapping for Intelligent Vehicles. *Meng, Q.*, +, *TMECH June 2021 1307-1317*
- MEMS-Enabled Retrofitting of Automobile Wheel Balancer for Automatic Unbalance Detection. *Pozzato, G.,* +, *TMECH April 2021 830-840*
- Modeling and Adaptive Fault Compensation for Two Physically Linked 2WD Mobile Robots. *Ma*, *Y*., +, *TMECH April 2021 1161-1171*
- Modeling and Motion Control of Industrial Tractor–Trailers Vehicles Using Force Compensation. Zhao, H., +, TMECH April 2021 645-656
- Modified Configuration Control With Potential Field for Inverse Kinematic Solution of Redundant Manipulator. *Kim, J.*, +, *TMECH Aug. 2021 1782-1790*
- Multiobjective Scheduling Strategy With Genetic Algorithm and Time-Enhanced A* Planning for Autonomous Parking Robotics in High-Density Unmanned Parking Lots. *Chen, G.,* +, *TMECH June 2021 1547-1557*
- Neurodynamics-Based Model Predictive Control of Continuous-Time Under-Actuated Mechatronic Systems. *Wang, J.*, +, *TMECH Feb. 2021* 311-322
- Path Following of Wheeled Mobile Robots Using Online-Optimization-Based Guidance Vector Field. *Chen, J.*, +, *TMECH Aug. 2021 1737-1744*
- Point Stabilization of Nonholonomic Mobile Robot by Bézier Smooth Subline Constraint Nonlinear Model Predictive Control. *Zhang, Y.*, +, *TMECH April 2021 990-1001*
- Proportional-Integral Approximation-Free Control of Robotic Systems With Unknown Dynamics. Zhang, C., +, TMECH Aug. 2021 2226-2236

- Real-Time Avoidance Strategy of Dynamic Obstacles via Half Model-Free Detection and Tracking With 2D Lidar for Mobile Robots. *Dong, H.*, +, *TMECH Aug. 2021 2215-2225*
- Robust Concurrent Design of a 2-DOF Collaborative Robot (Cobot). Mendoza-Trejo, O., +, TMECH Feb. 2021 347-357
- Self-Balancing Two-Wheeled Robot Featuring Intelligent End-to-End Deep Visual-Steering. *Li, C.G.*, +, *TMECH Oct. 2021 2263-2273*
- Sliding-Mode-Disturbance-Observer-Based Robust Tracking Control for Omnidirectional Mobile Robots With Kinematic and Dynamic Uncertainties. *Jeong, S.*, +, *TMECH April 2021 741-752*
- Swing-Reducing Flight Control System for an Underactuated Indoor Miniature Autonomous Blimp. *Tao*, Q., +, *TMECH Aug. 2021 1895-1904*
- Takagi–Sugeno Fuzzy-Based Robust $H\infty$ Integrated Lane-Keeping and Direct Yaw Moment Controller of Unmanned Electric Vehicles. *Guo*, *J.*, +, *TMECH Aug. 2021 2151-2162*
- Topology Optimization of Skeleton-Reinforced Soft Pneumatic Actuators for Desired Motions. Chen, S., +, TMECH Aug. 2021 1745-1753
- Toward Safe and Personalized Autonomous Driving: Decision-Making and Motion Control With DPF and CDT Techniques. *Huang, C.*, +, *TMECH April 2021 611-620*
- Vibration Reduction of Flexible Rope-Driven Mobile Robot for Safe Façade Operation. Seo, M., +, TMECH Aug. 2021 1812-1819
- Virtual Landmark-Based Control of Docking Support for Assistive Mobility Devices. Chen, Y., +, TMECH Aug. 2021 2007-2015
- Whole-Body Control of an Autonomous Mobile Manipulator Using Series Elastic Actuators. *Liu*, *Y*, +, *TMECH April 2021 657-667*

Modal analysis

A Piezoelectric Microultrasonic Motor With High Q and Good Mode Match. Zhou, W., +, TMECH Aug. 2021 1773-1781

Modeling

Modeling of One-Ply and Two-Ply Twisted and Coiled Polymer Artificial Muscles. *Karami, F.*, +, *TMECH Feb. 2021 300-310*

Molecular biophysics

Blindly Controlled Magnetically Actuated Capsule for Noninvasive Sampling of the Gastrointestinal Microbiome. *Shokrollahi*, P., +, *TMECH Oct.* 2021 2616-2628

Monte Carlo methods

Global Parameter Sensitivity Analysis of Electrochemical Model for Lithium-Ion Batteries Considering Aging. *Gao, Y.*, +, *TMECH June 2021 1283-1294*

Motion compensation

Loop-Closure Detection With a Multiresolution Point Cloud Histogram Mode in Lidar Odometry and Mapping for Intelligent Vehicles. *Meng*, *Q*., +, *TMECH June 2021 1307-1317*

Motion control

- A Hybrid Active and Passive Cable-Driven Segmented Redundant Manipulator: Design, Kinematics, and Planning. *Liu*, *T*., +, *TMECH April 2021* 930-942
- A Novel Cable-Driven 7-DOF Anthropomorphic Manipulator. *Huang, Y.*, +, *TMECH Aug. 2021 2174-2185*
- A Tilting-Rotor Unmanned Aerial Vehicle for Enhanced Aerial Locomotion and Manipulation Capabilities: Design, Control, and Applications. *Ding, C.*, +, *TMECH Aug. 2021 2237-2248*
- Accurate Motion Control of a Direct-Drive Hydraulic System With an Adaptive Nonlinear Pump Flow Compensation. *Helian, B.*, +, *TMECH Oct.* 2021 2593-2603
- Analytical Design and Experimental Verification of Geofencing Control for Aerial Applications. *Ghaffari, A., TMECH April 2021 1106-1117*
- Biomimetic Realization of a Robotic Penguin Wing: Design and Thrust Characteristics. Shen, Y., +, TMECH Oct. 2021 2350-2361
- Characterization of a Packaged Triboelectric Harvester Under Simulated Gait Loading for Total Knee Replacement. *Hossain, N.A.*, +, *TMECH Dec.* 2021 2967-2976
- Compliant Bistable Grippers Enable Passive Perching for Micro Aerial Vehicles. *Zhang, H.,* +, *TMECH Oct. 2021 2316-2326*
- Coordinated Dynamic Control in the Task Space for Redundantly Actuated Cable-Driven Parallel Robots. Zhang, B., +, TMECH Oct. 2021 2396-2407

- Cyber–Physical Codesign of Field-Level Reconfigurations in Networked Motion Controllers. *Zhou*, *N*., +, *TMECH Aug*. 2021 2092-2103
- Development of a Nanopositioning Platform With Large Travel Range Based on Bionic Quadruped Piezoelectric Actuator. *Deng, J.*, +, *TMECH Aug. 2021 2059-2070*
- Development of a Small and Lightweight Missile Fin Control Actuation System Driven by Novel Dielectric Elastomer Actuators. *Jung, H.S.*, +, *TMECH April 2021 1002-1012*
- Development of Embedded Sensor System for 5-DOF Finger-Wearable Tactile Interface. *Lim, B., +, TMECH Aug. 2021 1728-1736*
- Diversified and Untethered Motion Generation Via Crease Patterning from Magnetically Actuated Caterpillar-Inspired Origami Robot. Cai, C.J., +, TMECH June 2021 1678-1688
- Dynamic Torso Compliance Control for Standing and Walking Balance of Position-Controlled Humanoid Robots. *Li*, *Q*., +, *TMECH April 2021 679-688*
- Efficient Cooperative Structured Control for a Multijoint Biomimetic Robotic Fish. Yan, S., +, TMECH Oct. 2021 2506-2516
- Efficient Motion Planning Based on Kinodynamic Model for Quadruped Robots Following Persons in Confined Spaces. *Zhang, Z.*, +, *TMECH Aug.* 2021 1997-2006
- Evaluation of Locomotion Performances for a Mecanum-Wheeled Hybrid Hexapod Robot. Orozco-Magdaleno, E.C., +, TMECH June 2021 1657-1667
- Formation Reconstruction and Trajectory Replanning for Multi-UAV Patrol. *Wang*, Y., +, *TMECH April 2021 719-729*
- Fully Actuated Autonomous Flight of Thruster-Tilting Multirotor. Lee, S.J., +, TMECH April 2021 765-776
- Fully Distributed Cooperative Circumnavigation of Networked Unmanned Aerial Vehicles. Li, D., +, TMECH April 2021 709-718
- Human-in-the-Loop Control of a Wearable Lower Limb Exoskeleton for Stable Dynamic Walking. *Li*, *Z*., +, *TMECH Oct. 2021 2700-2711*
- Hybrid Control Strategy for Force and Precise End Effector Positioning of a Twisted String Actuator. Rodriguez, A.S., +, TMECH Oct. 2021 2791-2802
- Individual Auxiliary and Fault-Tolerant Control of Steer-by-Wire System Considering Different Drivers Steering Characteristics. *Zhao, W.*, +, *TMECH June 2021 1558-1569*
- Locomotion Analysis of a Clamper-Based Capsule Robot in a Compliant Tube. Gao, J., +, TMECH Feb. 2021 55-65
- Longitudinal Motion Modeling and Experimental Verification of a Microrobot Subject to Liquid Laminar Flow. Demircali, A.A., +, TMECH Dec. 2021 2956-2966
- Magnetically Levitated Linear Drive Using an Active Gravity Compensation Based on Hybrid Shape Memory Actuators. *Raab, M.*, +, *TMECH June* 2021 1380-1391
- Modeling and Motion Control of Industrial Tractor–Trailers Vehicles Using Force Compensation. Zhao, H., +, TMECH April 2021 645-656
- Nonlinear Model Predictive Control for Integrated Energy-Efficient Torque-Vectoring and Anti-Roll Moment Distribution. *Dalboni, M.*, +, *TMECH June 2021 1212-1224*
- Nonprehensile Manipulation: A Trajectory-Planning Perspective. Acharya, P., +, TMECH Feb. 2021 527-538
- On Perpendicular Curve-Based Model-Less Control Considering Incomplete Orientation Constraint. Li, G., +, TMECH June 2021 1479-1489
- Online Delayed Reference Generation for a Humanoid Imitating Human Walking Motion. *Oh, J.*, +, *TMECH Feb. 2021 102-112*
- Planning Three-Dimensional Collision-Free Optimized Climbing Path for Biped Wall-Climbing Robots. *Zhu, H.*, +, *TMECH Oct. 2021 2712-2723*
- Proportional-Integral Approximation-Free Control of Robotic Systems With Unknown Dynamics. *Zhang, C.,* +, *TMECH Aug. 2021 2226-2236*
- Robust Concurrent Design of a 2-DOF Collaborative Robot (Cobot). Mendoza-Trejo, O., +, TMECH Feb. 2021 347-357
- Roller-Skating of Mammalian Quadrupedal Robot With Passive Wheels Inspired by Human. *Chen*, J., +, *TMECH June 2021 1624-1634*

Sensor-Fault-Tolerant Operation for the Independent Metering Control System. *Ding*, *R.*, +, *TMECH Oct.* 2021 2558-2569

- Sliding Mode Control With Model-Based Switching Functions Applied on a 7-DOF Exoskeleton Arm. *Fallaha*, C., +, *TMECH Feb. 2021 539-550*
- Stability and Robustness of the Disturbance Observer-Based Motion Control Systems in Discrete-Time Domain. *Sariyildiz, E., +, TMECH Aug. 2021* 2139-2150
- Swing-Reducing Flight Control System for an Underactuated Indoor Miniature Autonomous Blimp. *Tao*, Q., +, *TMECH Aug*. 2021 1895-1904
- Takagi–Sugeno Fuzzy-Based Robust $H\infty$ Integrated Lane-Keeping and Direct Yaw Moment Controller of Unmanned Electric Vehicles. *Guo*, *J.*, +, *TMECH Aug. 2021 2151-2162*
- Toward Safe and Personalized Autonomous Driving: Decision-Making and Motion Control With DPF and CDT Techniques. *Huang, C.*, +, *TMECH April 2021 611-620*
- Unified Motion/Force/Impedance Control for Manipulators in Unknown Contact Environments Based on Robust Model-Reaching Approach. *Lin*, *Y*, +, *TMECH Aug. 2021 1905-1913*
- Vision-Based Cutting Control of Deformable Objects With Surface Tracking. Han, L., +, TMECH Aug. 2021 2016-2026

Motion measurement

- An Automated AFM Tip-Replacement System for *In Situ* Tip-Replacement. *Vikrant, K.S.*, +, *TMECH April 2021 798-806*
- Motion planning
 - Focused Section on the Second Edition of TMECH/AIM Emerging Topics. Chen, X., +, TMECH Aug. 2021 1705-1707

Motion segmentation

Reconstructing Walking Dynamics From Two Shank-Mounted Inertial Measurement Units. Li, T., +, TMECH Dec. 2021 3040-3050

Motion sensors

An Automated AFM Tip-Replacement System for *In Situ* Tip-Replacement. *Vikrant, K.S.*, +, *TMECH April 2021 798-806*

Motorcycles

- Kinematic Modeling, Analysis, and Verification of an Essboard-Like Robot. *Guan, Y.*, +, *TMECH April 2021 864-875*
- Multi-agent systems
- Learning Communication for Cooperation in Dynamic Agent-Number Environment. *Liu, W.*, +, *TMECH Aug. 2021 1846-1857*

Multi-robot systems

- A Binary Tree Based Coordination Scheme for Target Enclosing With Micro Aerial Vehicles. *Duan, H.*, +, *TMECH Feb. 2021 458-468*
- Collaborative Semantic Understanding and Mapping Framework for Autonomous Systems. Yue, Y., +, TMECH April 2021 978-989
- Design and Real-Time Optimization for a Magnetic Actuation System With Enhanced Flexibility. *Du*, *X*., +, *TMECH June 2021 1524-1535*
- Distributed Formation Control Using Fuzzy Self-Tuning of Strictly Negative Imaginary Consensus Controllers in Aerial Robotics. *Tran, V.P.*, +, *TMECH Oct. 2021 2306-2315*
- Formation Reconstruction and Trajectory Replanning for Multi-UAV Patrol. *Wang, Y., +, TMECH April 2021 719-729*
- Fully Distributed Cooperative Circumnavigation of Networked Unmanned Aerial Vehicles. *Li*, *D.*, +, *TMECH April 2021 709-718*
- Multiobjective Scheduling Strategy With Genetic Algorithm and Time-Enhanced A* Planning for Autonomous Parking Robotics in High-Density Unmanned Parking Lots. *Chen, G.,* +, *TMECH June 2021 1547-1557*
- Terrain Identification for Humanoid Robots Applying Convolutional Neural Networks. *Venancio, M.M.*, +, *TMECH June 2021 1433-1444*

Multi-stage noise shaping

Coordinated Trajectory-Tracking Control of a Marine Aerial-Surface Heterogeneous System. Wang, N., +, TMECH Dec. 2021 3198-3210

Muscle

- A New Ankle Robotic System Enabling Whole-Stage Compliance Rehabilitation Training. *Dong, M.*, +, *TMECH June 2021 1490-1500*
- Design and Characterization of a Bellows-Driven Soft Pneumatic Actuator. *Hashem, R.*, +, *TMECH Oct. 2021 2327-2338*
- Dual Fast Marching Tree Algorithm for Human-Like Motion Planning of Anthropomorphic Arms With Task Constraints. *Xia, J.*, +, *TMECH Oct.* 2021 2803-2813

- Modified Stiffness-Based Soft Optical Waveguide Integrated Pneumatic Artificial Muscle (PAM) Actuators for Contraction and Force Sensing. *Jamil, B.*, +, *TMECH Dec. 2021 3243-3253*
- Wearable Knee Assistive Devices for Kneeling Tasks in Construction. Chen, S., +, TMECH Aug. 2021 1989-1996

N

NAND circuits

A Lightweight Wireless Overpressure Node Based Efficient Monitoring for Shock Waves. Gao, S., +, TMECH Feb. 2021 448-457

Nanomagnetics

Optimal Design and Implementation of a Novel Two-Dimensional Electromagnetic Navigation System That Allows Focused Heating of Magnetic Nanoparticles. *Le, T.,* +, *TMECH Feb. 2021 551-562*

Nanomedicine

Optimal Design and Implementation of a Novel Two-Dimensional Electromagnetic Navigation System That Allows Focused Heating of Magnetic Nanoparticles. *Le, T.,* +, *TMECH Feb. 2021 551-562*

Nanoparticles

Optimal Design and Implementation of a Novel Two-Dimensional Electromagnetic Navigation System That Allows Focused Heating of Magnetic Nanoparticles. *Le, T.,* +, *TMECH Feb. 2021 551-562*

Nanopositioning

A Smoothed Raster Scanning Trajectory Based on Acceleration-Continuous B-Spline Transition for High-Speed Atomic Force Microscopy. *Li*, *L*., +, *TMECH Feb. 2021 24-32*

- Closed-Loop Range-Based Control of Dual-Stage Nanopositioning Systems. *Mitrovic, A., +, TMECH June 2021 1412-1421*
- Development of a Nanopositioning Platform With Large Travel Range Based on Bionic Quadruped Piezoelectric Actuator. *Deng, J.*, +, *TMECH Aug.* 2021 2059-2070
- Iterative Learning Control for Video-Rate Atomic Force Microscopy. Nikooienejad, N., +, TMECH Aug. 2021 2127-2138
- Time/Space-Separation-Based Gaussian Process Modeling for the Cross-Coupling Effect of a 2-DOF Nanopositioning Stage. *Tao, Y.*, +, *TMECH Aug. 2021 2186-2194*

Nanotechnology

Time/Space-Separation-Based Gaussian Process Modeling for the Cross-Coupling Effect of a 2-DOF Nanopositioning Stage. *Tao, Y.*, +, *TMECH Aug. 2021 2186-2194*

Navigation

Autonomous Navigation of Magnetic Microrobots in a Large Workspace Using Mobile-Coil System. Yang, Z., +, TMECH Dec. 2021 3163-3174

Robot-Assisted Object Detection for Construction Automation: Data and Information-Driven Approach. *Muhammad, I.*, +, *TMECH Dec. 2021* 2845-2856

Nearest neighbor methods

Global Optimization of the Hydraulic-Electromagnetic Energy-Harvesting Shock Absorber for Road Vehicles With Human-Knowledge-Integrated Particle Swarm Optimization Scheme. *Zhou, Q., +, TMECH June 2021 1225-1235*

Neck

Investigation on a New Approach for Designing Articulated Soft Robots With Discrete Variable Stiffness. *Zhong, Y., +, TMECH Dec. 2021 2998-3009*

Needles

- A Fully Actuated Robotic Assistant for MRI-Guided Precision Conformal Ablation of Brain Tumors. *Li*, *G.*, +, *TMECH Feb. 2021 255-266*
- A Mechanism-Image Fusion Approach to Calibration of an Ultrasound-Guided Dual-Arm Robotic Brachytherapy System. *Xiong, J.*, +, *TMECH Dec. 2021 3211-3220*
- A Tubular Dual-Roller Bending Mechanism Toward Robotic Transurethral Prostate Biopsy. Xiao, X., +, TMECH Oct. 2021 2483-2494
- Investigation of Micromotion Kinematics of Continuum Robots for Volumetric OCT and OCT-Guided Visual Servoing. *Giudice, G.D.*, +, *TMECH Oct.* 2021 2604-2615

- Needle Deflection Modeling and Preoperative Trajectory Planning During Insertion Into Multilayered Tissues. *Zhao, B., +, TMECH April 2021 943-954*
- Stochastic Force-Based Insertion Depth and Tip Position Estimations of Flexible FBG-Equipped Instruments in Robotic Retinal Surgery. *Ebrahimi, A.*, +, *TMECH June 2021 1512-1523*

Networked control systems

Cyber–Physical Codesign of Field-Level Reconfigurations in Networked Motion Controllers. *Zhou*, *N*., +, *TMECH Aug*. 2021 2092-2103

Neural networks

Edge-Dependent Efficient Grasp Rectangle Search in Robotic Grasp Detection. Chen, L., +, TMECH Dec. 2021 2922-2931

Neural networks

- A Circadian Rhythms Neural Network for Solving the Redundant Robot Manipulators Tracking Problem Perturbed by Periodic Noise. *Zhang, Z.*, +, *TMECH Dec. 2021 3232-3242*
- An Integrated Terrain Identification Framework for Mobile Robots: System Development, Analysis, and Verification. Zeng, R., +, TMECH June 2021 1581-1590
- An Investigation Into Fault Diagnosis of Planetary Gearboxes Using A Bispectrum Convolutional Neural Network. *Pang, X.*, +, *TMECH Aug.* 2021 2027-2037
- Geometrical-Based Displacement Measurement With Pseudostereo Monocular Camera on Bidirectional Cascaded Linear Actuator. *Lee, D.*, +, *TMECH Aug. 2021 1923-1931*
- Interactive Behavior Prediction for Heterogeneous Traffic Participants in the Urban Road: A Graph-Neural-Network-Based Multitask Learning Framework. *Li*, *Z*., +, *TMECH June 2021 1339-1349*
- Sensing and Reconstruction of 3-D Deformation on Pneumatic Soft Robots. Scharff, R.B.N., +, TMECH Aug. 2021 1877-1885

Unmanned System Safety Decision-Making Support: Analysis and Assessment of Road Traffic Accidents. Xie, G., +, TMECH April 2021 633-644

Neurocontrollers

- A Visual Servo-Based Predictive Control With Echo State Gaussian Process for Soft Bending Actuator. *Cao*, Y., +, *TMECH Feb. 2021* 574-585
- An Observer-Based Neural Adaptive\$PID^2\$ Controller for Robot Manipulators Including Motor Dynamics With a Prescribed Performance. *Shojaei*, *K.*, +, *TMECH June 2021 1689-1699*
- Efficient Cooperative Structured Control for a Multijoint Biomimetic Robotic Fish. Yan, S., +, TMECH Oct. 2021 2506-2516
- Event-Triggered-Based Discrete-Time Neural Control for a Quadrotor UAV Using Disturbance Observer. Shao, S., +, TMECH April 2021 689-699
- Fractional-Order Control for Uncertain Teleoperated Cyber-Physical System With Actuator Fault. *Ma*, *Z*., +, *TMECH Oct.* 2021 2472-2482
- Model-Free Control of Flexible Manipulator Based on Intrinsic Design. *Jiang, N.*, +, *TMECH Oct. 2021 2641-2652*
- Neurodynamics-Based Model Predictive Control of Continuous-Time Under-Actuated Mechatronic Systems. *Wang, J.*, +, *TMECH Feb. 2021* 311-322
- Novel Joint-Drift-Free Scheme at Acceleration Level for Robotic Redundancy Resolution With Tracking Error Theoretically Eliminated. *Jin*, *L.*, +, *TMECH Feb. 2021 90-101*
- Terrain Identification for Humanoid Robots Applying Convolutional Neural Networks. *Venancio, M.M.*, +, *TMECH June 2021 1433-1444*
- Whole-Body Control of an Autonomous Mobile Manipulator Using Series Elastic Actuators. *Liu*, *Y*, +, *TMECH April 2021 657-667*

Neuromuscular

MPC-Based Haptic Shared Steering System: A Driver Modeling Approach for Symbiotic Driving. *Lazcano, A.M.*, +, *TMECH June 2021 1201-1211* Neuromuscular stimulation

Brain–Machine Interface Using Functional Electrical Stimulation and Motion-Related Cortical Potentials Identified by a Support Vector Machine. *Miura*, S., +, *TMECH April 2021 1013-1021*

Neurophysiology

A Suction-Based Peripheral Nerve Gripper Capable of Controlling the Suction Force. Jang, N., +, TMECH Aug. 2021 1867-1876

- Brain–Machine Interface Using Functional Electrical Stimulation and Motion-Related Cortical Potentials Identified by a Support Vector Machine. *Miura*, S., +, *TMECH April 2021 1013-1021*
- On-Body RF Sensor Toward Tremor Detection in Parkinson's Disease. Abirami B, S., +, TMECH Oct. 2021 2814-2817

Newton method

A Lie-Theory-Based Dynamic Parameter Identification Methodology for Serial Manipulators. *Fu*, *Z*., +, *TMECH Oct. 2021 2688-2699*

Noise measurement

 A Circadian Rhythms Neural Network for Solving the Redundant Robot Manipulators Tracking Problem Perturbed by Periodic Noise. *Zhang, Z.*,
+, *TMECH Dec. 2021 3232-3242*

Nonlinear control systems

- A Tilting-Rotor Unmanned Aerial Vehicle for Enhanced Aerial Locomotion and Manipulation Capabilities: Design, Control, and Applications. *Ding*, *C.*, +, *TMECH Aug. 2021 2237-2248*
- A Visual Servo-Based Predictive Control With Echo State Gaussian Process for Soft Bending Actuator. *Cao*, Y., +, *TMECH Feb. 2021* 574-585
- Active Disturbance Rejection Control for a Fluid-Driven Hand Rehabilitation Device. Li, H., +, TMECH April 2021 841-853
- Adaptive Output Feedback Control of Steer-by-Wire Systems With Event-Triggered Communication. *Ma*, *B*., +, *TMECH Aug. 2021 1968-1979*
- Adaptive Robust Finite-Time Nonlinear Control of a Typical Autonomous Underwater Vehicle With Saturated Inputs and Uncertainties. *Sedghi, F.,* +, *TMECH Oct. 2021 2517-2527*
- Analytical Design and Experimental Verification of Geofencing Control for Aerial Applications. *Ghaffari, A., TMECH April 2021 1106-1117*
- Asymptotic Tracking Control of Mechanical Servosystems With Mismatched Uncertainties. *Deng, W.*, +, *TMECH Aug. 2021 2204-2214*
- Computationally Improved State-Dependent Riccati Equation Scheme for Nonlinear Benchmark System. Lin, L., TMECH April 2021 1064-1075
- Design and Experimental Validation of Robust Self-Scheduled Fault-Tolerant Control Laws for a Multicopter UAV. Nguyen, D., +, TMECH Oct. 2021 2548-2557
- Distributed Control Algorithm for Leader–Follower Formation Tracking of Multiple Quadrotors: Theory and Experiment. Wang, Z., +, TMECH April 2021 1095-1105
- Distributed Formation Control Using Fuzzy Self-Tuning of Strictly Negative Imaginary Consensus Controllers in Aerial Robotics. *Tran, V.P.*, +, *TMECH Oct. 2021 2306-2315*
- Dynamic Torso Compliance Control for Standing and Walking Balance of Position-Controlled Humanoid Robots. *Li*, *Q*., +, *TMECH April 2021 679-688*
- Event-Triggered-Based Discrete-Time Neural Control for a Quadrotor UAV Using Disturbance Observer. Shao, S., +, TMECH April 2021 689-699
- Experimental Investigation on Control of an Infinitely Variable Transmission System for Tidal Current Energy Converters. Li, G., +, TMECH Aug. 2021 1960-1967
- Finite-Time Synchronization Control for Bilateral Teleoperation Systems With Asymmetric Time-Varying Delay and Input Dead Zone. *Bao, J.*, +, *TMECH June 2021 1570-1580*
- Fractional-Order Control for Uncertain Teleoperated Cyber-Physical System With Actuator Fault. *Ma*, *Z*., +, *TMECH Oct. 2021 2472-2482*
- Fully Actuated Autonomous Flight of Thruster-Tilting Multirotor. Lee, S.J., +, TMECH April 2021 765-776
- Hybrid Control Strategy for Force and Precise End Effector Positioning of a Twisted String Actuator. *Rodriguez, A.S., +, TMECH Oct. 2021 2791-2802*
- Kernel-Orthogonal Control of Tensegrity Systems. Yang, S., TMECH April 2021 1043-1052
- Modeling and Adaptive Fault Compensation for Two Physically Linked 2WD Mobile Robots. *Ma*, *Y*, +, *TMECH April 2021 1161-1171*
- Modeling and Motion Control of Industrial Tractor–Trailers Vehicles Using Force Compensation. Zhao, H., +, TMECH April 2021 645-656
- Nonlinear Model Predictive Control for Integrated Energy-Efficient Torque-Vectoring and Anti-Roll Moment Distribution. *Dalboni, M.*, +, *TMECH June 2021 1212-1224*

- On Perpendicular Curve-Based Model-Less Control Considering Incomplete Orientation Constraint. *Li*, *G*., +, *TMECH June 2021 1479-1489*
- Passivity-Based Nonlinear Control Approach for Tracking Task of an Underactuated CMG. *Toriumi, F.Y.*, +, *TMECH Oct. 2021 2285-2293*
- Path Following of Wheeled Mobile Robots Using Online-Optimization-Based Guidance Vector Field. *Chen, J.*, +, *TMECH Aug. 2021 1737-1744*
- Point Stabilization of Nonholonomic Mobile Robot by Bézier Smooth Subline Constraint Nonlinear Model Predictive Control. *Zhang, Y.*, +, *TMECH April 2021 990-1001*
- Practical Terminal Sliding Mode Control of Nonlinear Uncertain Active Suspension Systems With Adaptive Disturbance Observer. *Wang, G.*, +, *TMECH April 2021 789-797*
- Proportional-Integral Approximation-Free Control of Robotic Systems With Unknown Dynamics. *Zhang, C.*, +, *TMECH Aug. 2021 2226-2236*
- Quasi-LPV Interconnected Observer Design for Full Vehicle Dynamics Estimation With Hardware Experiments. *Fouka*, M., +, *TMECH Aug. 2021* 1763-1772
- Quasi-Synchronization Control of Multiple Electrohydraulic Actuators With Load Disturbance and Uncertain Parameters. *Guo, Q.*, +, *TMECH Aug.* 2021 2048-2058
- Robust Adaptive Tracking Control of Underwater Vehicles: Design, Stability Analysis, and Experiments. *Tijjani, A.S.*, +, *TMECH April 2021 897-907*
- Robust Nonlinear Model Predictive Control Based Visual Servoing of Quadrotor UAVs. *Zhang, K.,* +, *TMECH April 2021 700-708*
- Robust Tracking Control of a Quadrotor Unmanned Aerial Vehicle-Suspended Payload System. Xian, B., +, TMECH Oct. 2021 2653-2663
- Sliding-Mode-Disturbance-Observer-Based Robust Tracking Control for Omnidirectional Mobile Robots With Kinematic and Dynamic Uncertainties. Jeong, S., +, TMECH April 2021 741-752
- Takagi–Sugeno Fuzzy Unknown Input Observers to Estimate Nonlinear Dynamics of Autonomous Ground Vehicles: Theory and Real-Time Verification. Nguyen, A., +, TMECH June 2021 1328-1338
- Tracking Accuracy Improvement Based on Adaptive Nonlinear Sliding Mode Control. *Tsai*, W., +, *TMECH Feb. 2021 179-190*
- Virtual Landmark-Based Control of Docking Support for Assistive Mobility Devices. Chen, Y., +, TMECH Aug. 2021 2007-2015
- Whole-Body Control of an Autonomous Mobile Manipulator Using Series Elastic Actuators. *Liu*, *Y*., +, *TMECH April 2021 657-667*

Nonlinear differential equations

Actuation Frequency Modeling and Prediction for Shape Memory Alloy Actuators. *Liu, X., +, TMECH June 2021 1536-1546*

Static Pull-In Behavior of Hybrid Levitation Microactuators: Simulation, Modeling, and Experimental Study. Poletkin, K.V., TMECH April 2021 753-764

Nonlinear equations

Dynamic Modeling and State Estimation of Cable-Conduit Actuation During Interaction With Nonpassive Environments. *Buchanan, S.*, +, *TMECH Oct.* 2021 2462-2471

Nonlinear filters

An Adaptive Fault-Tolerant EKF for Vehicle State Estimation With Partial Missing Measurements. *Wang, Y.*, +, *TMECH June 2021 1318-1327*

Numerical models

- Automatic Construction of Three-Dimensional Ground Model by Data Processing. *Takeyama*, *T*., +, *TMECH Dec.* 2021 2881-2887
- Energy-Based Modeling of Ionic Polymer–Metal Composite Actuators Dedicated to the Control of Flexible Structures. *Liu, N.*, +, *TMECH Dec. 2021* 3139-3150
- Prediction-Model-Based Contouring Error Iterative Precompensation Scheme for Precision Multiaxis Motion Systems. *Wang, Z.*, +, *TMECH Oct. 2021 2274-2284*

Numerical stability

Computationally Efficient Practical Method for Solving the Dynamics of Fluid Power Circuits in the Presence of Singularities. *Malysheva*, J., +, *TMECH Oct.* 2021 2385-2395

Object detection

- Autonomous Vision-Guided Object Collection From Water Surfaces With a Customized Multirotor. *Mishra, S.*, +, *TMECH Aug. 2021 1914-1922*
- Efficient Anomaly Detection in a Laser-Surface Heat-Treatment Process via Laser-Spot Tracking. *Atienza*, *D.*, +, *TMECH Feb. 2021 405-415*
- Loop-Closure Detection With a Multiresolution Point Cloud Histogram Mode in Lidar Odometry and Mapping for Intelligent Vehicles. *Meng*, *Q*., +, *TMECH June 2021 1307-1317*
- Modeling and Experimental Validation of a Planar Microconveyor Based on a 2 × 2 Array of Digital Electromagnetic Actuators. *Tisnes, S.D.*, +, *TMECH June 2021 1422-1432*
- Real-Time Avoidance Strategy of Dynamic Obstacles via Half Model-Free Detection and Tracking With 2D Lidar for Mobile Robots. *Dong, H.*, +, *TMECH Aug. 2021 2215-2225*
- Robot-Assisted Object Detection for Construction Automation: Data and Information-Driven Approach. *Muhammad, I.*, +, *TMECH Dec. 2021* 2845-2856

Object recognition

OrthographicNet: A Deep Transfer Learning Approach for 3-D Object Recognition in Open-Ended Domains. Kasaei, S.H., TMECH Dec. 2021 2910-2921

Object tracking

- On-Body RF Sensor Toward Tremor Detection in Parkinson's Disease. Abirami B, S., +, TMECH Oct. 2021 2814-2817
- Virtual Landmark-Based Control of Docking Support for Assistive Mobility Devices. Chen, Y., +, TMECH Aug. 2021 2007-2015

Observability

Quasi-LPV Interconnected Observer Design for Full Vehicle Dynamics Estimation With Hardware Experiments. *Fouka*, M., +, *TMECH Aug. 2021* 1763-1772

Observers

- A Computational-Effective Field-Oriented Control Strategy for Accurate and Efficient Electric Propulsion of Unmanned Aerial Vehicles. *Bosso, A.*,
 +, *TMECH June 2021 1501-1511*
- A Generalized Design Method for Learning-Based Disturbance Observer. Zheng, M., +, TMECH Feb. 2021 45-54
- A Novel Rotational Actuator With Variable Stiffness Using S-Shaped Springs. Xu, Y, +, TMECH Aug. 2021 2249-2260
- Active Disturbance Rejection Control for a Fluid-Driven Hand Rehabilitation Device. Li, H., +, TMECH April 2021 841-853
- Adaptive Output Feedback Control of Steer-by-Wire Systems With Event-Triggered Communication. *Ma*, *B*., +, *TMECH Aug. 2021 1968-1979*
- An Observer-Based Neural Adaptive\$PID^2\$ Controller for Robot Manipulators Including Motor Dynamics With a Prescribed Performance. *Shojaei*, *K.*, +, *TMECH June 2021 1689-1699*
- An Output Feedback Based Robust Saturated Controller Design for Pavement Sweeping Self-Reconfigurable Robot. *Rayguru, M.M.*, +, *TMECH June 2021 1236-1247*
- Dimensionless Model-Based System Tracking Via Augmented Kalman Filter for Multiscale Unmanned Ground Vehicles. *Sun, C.*, +, *TMECH April* 2021 600-610
- Event-Triggered-Based Discrete-Time Neural Control for a Quadrotor UAV Using Disturbance Observer. *Shao, S.,* +, *TMECH April 2021 689-699*
- Low Impedance-Guaranteed Gain-Scheduled GESO for Torque-Controlled VSA With Application of Exoskeleton-Assisted Sit-to-Stand. *Liu, L., +, TMECH Aug. 2021 2080-2091*
- Practical Terminal Sliding Mode Control of Nonlinear Uncertain Active Suspension Systems With Adaptive Disturbance Observer. *Wang, G.*, +, *TMECH April 2021 789-797*
- Quasi-LPV Interconnected Observer Design for Full Vehicle Dynamics Estimation With Hardware Experiments. *Fouka, M.*, +, *TMECH Aug. 2021* 1763-1772
- Simultaneous State Estimation and Tire Model Learning for Autonomous Vehicle Applications. Jeon, W., +, TMECH Aug. 2021 1941-1950

- Sliding-Mode-Disturbance-Observer-Based Robust Tracking Control for Omnidirectional Mobile Robots With Kinematic and Dynamic Uncertainties. Jeong, S., +, TMECH April 2021 741-752
- Stability and Robustness of the Disturbance Observer-Based Motion Control Systems in Discrete-Time Domain. *Sariyildiz, E., +, TMECH Aug. 2021* 2139-2150
- Takagi–Sugeno Fuzzy Unknown Input Observers to Estimate Nonlinear Dynamics of Autonomous Ground Vehicles: Theory and Real-Time Verification. Nguyen, A., +, TMECH June 2021 1328-1338

Oils

Failure Monitoring and Predictive Maintenance of Hydraulic Cylinder— State-of-the-Art Review. *Shanbhag, V.V.*, +, *TMECH Dec. 2021 3087-3103*

Open loop systems

Modeling and Experimental Validation of a Planar Microconveyor Based on a 2 × 2 Array of Digital Electromagnetic Actuators. *Tisnes, S.D.*, +, *TMECH June 2021 1422-1432*

Optical arrays

Ultraviolet Beam Lithography System for Digital Fabrication of Roller Molds. Yang, S., +, TMECH Feb. 2021 226-234

Optical design techniques

Exploring the Pareto Fronts of Actuation Technologies for High Performance Mechatronic Systems. *Csencsics, E.*, +, *TMECH April 2021 1053-1063*

Optical fabrication

Ultraviolet Beam Lithography System for Digital Fabrication of Roller Molds. Yang, S., +, TMECH Feb. 2021 226-234

Optical feedback

Modified Stiffness-Based Soft Optical Waveguide Integrated Pneumatic Artificial Muscle (PAM) Actuators for Contraction and Force Sensing. *Jamil, B.,* +, *TMECH Dec. 2021 3243-3253*

Optical fibers

Ultraviolet Beam Lithography System for Digital Fabrication of Roller Molds. Yang, S., +, TMECH Feb. 2021 226-234

Optical imaging

Radial Coverage Strength for Optimization of Monocular Multicamera Deployment. Lei, Z., +, TMECH Dec. 2021 3221-3231

Optical microscopy

Image Processing Metrics for Phase Identification of a Multiaxis MEMS Scanner Used in Single Pixel Imaging. *Birla, M.*, +, *TMECH June 2021* 1445-1454

Optical modulation

- Ultraviolet Beam Lithography System for Digital Fabrication of Roller Molds. Yang, S., +, TMECH Feb. 2021 226-234
- **Optical noise**

UltraLow Noise, High Bandwidth, Low Latency, No Overload 6-Axis Optical Force Sensor. *Hosseinabadi, A.H.H.*, +, *TMECH Oct. 2021 2581-2592* Optical radar

Loop-Closure Detection With a Multiresolution Point Cloud Histogram Mode in Lidar Odometry and Mapping for Intelligent Vehicles. *Meng*, Q., +, *TMECH June 2021 1307-1317*

Real-Time Avoidance Strategy of Dynamic Obstacles via Half Model-Free Detection and Tracking With 2D Lidar for Mobile Robots. *Dong, H.*, +, *TMECH Aug, 2021 2215-2225*

Optical scanners

- Development of a Resonant Scanner to Improve the Imaging Rate of Astigmatic Optical Profilometers. *Liao, H., +, TMECH April 2021 1172-1177*
- Image Processing Metrics for Phase Identification of a Multiaxis MEMS Scanner Used in Single Pixel Imaging. *Birla, M.*, +, *TMECH June 2021* 1445-1454

Optical sensors

- An Automated AFM Tip-Replacement System for *In Situ* Tip-Replacement. *Vikrant, K.S.*, +, *TMECH April 2021 798-806*
- Modified Stiffness-Based Soft Optical Waveguide Integrated Pneumatic Artificial Muscle (PAM) Actuators for Contraction and Force Sensing. *Jamil, B.,* +, *TMECH Dec. 2021 3243-3253*
- UltraLow Noise, High Bandwidth, Low Latency, No Overload 6-Axis Optical Force Sensor. *Hosseinabadi*, A.H.H., +, *TMECH Oct. 2021 2581-2592*

- Automated Retinal Vein Cannulation on Silicone Phantoms Using Optical-Coherence-Tomography-Guided Robotic Manipulations. Gerber, M.J., +, TMECH Oct. 2021 2758-2769
- Investigation of Micromotion Kinematics of Continuum Robots for Volumetric OCT and OCT-Guided Visual Servoing. Giudice, G.D., +, TMECH Oct, 2021 2604-2615

Optimal control

Efficient Motion Planning Based on Kinodynamic Model for Quadruped Robots Following Persons in Confined Spaces. *Zhang, Z.*, +, *TMECH Aug.* 2021 1997-2006

- Fractional-Order Control for Uncertain Teleoperated Cyber-Physical System With Actuator Fault. *Ma*, *Z*., +, *TMECH Oct. 2021 2472-2482*
- Robust Concurrent Design of a 2-DOF Collaborative Robot (Cobot). Mendoza-Trejo, O., +, TMECH Feb. 2021 347-357

Optimization

- A Novel Clustering-Based Algorithm for Solving Spatially Constrained Robotic Task Sequencing Problems. *Wong, C.*, +, *TMECH Oct. 2021 2294-2305*
- An Electrical Impedance Tomography Based Interface for Human–Robot Collaboration. Zheng, E., +, TMECH Oct. 2021 2373-2384
- Constrained Surrogate-Based Engine Calibration Using Lower Confidence Bound. Pal, A., +, TMECH Dec. 2021 3116-3127
- Efficiency Optimization Strategy for Switched Reluctance Generator System With Position Sensorless Control. *Chen, H., +, TMECH Feb. 2021* 469-479
- Efficient Bathymetric SLAM With Invalid Loop Closure Identification. *Teng, M.*, +, *TMECH Oct. 2021 2570-2580*
- Efficient Cooperative Structured Control for a Multijoint Biomimetic Robotic Fish. Yan, S., +, TMECH Oct. 2021 2506-2516
- Efficient Motion Planning Based on Kinodynamic Model for Quadruped Robots Following Persons in Confined Spaces. *Zhang, Z.*, +, *TMECH Aug.* 2021 1997-2006
- Global Optimization of the Hydraulic-Electromagnetic Energy-Harvesting Shock Absorber for Road Vehicles With Human-Knowledge-Integrated Particle Swarm Optimization Scheme. *Zhou, Q.*, +, *TMECH June 2021* 1225-1235
- Globally Optimal Symbolic Hand-Eye Calibration. *Wu, J.*, +, *TMECH June* 2021 1369-1379
- Integral Design and Manufacturing Methodology of a Reduced-Scale Servo Press. Olaizola, J., +, TMECH Oct. 2021 2418-2428
- Localized Property Design and Gradient Processing of a Hydraulic Valve Body Using Selective Laser Melting. *Zhu, Y.*, +, *TMECH April 2021 1151-1160*
- Neurodynamics-Based Model Predictive Control of Continuous-Time Under-Actuated Mechatronic Systems. *Wang, J.*, +, *TMECH Feb. 2021* 311-322
- Nonprehensile Manipulation: A Trajectory-Planning Perspective. Acharya, P., +, TMECH Feb. 2021 527-538
- Novel Joint-Drift-Free Scheme at Acceleration Level for Robotic Redundancy Resolution With Tracking Error Theoretically Eliminated. *Jin*, *L*., +, *TMECH Feb.* 2021 90-101
- Optimization of Generalized S-Curve Trajectories for Residual Vibration Suppression and Compliance With Kinematic Bounds. *Biagiotti, L.*, +, *TMECH Oct. 2021 2724-2734*
- Radial Coverage Strength for Optimization of Monocular Multicamera Deployment. Lei, Z., +, TMECH Dec. 2021 3221-3231
- Thermal Modeling and Characterization of Twisted Coiled Actuators for Upper Limb Wearable Devices. *Edmonds, B.P.R.*, +, *TMECH April 2021* 966-977
- Topology Optimization for Design of a 3D-Printed Constant-Force Compliant Finger. Liu, C., +, TMECH Aug. 2021 1828-1836
- Topology Optimization of Skeleton-Reinforced Soft Pneumatic Actuators for Desired Motions. Chen, S., +, TMECH Aug. 2021 1745-1753

Orthopedics

A Surgical Robotic System for Treatment of Pelvic Osteolysis Using an FBG-Equipped Continuum Manipulator and Flexible Instruments. *Sefati, S.*, +, *TMECH Feb. 2021 369-380*

Orthotics

Mech-Walker:A Novel Single-DOF Linkage Device With Movable Frame for Gait Rehabilitation. *Haghjoo*, *M.R.*, +, *TMECH Feb. 2021 13-23*Mechanical Aspects of Robot Hands, Active Hand Orthoses, and Prostheses: A Comparative Review. *Vertongen*, *J.*, +, *TMECH April 2021 955-965*

Р

Control Parameters Design Based on Dynamic Characteristics of a Hybrid Robot With Parallelogram Structures. *Liu, Z.*, +, *TMECH April 2021 1140-1150*

Pancreas

Painting

Development of a Soft Robot Based Photodynamic Therapy for Pancreatic Cancer. *Li*, *Y*, +, *TMECH Dec. 2021 2977-2985*

Parallel processing

Toolpath Regeneration in Subregional Contour-Parallel Processing Based on Isoscallop Method. Ma, J., +, TMECH April 2021 730-740

Parameter estimation

- A Lie-Theory-Based Dynamic Parameter Identification Methodology for Serial Manipulators. Fu, Z., +, TMECH Oct. 2021 2688-2699
- Electrical Parameter Identification of Medium-Frequency DC Resistance Spot Welding System Using Intelligent Algorithm. *Wang, X.*, +, *TMECH Aug. 2021 1791-1802*

Identification of a Nonlinear Dielectric Elastomer Actuator Based on the Harmonic Balance Method. Bernat, J., +, TMECH Oct. 2021 2664-2675

Pareto optimization

Exploring the Pareto Fronts of Actuation Technologies for High Performance Mechatronic Systems. Csencsics, E., +, TMECH April 2021 1053-1063

Particle filtering (numerical methods)

Efficient Bathymetric SLAM With Invalid Loop Closure Identification. Teng, M., +, TMECH Oct. 2021 2570-2580

Particle swarm optimization

- Design and Real-Time Optimization for a Magnetic Actuation System With Enhanced Flexibility. *Du*, *X.*, +, *TMECH June 2021 1524-1535*
- Electrical Parameter Identification of Medium-Frequency DC Resistance Spot Welding System Using Intelligent Algorithm. *Wang, X.*, +, *TMECH Aug. 2021 1791-1802*
- Global Optimization of the Hydraulic-Electromagnetic Energy-Harvesting Shock Absorber for Road Vehicles With Human-Knowledge-Integrated Particle Swarm Optimization Scheme. *Zhou, Q.*, +, *TMECH June 2021* 1225-1235

Path planning

- A Hybrid Active and Passive Cable-Driven Segmented Redundant Manipulator: Design, Kinematics, and Planning. *Liu*, *T.*, +, *TMECH April 2021* 930-942
- Autonomous Navigation of Magnetic Microrobots in a Large Workspace Using Mobile-Coil System. Yang, Z., +, TMECH Dec. 2021 3163-3174
- Collaborative Semantic Understanding and Mapping Framework for Autonomous Systems. Yue, Y., +, TMECH April 2021 978-989
- Development and Performance Enhancement of an Overactuated Autonomous Ground Vehicle. *Huang, Y.*, +, *TMECH Feb. 2021 33-44*
- Dual Fast Marching Tree Algorithm for Human-Like Motion Planning of Anthropomorphic Arms With Task Constraints. Xia, J., +, TMECH Oct. 2021 2803-2813
- Dynamic State Estimation and Control of a Heavy Tractor–Trailers Vehicle. Zhou, S., +, TMECH June 2021 1467-1478
- Efficient Bathymetric SLAM With Invalid Loop Closure Identification. Teng, M., +, TMECH Oct. 2021 2570-2580
- Integrated Predictive Powertrain Control for a Multimode Plug-in Hybrid Electric Vehicle. *Oncken, J.*, +, *TMECH June 2021 1248-1259*
- Interactive Behavior Prediction for Heterogeneous Traffic Participants in the Urban Road: A Graph-Neural-Network-Based Multitask Learning Framework. *Li*, *Z*., +, *TMECH June 2021 1339-1349*

- Multiobjective Scheduling Strategy With Genetic Algorithm and Time-Enhanced A* Planning for Autonomous Parking Robotics in High-Density Unmanned Parking Lots. *Chen, G.,* +, *TMECH June 2021 1547-1557*
- Nonprehensile Manipulation:A Trajectory-Planning Perspective. Acharya, P., +, TMECH Feb. 2021 527-538
- Self-Balancing Two-Wheeled Robot Featuring Intelligent End-to-End Deep Visual-Steering. Li, C.G., +, TMECH Oct. 2021 2263-2273
- Toward Safe and Personalized Autonomous Driving: Decision-Making and Motion Control With DPF and CDT Techniques. *Huang, C.*, +, *TMECH April 2021 611-620*
- Virtual Landmark-Based Control of Docking Support for Assistive Mobility Devices. *Chen, Y., +, TMECH Aug. 2021 2007-2015*

Patient monitoring

On-Body RF Sensor Toward Tremor Detection in Parkinson's Disease. Abirami B, S., +, TMECH Oct. 2021 2814-2817

Patient rehabilitation

- A New Ankle Robotic System Enabling Whole-Stage Compliance Rehabilitation Training. Dong, M., +, TMECH June 2021 1490-1500
- Active Disturbance Rejection Control for a Fluid-Driven Hand Rehabilitation Device. Li, H., +, TMECH April 2021 841-853
- Brain–Machine Interface Using Functional Electrical Stimulation and Motion-Related Cortical Potentials Identified by a Support Vector Machine. *Miura*, S., +, *TMECH April 2021 1013-1021*
- Design Principles for Compact, Backdrivable Actuation in Partial-Assist Powered Knee Orthoses. Zhu, H., +, TMECH Dec. 2021 3104-3115
- Human–Robot Cooperation Control Based on Trajectory Deformation Algorithm for a Lower Limb Rehabilitation Robot. *Zhou, J.*, +, *TMECH Dec.* 2021 3128-3138
- Markovian Robust Filtering and Control Applied to Rehabilitation Robotics. Escalante, F.M., +, TMECH Feb. 2021 491-502
- Mech-Walker: A Novel Single-DOF Linkage Device With Movable Frame for Gait Rehabilitation. *Haghjoo*, *M.R.*, +, *TMECH Feb. 2021 13-23*
- Mechanism and Controller Design of a Transfemoral Prosthesis With Electrohydraulic Knee and Motor-Driven Ankle. *Gao, S.*, +, *TMECH Oct. 2021* 2429-2439

Wearable Knee Assistive Devices for Kneeling Tasks in Construction. *Chen, S.*, +, *TMECH Aug. 2021 1989-1996*

Patient treatment

Blindly Controlled Magnetically Actuated Capsule for Noninvasive Sampling of the Gastrointestinal Microbiome. *Shokrollahi, P., +, TMECH Oct.* 2021 2616-2628

Pattern classification

Efficient Anomaly Detection in a Laser-Surface Heat-Treatment Process via Laser-Spot Tracking. *Atienza*, D., +, *TMECH Feb. 2021 405-415*

Unsupervised Cross-Domain Fault Diagnosis Using Feature Representation Alignment Networks for Rotating Machinery. *Chen, J.*, +, *TMECH Oct.* 2021 2770-2781

Pattern clustering

A Novel Clustering-Based Algorithm for Solving Spatially Constrained Robotic Task Sequencing Problems. *Wong, C.*, +, *TMECH Oct. 2021 2294-2305*

Payloads

- Kinematic Modeling and Control of Variable Curvature Soft Continuum Robots. *Huang, X.*, +, *TMECH Dec. 2021 3175-3185*
- On the Mechanical Power Output Comparisons of Cone Dielectric Elastomer Actuators. Cao, C., +, TMECH Dec. 2021 3151-3162

PD control

Robust Concurrent Design of a 2-DOF Collaborative Robot (Cobot). Mendoza-Trejo, O., +, TMECH Feb. 2021 347-357

Pendulums

- Roller-Skating of Mammalian Quadrupedal Robot With Passive Wheels Inspired by Human. Chen, J., +, TMECH June 2021 1624-1634
- Vision-Based Control of a Knuckle Boom Crane With Online Cable Length Estimation. *Tysse, G.O.*, +, *TMECH Feb. 2021 416-426*

Peripheral interfaces

A Lightweight Wireless Overpressure Node Based Efficient Monitoring for Shock Waves. *Gao*, S., +, *TMECH Feb*. 2021 448-457

Peristaltic flow

Measurement of Peristaltic Forces Exerted by Living Intestine on Robotic Capsule. *Rehan, M.*, +, *TMECH Aug. 2021 1803-1811*

Permanent magnet machines

Design Process and Verification of SPMSM for a Wearable Robot Considering Thermal Characteristics Through LPTN. *Hwang, S.*, +, *TMECH April* 2021 1033-1042

Permanent magnet motors

- Design Principles for Compact, Backdrivable Actuation in Partial-Assist Powered Knee Orthoses. Zhu, H., +, TMECH Dec. 2021 3104-3115
- Design Process and Verification of SPMSM for a Wearable Robot Considering Thermal Characteristics Through LPTN. Hwang, S., +, TMECH April 2021 1033-1042
- Magnetically Levitated Linear Stage With Linear Bearingless Slice Hysteresis Motors. Zhou, L., +, TMECH April 2021 1084-1094
- Online Compensation of Mechanical Load Defects With Composite Control in PMSM Drives. Kommuri, S.K., +, TMECH June 2021 1392-1400
- Practical Fixed-Time Position Tracking Control of Permanent Magnet DC Torque Motor Systems. *Wu, Y., +, TMECH Feb. 2021 563-573*
- Rotor Position Tracking Control for Low Speed Operation of Direct-Drive PMSM Servo System. *Bu*, *F*, +, *TMECH April 2021 1129-1139*
- Static Position Sensor Bias Fault Diagnosis in Permanent Magnet Synchronous Machines via Current Estimation. Kuruppu, S.S., +, TMECH April 2021 888-896
- Study on a Double-Sided Permanent-Magnet Linear Synchronous Motor With Reversed Slots. Zhao, J., +, TMECH Feb. 2021 3-12

Permanent magnets

- Analysis of Quasi-Zero Power Characteristic for a Permanent Magnetic Levitation System With a Variable Flux Path Control Mechanism. *Zhao, C.*, +, *TMECH Feb. 2021 437-447*
- Blindly Controlled Magnetically Actuated Capsule for Noninvasive Sampling of the Gastrointestinal Microbiome. *Shokrollahi, P., +, TMECH Oct.* 2021 2616-2628
- Magnetically Levitated Linear Drive Using an Active Gravity Compensation Based on Hybrid Shape Memory Actuators. *Raab, M.*, +, *TMECH June* 2021 1380-1391
- Magnetically Levitated Linear Stage With Linear Bearingless Slice Hysteresis Motors. Zhou, L., +, TMECH April 2021 1084-1094

Permeability

A DC-Biased Scanning Induction Thermographic System for Characterizing Surface Cracks in Ferromagnetic Components. *Wu, J.*, +, *TMECH Oct.* 2021 2782-2790

Phantoms

- A Fully Actuated Robotic Assistant for MRI-Guided Precision Conformal Ablation of Brain Tumors. *Li*, *G.*, +, *TMECH Feb. 2021 255-266*
- A Mechanism-Image Fusion Approach to Calibration of an Ultrasound-Guided Dual-Arm Robotic Brachytherapy System. *Xiong, J.*, +, *TMECH Dec. 2021 3211-3220*
- A Surgical Robotic System for Treatment of Pelvic Osteolysis Using an FBG-Equipped Continuum Manipulator and Flexible Instruments. *Sefati, S.*, +, *TMECH Feb. 2021 369-380*
- A Tubular Dual-Roller Bending Mechanism Toward Robotic Transurethral Prostate Biopsy. Xiao, X., +, TMECH Oct. 2021 2483-2494
- Automated Retinal Vein Cannulation on Silicone Phantoms Using Optical-Coherence-Tomography-Guided Robotic Manipulations. *Gerber, M.J.*, +, *TMECH Oct. 2021 2758-2769*

Robotized Catheter With Enhanced Distal Targeting for Peripheral Pulmonary Biopsy. *Kato*, *T*., +, *TMECH Oct. 2021 2451-2461*

Photodetectors

UltraLow Noise, High Bandwidth, Low Latency, No Overload 6-Axis Optical Force Sensor. *Hosseinabadi, A.H.H.*, +, *TMECH Oct. 2021 2581-2592* Photography

Design and Control of Soft Unmanned Aerial Vehicle "S-CLOUD". Song, S.H., +, TMECH Feb. 2021 267-275

Photoresists

Ultraviolet Beam Lithography System for Digital Fabrication of Roller Molds. Yang, S., +, TMECH Feb. 2021 226-234

Physical instrumentation control

Iterative Learning Control for Video-Rate Atomic Force Microscopy. Nikooienejad, N., +, TMECH Aug. 2021 2127-2138

PI control

Proportional-Integral Approximation-Free Control of Robotic Systems With Unknown Dynamics. *Zhang, C., +, TMECH Aug. 2021 2226-2236*

Piezoelectric actuators

- A Fully Actuated Robotic Assistant for MRI-Guided Precision Conformal Ablation of Brain Tumors. *Li*, *G.*, +, *TMECH Feb. 2021 255-266*
- A Monolithic Force Sensing Integrated Flexure Bonder Dedicated to Flip-Chip Active Soft-Landing Interconnection. *Tang, H.*, +, *TMECH Feb.* 2021 323-334
- A Piezoelectric Robotic System for MRI Targeting Assessments of Therapeutics During Dipole Field Navigation. *Shi*, Y., +, *TMECH Feb. 2021* 214-225
- Closed-Loop Range-Based Control of Dual-Stage Nanopositioning Systems. *Mitrovic, A., +, TMECH June 2021 1412-1421*
- Development and Test of a Two-Dimensional Stacked Terfenol-D Actuator With High Bandwidth and Large Stroke. *Chen, L.*, +, *TMECH Aug. 2021* 1951-1959
- Development of a Nanopositioning Platform With Large Travel Range Based on Bionic Quadruped Piezoelectric Actuator. *Deng, J.*, +, *TMECH Aug. 2021 2059-2070*

Exploring the Pareto Fronts of Actuation Technologies for High Performance Mechatronic Systems. Csencsics, E., +, TMECH April 2021 1053-1063

Piezoelectric devices

- A Smoothed Raster Scanning Trajectory Based on Acceleration-Continuous B-Spline Transition for High-Speed Atomic Force Microscopy. *Li*, *L.*, +, *TMECH Feb. 2021 24-32*
- Erratum to "A Smoothed Raster Scanning Trajectory Based on Acceleration-Continuous B-Spline Transition for High-Speed Atomic Force Microscopy" [Feb 21 24-32]. Li, L., +, TMECH June 2021 1700
- Structural Failure Detection Using Wireless Transmission Rate From Piezoelectric Energy Harvesters. Jung, H.J., +, TMECH Aug. 2021 1708-1718

Piezoelectric materials

 Structural Failure Detection Using Wireless Transmission Rate From Piezoelectric Energy Harvesters. Jung, H.J., +, TMECH Aug. 2021 1708-1718
Tendon-Inspired Piezoelectric Sensor for Biometric Application. Kim, H., +, TMECH Oct. 2021 2538-2547

Piezoelectric transducers

Structural Failure Detection Using Wireless Transmission Rate From Piezoelectric Energy Harvesters. Jung, H.J., +, TMECH Aug. 2021 1708-1718

Piezoresistive devices

Design and Testing of a New Force-Sensing Cell Microinjector Based on Small-Stiffness Compliant Mechanism. *Wei, Y.*, +, *TMECH April 2021* 818-829

Pipelines

Geometrical-Based Displacement Measurement With Pseudostereo Monocular Camera on Bidirectional Cascaded Linear Actuator. *Lee, D.*, +, *TMECH Aug. 2021 1923-1931*

Pistons

- A Method for Mass Flow and Displacement Estimation in a Pneumatic Actuation System Using Valve-Based Pressure Sensing. Vailati, L.G., +, TMECH Feb. 2021 235-245
- Analytical Harmonic Method for Modeling High-Frequency Oscillation With Applications to Aircraft Piston Pump Vibration Analysis. *Li*, *L.*, +, *TMECH April 2021 918-929*
- Failure Monitoring and Predictive Maintenance of Hydraulic Cylinder— State-of-the-Art Review. Shanbhag, V.V., +, TMECH Dec. 2021 3087-3103
- Intelligent Vibration Control for Semiactive Suspension Systems Without Prior Knowledge of Dynamical Nonlinear Damper Behaviors Based on Improved Extreme Learning Machine. *Huang, W.*, +, *TMECH Aug. 2021* 2071-2079

Plates (structures)

Analytical Harmonic Method for Modeling High-Frequency Oscillation With Applications to Aircraft Piston Pump Vibration Analysis. *Li*, *L.*, +, *TMECH April 2021 918-929*

Pneumatic actuators

- A Method for Mass Flow and Displacement Estimation in a Pneumatic Actuation System Using Valve-Based Pressure Sensing. *Vailati, L.G.*, +, *TMECH Feb. 2021 235-245*
- A Two-Finger Soft-Robotic Gripper With Enveloping and Pinching Grasping Modes. *Liu*, S., +, *TMECH Feb. 2021 146-155*
- Design and Characterization of a Bellows-Driven Soft Pneumatic Actuator. Hashem, R., +, TMECH Oct. 2021 2327-2338
- Design, Modeling, and Control of a 3D Printed Monolithic Soft Robotic Finger With Embedded Pneumatic Sensing Chambers. *Tawk, C.*, +, *TMECH April 2021 876-887*
- Modeling and Analysis of Soft Pneumatic Network Bending Actuators. *Liu*, *Z.*, +, *TMECH Aug. 2021 2195-2203*
- Sensing and Reconstruction of 3-D Deformation on Pneumatic Soft Robots. Scharff, R.B.N., +, TMECH Aug. 2021 1877-1885

Topology Optimization of Skeleton-Reinforced Soft Pneumatic Actuators for Desired Motions. *Chen, S.,* +, *TMECH Aug. 2021 1745-1753*

Pneumatic systems

- Design, Modeling, and Control of a 3D Printed Monolithic Soft Robotic Finger With Embedded Pneumatic Sensing Chambers. *Tawk, C.*, +, *TMECH April 2021 876-887*
- Kinematic Modeling and Control of Variable Curvature Soft Continuum Robots. *Huang, X.*, +, *TMECH Dec. 2021 3175-3185*

Poincare mapping

Roller-Skating of Mammalian Quadrupedal Robot With Passive Wheels Inspired by Human. *Chen*, J., +, *TMECH June 2021 1624-1634*

Polymers

Energy-Based Modeling of Ionic Polymer–Metal Composite Actuators Dedicated to the Control of Flexible Structures. *Liu*, N., +, *TMECH Dec. 2021* 3139-3150

Polynomials

Nonprehensile Manipulation:A Trajectory-Planning Perspective. Acharya, P., +, TMECH Feb. 2021 527-538

Pose estimation

- Globally Optimal Symbolic Hand-Eye Calibration. *Wu, J.*, +, *TMECH June* 2021 1369-1379
- Nontarget-Based Measurement of 6-DOF Structural Displacement Using Combined RGB Color and Depth Information. *Lee, S.*, +, *TMECH June* 2021 1358-1368
- Pose Error Estimation Using a Cylinder in Scanner-Based Robotic Belt Grinding. Xie, H., +, TMECH Feb. 2021 515-526

Position control

- A Computational-Effective Field-Oriented Control Strategy for Accurate and Efficient Electric Propulsion of Unmanned Aerial Vehicles. *Bosso, A.*, +, *TMECH June 2021 1501-1511*
- A Fully Actuated Robotic Assistant for MRI-Guided Precision Conformal Ablation of Brain Tumors. *Li*, *G*., +, *TMECH Feb. 2021 255-266*
- A Laser-Guided Solution to Manipulate Mobile Robot Arm Terminals Within a Large Workspace. *Li*, *F*., +, *TMECH Oct. 2021 2676-2687*
- A New Position Detection and Status Monitoring System for Joint of SCARA. Lu, W., +, TMECH June 2021 1613-1623
- A Novel Rotational Actuator With Variable Stiffness Using S-Shaped Springs. Xu, Y, +, TMECH Aug. 2021 2249-2260
- A Position Sensorless Torque Control Strategy for Switched Reluctance Machines With Fewer Current Sensors. *Gan, C.*, +, *TMECH April 2021* 1118-1128
- A Surgical Robotic System for Treatment of Pelvic Osteolysis Using an FBG-Equipped Continuum Manipulator and Flexible Instruments. *Sefati, S.*, +, *TMECH Feb. 2021 369-380*
- A Tilting-Rotor Unmanned Aerial Vehicle for Enhanced Aerial Locomotion and Manipulation Capabilities: Design, Control, and Applications. *Ding, C.*, +, *TMECH Aug. 2021 2237-2248*
- A Visual Servo-Based Predictive Control With Echo State Gaussian Process for Soft Bending Actuator. *Cao, Y., +, TMECH Feb. 2021 574-585*
- An Output Feedback Based Robust Saturated Controller Design for Pavement Sweeping Self-Reconfigurable Robot. *Rayguru, M.M.*, +, *TMECH June 2021 1236-1247*

- Analytical Design and Experimental Verification of Geofencing Control for Aerial Applications. *Ghaffari, A., TMECH April 2021 1106-1117*
- Compliant Bistable Grippers Enable Passive Perching for Micro Aerial Vehicles. Zhang, H., +, TMECH Oct. 2021 2316-2326
- Design and Experimental Validation of a Novel High-Speed Omnidirectional Underwater Propulsion Mechanism. *Njaka, T.*, +, *TMECH Oct. 2021* 2339-2349
- Design and Real-Time Optimization for a Magnetic Actuation System With Enhanced Flexibility. *Du*, *X*., +, *TMECH June 2021 1524-1535*
- Distributed Control Algorithm for Leader–Follower Formation Tracking of Multiple Quadrotors: Theory and Experiment. *Wang, Z.*, +, *TMECH April* 2021 1095-1105
- Distributed Formation Control Using Fuzzy Self-Tuning of Strictly Negative Imaginary Consensus Controllers in Aerial Robotics. *Tran, V.P.*, +, *TMECH Oct. 2021 2306-2315*
- Dynamic Modeling and State Estimation of Cable-Conduit Actuation During Interaction With Nonpassive Environments. *Buchanan, S.*, +, *TMECH Oct.* 2021 2462-2471
- Dynamic Path Correction of an Industrial Robot Using a Distance Sensor and an ADRC Controller. *Khaled, T.A.*, +, *TMECH June 2021 1646-1656*
- Dynamic Torso Compliance Control for Standing and Walking Balance of Position-Controlled Humanoid Robots. *Li*, *Q*., +, *TMECH April 2021 679-688*
- Efficiency Optimization Strategy for Switched Reluctance Generator System With Position Sensorless Control. *Chen, H., +, TMECH Feb. 2021* 469-479
- Façade Cleaning Robot With Manipulating and Sensing Devices Equipped on a Gondola. Chae, H., +, TMECH Aug. 2021 1719-1727
- Hybrid Control Strategy for Force and Precise End Effector Positioning of a Twisted String Actuator. Rodriguez, A.S., +, TMECH Oct. 2021 2791-2802
- Identification of a Nonlinear Dielectric Elastomer Actuator Based on the Harmonic Balance Method. *Bernat, J.*, +, *TMECH Oct. 2021 2664-2675*
- Loop-Closure Detection With a Multiresolution Point Cloud Histogram Mode in Lidar Odometry and Mapping for Intelligent Vehicles. *Meng*, *Q*., +, *TMECH June 2021 1307-1317*
- Magnetically Levitated Linear Drive Using an Active Gravity Compensation Based on Hybrid Shape Memory Actuators. *Raab, M.*, +, *TMECH June* 2021 1380-1391
- Magnetically Levitated Linear Stage With Linear Bearingless Slice Hysteresis Motors. Zhou, L., +, TMECH April 2021 1084-1094
- Model-Free Control of Flexible Manipulator Based on Intrinsic Design. Jiang, N., +, TMECH Oct. 2021 2641-2652
- Modeling and Experimental Validation of a Planar Microconveyor Based on a 2 × 2 Array of Digital Electromagnetic Actuators. *Tisnes, S.D.*, +, *TMECH June 2021 1422-1432*
- Modeling and Motion Control of Industrial Tractor–Trailers Vehicles Using Force Compensation. Zhao, H., +, TMECH April 2021 645-656
- Needle Deflection Modeling and Preoperative Trajectory Planning During Insertion Into Multilayered Tissues. *Zhao, B., +, TMECH April 2021 943-954*
- Novel Joint-Drift-Free Scheme at Acceleration Level for Robotic Redundancy Resolution With Tracking Error Theoretically Eliminated. *Jin, L.*, +, *TMECH Feb. 2021 90-101*
- On Perpendicular Curve-Based Model-Less Control Considering Incomplete Orientation Constraint. Li, G., +, TMECH June 2021 1479-1489
- Point Stabilization of Nonholonomic Mobile Robot by Bézier Smooth Subline Constraint Nonlinear Model Predictive Control. Zhang, Y., +, TMECH April 2021 990-1001
- Position-Tracking Control of Dual-Rope Winch Robot With Rope Slip Compensation. Yoo, S., +, TMECH Aug. 2021 1754-1762
- Practical Fixed-Time Position Tracking Control of Permanent Magnet DC Torque Motor Systems. *Wu, Y., +, TMECH Feb. 2021 563-573*
- Quasi-Synchronization Control of Multiple Electrohydraulic Actuators With Load Disturbance and Uncertain Parameters. *Guo, Q.*, +, *TMECH Aug.* 2021 2048-2058
- Robotized Catheter With Enhanced Distal Targeting for Peripheral Pulmonary Biopsy. Kato, T., +, TMECH Oct. 2021 2451-2461

- Robust Concurrent Design of a 2-DOF Collaborative Robot (Cobot). Mendoza-Trejo, O., +, TMECH Feb. 2021 347-357
- Robust Tracking Control of a Quadrotor Unmanned Aerial Vehicle-Suspended Payload System. Xian, B., +, TMECH Oct. 2021 2653-2663
- Rotor Position Tracking Control for Low Speed Operation of Direct-Drive PMSM Servo System. *Bu*, *F*, +, *TMECH April 2021 1129-1139*
- Sliding-Mode-Disturbance-Observer-Based Robust Tracking Control for Omnidirectional Mobile Robots With Kinematic and Dynamic Uncertainties. Jeong, S., +, TMECH April 2021 741-752
- Static Position Sensor Bias Fault Diagnosis in Permanent Magnet Synchronous Machines via Current Estimation. Kuruppu, S.S., +, TMECH April 2021 888-896
- Takagi–Sugeno Fuzzy-Based Robust $H\infty$ Integrated Lane-Keeping and Direct Yaw Moment Controller of Unmanned Electric Vehicles. *Guo*, *J.*, +, *TMECH Aug. 2021 2151-2162*
- Tracking Accuracy Improvement Based on Adaptive Nonlinear Sliding Mode Control. *Tsai*, W., +, *TMECH Feb. 2021 179-190*
- Unified Motion/Force/Impedance Control for Manipulators in Unknown Contact Environments Based on Robust Model-Reaching Approach. *Lin*, *Y*, +, *TMECH Aug. 2021 1905-1913*
- Vision-Based Cutting Control of Deformable Objects With Surface Tracking. Han, L., +, TMECH Aug. 2021 2016-2026

Position measurement

- A Laser-Guided Solution to Manipulate Mobile Robot Arm Terminals Within a Large Workspace. *Li, F.*, +, *TMECH Oct. 2021 2676-2687*
- A New Position Detection and Status Monitoring System for Joint of SCARA. Lu, W., +, TMECH June 2021 1613-1623
- Modeling and Experimental Validation of a Planar Microconveyor Based on a 2 × 2 Array of Digital Electromagnetic Actuators. *Tisnes, S.D.*, +, *TMECH June 2021 1422-1432*

Power control

Real-Time Integrated Power and Thermal Management of Connected HEVs Based on Hierarchical Model Predictive Control. *Gong, X.*, +, *TMECH June 2021 1271-1282*

Power engineering computing

General Discharge Voltage Information Enabled Health Evaluation for Lithium-Ion Batteries. Deng, Z., +, TMECH June 2021 1295-1306

Power steering

Integral Sliding-Mode Tracking Control for Heavy Vehicle Electrohydraulic Power Steering System. Du, H., +, TMECH June 2021 1455-1466

Power system control

Analysis of Quasi-Zero Power Characteristic for a Permanent Magnetic Levitation System With a Variable Flux Path Control Mechanism. *Zhao, C.*, +, *TMECH Feb. 2021 437-447*

Power transmission

A Hermaphrodite Electromechanical Connector for Self-Reconfigurable Robot Modules. *Tian, X.*, +, *TMECH Dec. 2021 3276-3281*

Power transmission (mechanical)

- A Novel Wolfrom-Based Gearbox for Robotic Actuators. Crispel, S., +, TMECH Aug. 2021 1980-1988
- Experimental Investigation on Control of an Infinitely Variable Transmission System for Tidal Current Energy Converters. *Li*, *G*., +, *TMECH Aug.* 2021 1960-1967
- Nonlinear Model Predictive Control for Integrated Energy-Efficient Torque-Vectoring and Anti-Roll Moment Distribution. *Dalboni, M.*, +, *TMECH June 2021 1212-1224*
- Steady-State Characteristics Study of a Power Split Hydraulic Transmission. *Wang, F.*, +, *TMECH Feb. 2021 78-89*

Precision engineering

Sensorless Unbalance Diagnosis of Affiliated Rotating Chamber Based on Driving Current of Permanent Magnet Synchronous Motor. *Huo, X.*, +, *TMECH Dec. 2021 2899-2909*

Predictive control

- A Visual Servo-Based Predictive Control With Echo State Gaussian Process for Soft Bending Actuator. *Cao*, Y, +, *TMECH Feb. 2021 574-585*
- Autonomous Vision-Guided Object Collection From Water Surfaces With a Customized Multirotor. *Mishra, S.*, +, *TMECH Aug. 2021 1914-1922*

- Formation Reconstruction and Trajectory Replanning for Multi-UAV Patrol. Wang, Y., +, TMECH April 2021 719-729
- Guest Editorial: Focused Section on Mechatronics in Road Mobility Systems. *Ivanov, V.*, +, *TMECH June 2021 1195-1200*
- Multimodal Dynamics Analysis and Control for Amphibious Fly-Drive Vehicle. Tan, Q., +, TMECH April 2021 621-632
- Neurodynamics-Based Model Predictive Control of Continuous-Time Under-Actuated Mechatronic Systems. *Wang, J.*, +, *TMECH Feb. 2021* 311-322
- Nonlinear Model Predictive Control for Integrated Energy-Efficient Torque-Vectoring and Anti-Roll Moment Distribution. *Dalboni, M.*, +, *TMECH June 2021 1212-1224*
- Point Stabilization of Nonholonomic Mobile Robot by Bézier Smooth Subline Constraint Nonlinear Model Predictive Control. *Zhang, Y.*, +, *TMECH April 2021 990-1001*
- Real-Time Integrated Power and Thermal Management of Connected HEVs Based on Hierarchical Model Predictive Control. *Gong, X.*, +, *TMECH June 2021 1271-1282*
- Robust Nonlinear Model Predictive Control Based Visual Servoing of Quadrotor UAVs. *Zhang, K.,* +, *TMECH April 2021 700-708*
- Toward Safe and Personalized Autonomous Driving: Decision-Making and Motion Control With DPF and CDT Techniques. *Huang, C.*, +, *TMECH April 2021 611-620*

Predictive models

Prediction-Model-Based Contouring Error Iterative Precompensation Scheme for Precision Multiaxis Motion Systems. *Wang, Z.*, +, *TMECH Oct. 2021 2274-2284*

Presses

Integral Design and Manufacturing Methodology of a Reduced-Scale Servo Press. Olaizola, J., +, TMECH Oct. 2021 2418-2428

Pressure sensors

- A Compact Ankle Exoskeleton With a Multiaxis Parallel Linkage Mechanism. Lee, M., +, TMECH Feb. 2021 191-202
- A Method for Mass Flow and Displacement Estimation in a Pneumatic Actuation System Using Valve-Based Pressure Sensing. *Vailati, L.G.*, +, *TMECH Feb. 2021 235-245*
- A Suction-Based Peripheral Nerve Gripper Capable of Controlling the Suction Force. Jang, N., +, TMECH Aug. 2021 1867-1876

Sensor-Fault-Tolerant Operation for the Independent Metering Control System. Ding, R., +, TMECH Oct. 2021 2558-2569

Preventive maintenance

An Efficient Design Solution for a Low-Cost High-G Centrifuge System. Mohajer, N., +, TMECH Feb. 2021 134-145

Principal component analysis

Kernel Principal Components Analysis of Lateral Force Data for Quantitative Evaluation of 3D Features Rendering Fidelity. *Liu, G., +, TMECH June 2021 1602-1612*

Printed circuits

Testing of a Strained Silicon Based 3-D Stress Sensor for Out-of-Plane Stress Measurements. *Balbola, A.A.*, +, *TMECH April 2021 1076-1083*

Printing

Robotic Prototyping of Paper-Based Field-Effect Transistors With Rolled-Up Semiconductor Microtubes. *Dong, X.*, +, *TMECH Feb. 2021* 427-436

Probability

Dual Fast Marching Tree Algorithm for Human-Like Motion Planning of Anthropomorphic Arms With Task Constraints. Xia, J., +, TMECH Oct. 2021 2803-2813

Probes

A Mechanism-Image Fusion Approach to Calibration of an Ultrasound-Guided Dual-Arm Robotic Brachytherapy System. *Xiong, J.*, +, *TMECH Dec. 2021 3211-3220*

Process monitoring

Generative Adversarial Network for Prediction of Workpiece Surface Topography in Machining Stage. *Cao, L.*, +, *TMECH Feb. 2021 480-490* **Production engineering computing**

Generative Adversarial Network for Prediction of Workpiece Surface Topography in Machining Stage. Cao, L., +, TMECH Feb. 2021 480-490

Toolpath Regeneration in Subregional Contour-Parallel Processing Based on Isoscallop Method. *Ma*, *J.*, +, *TMECH April 2021 730-740*

Production management

Integral Design and Manufacturing Methodology of a Reduced-Scale Servo Press. Olaizola, J., +, TMECH Oct. 2021 2418-2428

Prosthetics

- A Surgical Robotic System for Treatment of Pelvic Osteolysis Using an FBG-Equipped Continuum Manipulator and Flexible Instruments. *Sefati, S.*, +, *TMECH Feb. 2021 369-380*
- Characterization of a Packaged Triboelectric Harvester Under Simulated Gait Loading for Total Knee Replacement. *Hossain, N.A.*, +, *TMECH Dec.* 2021 2967-2976
- Mechanical Aspects of Robot Hands, Active Hand Orthoses, and Prostheses: A Comparative Review. Vertongen, J., +, TMECH April 2021 955-965
- Mechanism and Controller Design of a Transfemoral Prosthesis With Electrohydraulic Knee and Motor-Driven Ankle. *Gao, S.*, +, *TMECH Oct.* 2021 2429-2439

Prototypes

- Characterization of a Packaged Triboelectric Harvester Under Simulated Gait Loading for Total Knee Replacement. *Hossain, N.A.*, +, *TMECH Dec.* 2021 2967-2976
- Overcoming the Torque/Stiffness Range Tradeoff in Antagonistic Variable Stiffness Actuators. *Mengacci, R., +, TMECH Dec. 2021 3186-3197*

Pulleys

Position-Tracking Control of Dual-Rope Winch Robot With Rope Slip Compensation. Yoo, S., +, TMECH Aug. 2021 1754-1762

Pumps

- Analytical Harmonic Method for Modeling High-Frequency Oscillation With Applications to Aircraft Piston Pump Vibration Analysis. *Li*, *L.*, +, *TMECH April 2021 918-929*
- Steady-State Characteristics Study of a Power Split Hydraulic Transmission. Wang, F., +, TMECH Feb. 2021 78-89

Q

A Piezoelectric Microultrasonic Motor With High Q and Good Mode Match. Zhou, W., +, TMECH Aug. 2021 1773-1781

Q-learning

Q factor

Optimized Interaction Control for Robot Manipulator Interacting With Flexible Environment. *Liu*, *X.*, +, *TMECH Dec. 2021 2888-2898*

Quadratic programming

- A Circadian Rhythms Neural Network for Solving the Redundant Robot Manipulators Tracking Problem Perturbed by Periodic Noise. *Zhang, Z.*, +, *TMECH Dec. 2021 3232-3242*
- Dynamic Torso Compliance Control for Standing and Walking Balance of Position-Controlled Humanoid Robots. *Li*, *Q*., +, *TMECH April 2021 679-688*
- Regularized Hierarchical Quadratic Program for Real-Time Whole-Body Motion Generation. *Hong*, S., +, *TMECH Aug*. 2021 2115-2126
- Takagi–Sugeno Fuzzy-Based Robust H∞ Integrated Lane-Keeping and Direct Yaw Moment Controller of Unmanned Electric Vehicles. Guo, J., +, TMECH Aug. 2021 2151-2162

R

Radial basis function networks

Finite-Time Synchronization Control for Bilateral Teleoperation Systems With Asymmetric Time-Varying Delay and Input Dead Zone. *Bao, J.*, +, *TMECH June 2021 1570-1580*

Radio frequency

Feature Analyses and Modeling of Lithium-Ion Battery Manufacturing Based on Random Forest Classification. *Liu, K.*, +, *TMECH Dec. 2021* 2944-2955

Rails

Geometrical-Based Displacement Measurement With Pseudostereo Monocular Camera on Bidirectional Cascaded Linear Actuator. *Lee, D.*, +, *TMECH Aug. 2021 1923-1931*

Railway engineering

Geometrical-Based Displacement Measurement With Pseudostereo Monocular Camera on Bidirectional Cascaded Linear Actuator. *Lee, D.*, +, *TMECH Aug. 2021 1923-1931*

Rapid prototyping (industrial)

- Design, Modeling, and Control of a 3D Printed Monolithic Soft Robotic Finger With Embedded Pneumatic Sensing Chambers. *Tawk, C.*, +, *TMECH April 2021 876-887*
- Robotic Prototyping of Paper-Based Field-Effect Transistors With Rolled-Up Semiconductor Microtubes. Dong, X., +, TMECH Feb. 2021 427-436

Real-time systems

- An Active Sense and Avoid System for Flying Robots in Dynamic Environments. Chen, G., +, TMECH April 2021 668-678
- Guest Editorial: Focused Section on Mechatronics in Road Mobility Systems. *Ivanov, V.*, +, *TMECH June 2021 1195-1200*
- Integrated Predictive Powertrain Control for a Multimode Plug-in Hybrid Electric Vehicle. *Oncken, J.*, +, *TMECH June 2021 1248-1259*
- Sensing and Reconstruction of 3-D Deformation on Pneumatic Soft Robots. Scharff, R.B.N., +, TMECH Aug. 2021 1877-1885

Recurrent neural networks

A Visual Servo-Based Predictive Control With Echo State Gaussian Process for Soft Bending Actuator. *Cao*, Y, +, *TMECH Feb. 2021 574-585*

Recursive estimation

Unified Motion/Force/Impedance Control for Manipulators in Unknown Contact Environments Based on Robust Model-Reaching Approach. *Lin*, *Y*, +, *TMECH Aug. 2021 1905-1913*

Recursive filters

An Adaptive Fault-Tolerant EKF for Vehicle State Estimation With Partial Missing Measurements. *Wang, Y., +, TMECH June 2021 1318-1327*

Reduced order systems

Computationally Improved State-Dependent Riccati Equation Scheme for Nonlinear Benchmark System. *Lin, L., TMECH April 2021 1064-1075*

Redundancy

Sensor-Fault-Tolerant Operation for the Independent Metering Control System. Ding, R., +, TMECH Oct. 2021 2558-2569

Redundant manipulators

A Hybrid Active and Passive Cable-Driven Segmented Redundant Manipulator: Design, Kinematics, and Planning. *Liu*, *T.*, +, *TMECH April 2021* 930-942

Modified Configuration Control With Potential Field for Inverse Kinematic Solution of Redundant Manipulator. *Kim, J.*, +, *TMECH Aug. 2021 1782-1790*

Novel Joint-Drift-Free Scheme at Acceleration Level for Robotic Redundancy Resolution With Tracking Error Theoretically Eliminated. *Jin*, *L.*, +, *TMECH Feb.* 2021 90-101

Regression analysis

An Electrical Impedance Tomography Based Interface for Human–Robot Collaboration. Zheng, E., +, TMECH Oct. 2021 2373-2384

General Discharge Voltage Information Enabled Health Evaluation for Lithium-Ion Batteries. Deng, Z., +, TMECH June 2021 1295-1306

Intelligent Fault Diagnosis of a Reciprocating Compressor Using Mode Isolation Convolutional Deep Belief Networks. *Zhang, Y.*, +, *TMECH June* 2021 1668-1677

MEMS-Enabled Retrofitting of Automobile Wheel Balancer for Automatic Unbalance Detection. *Pozzato, G.,* +, *TMECH April 2021 830-840*

Rehabilitation robotics

Human–Robot Cooperation Control Based on Trajectory Deformation Algorithm for a Lower Limb Rehabilitation Robot. Zhou, J., +, TMECH Dec. 2021 3128-3138

Reliability

- A Two-Finger Soft-Robotic Gripper With Enveloping and Pinching Grasping Modes. *Liu*, S., +, *TMECH Feb. 2021 146-155*
- Automated In Situ Placing of Metal Components Into 3-D Printed FFF Objects. Ahlers, D., +, TMECH Aug. 2021 1886-1894
- Electrical Parameter Identification of Medium-Frequency DC Resistance Spot Welding System Using Intelligent Algorithm. *Wang, X.*, +, *TMECH Aug. 2021 1791-1802*

Integral Design and Manufacturing Methodology of a Reduced-Scale Servo Press. Olaizola, J., +, TMECH Oct. 2021 2418-2428

Structural Failure Detection Using Wireless Transmission Rate From Piezoelectric Energy Harvesters. Jung, H.J., +, TMECH Aug. 2021 1708-1718

Reluctance generators

Efficiency Optimization Strategy for Switched Reluctance Generator System With Position Sensorless Control. *Chen, H., +, TMECH Feb. 2021* 469-479

Reluctance machines

A Position Sensorless Torque Control Strategy for Switched Reluctance Machines With Fewer Current Sensors. *Gan, C., +, TMECH April 2021* 1118-1128

Reluctance motor drives

A Position Sensorless Torque Control Strategy for Switched Reluctance Machines With Fewer Current Sensors. *Gan, C., +, TMECH April 2021* 1118-1128

Reluctance motors

- A Position Sensorless Torque Control Strategy for Switched Reluctance Machines With Fewer Current Sensors. *Gan, C.*, +, *TMECH April 2021* 1118-1128
- Development of FW and MTPV Control for SynRM via Feedforward Voltage Angle Control. Chen, S., +, TMECH Dec. 2021 3254-3264

Remotely operated vehicles

- A Computational-Effective Field-Oriented Control Strategy for Accurate and Efficient Electric Propulsion of Unmanned Aerial Vehicles. *Bosso, A.*, +, *TMECH June 2021 1501-1511*
- A Tilting-Rotor Unmanned Aerial Vehicle for Enhanced Aerial Locomotion and Manipulation Capabilities: Design, Control, and Applications. *Ding, C.*, +, *TMECH Aug. 2021 2237-2248*
- Analytical Design and Experimental Verification of Geofencing Control for Aerial Applications. *Ghaffari, A., TMECH April 2021 1106-1117*
- Design and Control of Soft Unmanned Aerial Vehicle "S-CLOUD". Song, S.H., +, TMECH Feb. 2021 267-275
- Design and Experimental Validation of Robust Self-Scheduled Fault-Tolerant Control Laws for a Multicopter UAV. *Nguyen, D.*, +, *TMECH Oct.* 2021 2548-2557
- Dimensionless Model-Based System Tracking Via Augmented Kalman Filter for Multiscale Unmanned Ground Vehicles. *Sun, C.*, +, *TMECH April* 2021 600-610
- Distributed Formation Control Using Fuzzy Self-Tuning of Strictly Negative Imaginary Consensus Controllers in Aerial Robotics. *Tran, V.P.*, +, *TMECH Oct. 2021 2306-2315*
- Event-Triggered-Based Discrete-Time Neural Control for a Quadrotor UAV Using Disturbance Observer. Shao, S., +, TMECH April 2021 689-699
- Neurodynamics-Based Model Predictive Control of Continuous-Time Under-Actuated Mechatronic Systems. *Wang, J.*, +, *TMECH Feb. 2021* 311-322
- Takagi–Sugeno Fuzzy-Based Robust H∞ Integrated Lane-Keeping and Direct Yaw Moment Controller of Unmanned Electric Vehicles. Guo, J., +, TMECH Aug. 2021 2151-2162

Rendering (computer graphics)

- Design and Rapid Construction of a Cost-Effective Virtual Haptic Device. Wang, F, +, TMECH Feb. 2021 66-77
- Kernel Principal Components Analysis of Lateral Force Data for Quantitative Evaluation of 3D Features Rendering Fidelity. *Liu, G., +, TMECH June 2021 1602-1612*
- Optimal Current Allocation Rendering 3-D Magnetic Force Production in Hexapole Electromagnetic Actuation. *Long, F., +, TMECH Oct. 2021* 2408-2417

Rescue robots

Regularized Hierarchical Quadratic Program for Real-Time Whole-Body Motion Generation. *Hong, S.*, +, *TMECH Aug. 2021 2115-2126*

Resonators

A Piezoelectric Microultrasonic Motor With High Q and Good Mode Match. Zhou, W., +, TMECH Aug. 2021 1773-1781

Reviews

Mechanical Aspects of Robot Hands, Active Hand Orthoses, and Prostheses: A Comparative Review. Vertongen, J., +, TMECH April 2021 955-965

Riccati equations

- Computationally Improved State-Dependent Riccati Equation Scheme for Nonlinear Benchmark System. *Lin, L., TMECH April 2021 1064-1075*
- Rigidity
 - A High Range-to-Resolution Multiaxis μForce and Torque Sensing Platform. *Tiwari*, B., +, *TMECH Aug. 2021 1837-1845*
 - Design and Experimental Validation of a Miniaturized Robotic Tendon-Driven Articulated Surgical Drill for Enhancing Distal Dexterity in Minimally Invasive Spine Fusion. *Wang, Y.*, +, *TMECH Aug. 2021 1858-1866*
 - Design and Testing of a New Force-Sensing Cell Microinjector Based on Small-Stiffness Compliant Mechanism. *Wei*, *Y*, +, *TMECH April 2021* 818-829
 - Low Impedance-Guaranteed Gain-Scheduled GESO for Torque-Controlled VSA With Application of Exoskeleton-Assisted Sit-to-Stand. *Liu, L.*, +, *TMECH Aug. 2021 2080-2091*
 - Modeling of One-Ply and Two-Ply Twisted and Coiled Polymer Artificial Muscles. *Karami, F.*, +, *TMECH Feb. 2021 300-310*
 - Soft Robotic Palm With Tunable Stiffness Using Dual-Layered Particle Jamming Mechanism. Lee, J., +, TMECH Aug. 2021 1820-1827
 - Takagi–Sugeno Fuzzy-Based Robust $H\infty$ Integrated Lane-Keeping and Direct Yaw Moment Controller of Unmanned Electric Vehicles. *Guo*, *J.*, +, *TMECH Aug. 2021 2151-2162*

Rings (structures)

A Piezoelectric Microultrasonic Motor With High Q and Good Mode Match. Zhou, W., +, TMECH Aug. 2021 1773-1781

RNA

Blindly Controlled Magnetically Actuated Capsule for Noninvasive Sampling of the Gastrointestinal Microbiome. *Shokrollahi*, P., +, *TMECH Oct.* 2021 2616-2628

Road accidents

Unmanned System Safety Decision-Making Support: Analysis and Assessment of Road Traffic Accidents. *Xie, G.*, +, *TMECH April 2021 633-644*

Road safety

- Dynamic State Estimation and Control of a Heavy Tractor–Trailers Vehicle. Zhou, S., +, TMECH June 2021 1467-1478
- Quasi-LPV Interconnected Observer Design for Full Vehicle Dynamics Estimation With Hardware Experiments. *Fouka*, M., +, *TMECH Aug. 2021* 1763-1772
- Toward Safe and Personalized Autonomous Driving: Decision-Making and Motion Control With DPF and CDT Techniques. *Huang, C.*, +, *TMECH April 2021 611-620*
- Unmanned System Safety Decision-Making Support: Analysis and Assessment of Road Traffic Accidents. *Xie, G., +, TMECH April 2021 633-644* Road traffic
 - Covert Attacks Through Adversarial Learning: Study of Lane Keeping Attacks on the Safety of Autonomous Vehicles. *Farivar, F., +, TMECH June 2021 1350-1357*
 - Toward Safe and Personalized Autonomous Driving: Decision-Making and Motion Control With DPF and CDT Techniques. *Huang, C.*, +, *TMECH April 2021 611-620*

Unmanned System Safety Decision-Making Support: Analysis and Assessment of Road Traffic Accidents. Xie, G., +, TMECH April 2021 633-644

Road traffic control

Multiobjective Scheduling Strategy With Genetic Algorithm and Time-Enhanced A* Planning for Autonomous Parking Robotics in High-Density Unmanned Parking Lots. *Chen, G.,* +, *TMECH June 2021 1547-1557*

Road vehicles

- Adaptive Finite-Time Control for Half-Vehicle Active Suspension Systems With Uncertain Dynamics. *Liu*, Y, +, *TMECH Feb. 2021 168-178*
- Adaptive Output Feedback Control of Steer-by-Wire Systems With Event-Triggered Communication. *Ma*, *B*., +, *TMECH Aug. 2021 1968-1979*
- Covert Attacks Through Adversarial Learning: Study of Lane Keeping Attacks on the Safety of Autonomous Vehicles. *Farivar, F., +, TMECH June 2021 1350-1357*
- Development and Performance Enhancement of an Overactuated Autonomous Ground Vehicle. *Huang, Y., +, TMECH Feb. 2021 33-44*

- Dynamic State Estimation and Control of a Heavy Tractor–Trailers Vehicle. Zhou, S., +, TMECH June 2021 1467-1478
- Global Optimization of the Hydraulic-Electromagnetic Energy-Harvesting Shock Absorber for Road Vehicles With Human-Knowledge-Integrated Particle Swarm Optimization Scheme. *Zhou, Q., +, TMECH June 2021 1225-1235*
- Individual Auxiliary and Fault-Tolerant Control of Steer-by-Wire System Considering Different Drivers Steering Characteristics. *Zhao, W.*, +, *TMECH June 2021 1558-1569*
- Modeling and Motion Control of Industrial Tractor–Trailers Vehicles Using Force Compensation. Zhao, H., +, TMECH April 2021 645-656
- Multimodal Dynamics Analysis and Control for Amphibious Fly-Drive Vehicle. *Tan, Q.*, +, *TMECH April 2021 621-632*
- Nonlinear Model Predictive Control for Integrated Energy-Efficient Torque-Vectoring and Anti-Roll Moment Distribution. *Dalboni, M.*, +, *TMECH June 2021 1212-1224*
- Semiactively Controllable Vehicle Seat Suspension System With Negative Stiffness Magnetic Spring. *Tu, L.*, +, *TMECH Feb. 2021 156-167*
- Takagi–Sugeno Fuzzy Unknown Input Observers to Estimate Nonlinear Dynamics of Autonomous Ground Vehicles: Theory and Real-Time Verification. Nguyen, A., +, TMECH June 2021 1328-1338
- Takagi–Sugeno Fuzzy-Based Robust H∞ Integrated Lane-Keeping and Direct Yaw Moment Controller of Unmanned Electric Vehicles. Guo, J., +, TMECH Aug. 2021 2151-2162
- Toward Safe and Personalized Autonomous Driving: Decision-Making and Motion Control With DPF and CDT Techniques. *Huang, C.*, +, *TMECH April 2021 611-620*

Roads

- Simultaneous State Estimation and Tire Model Learning for Autonomous Vehicle Applications. *Jeon, W.*, +, *TMECH Aug. 2021 1941-1950*
- Robot dynamics
 - Control Parameters Design Based on Dynamic Characteristics of a Hybrid Robot With Parallelogram Structures. *Liu, Z.*, +, *TMECH April 2021 1140-1150*
 - Dynamic Torso Compliance Control for Standing and Walking Balance of Position-Controlled Humanoid Robots. *Li*, *Q*., +, *TMECH April 2021 679-688*
 - Efficient Motion Planning Based on Kinodynamic Model for Quadruped Robots Following Persons in Confined Spaces. *Zhang, Z.*, +, *TMECH Aug.* 2021 1997-2006
 - Fully Actuated Autonomous Flight of Thruster-Tilting Multirotor. Lee, S.J., +, TMECH April 2021 765-776
 - Human-in-the-Loop Control of a Wearable Lower Limb Exoskeleton for Stable Dynamic Walking. *Li*, *Z*., +, *TMECH Oct. 2021 2700-2711*
 - Low Impedance-Guaranteed Gain-Scheduled GESO for Torque-Controlled VSA With Application of Exoskeleton-Assisted Sit-to-Stand. *Liu, L.*, +, *TMECH Aug. 2021 2080-2091*
 - Modeling Quadrotor Dynamics in a Wind Field. Jeon, H., +, TMECH June 2021 1401-1411
 - Parallel Compliance Design for Increasing Robustness and Efficiency in Legged Locomotion–Theoretical Background and Applications. Sharbafi, M.A., +, TMECH Feb. 2021 335-346
 - Roller-Skating of Mammalian Quadrupedal Robot With Passive Wheels Inspired by Human. *Chen, J.*, +, *TMECH June 2021 1624-1634*
 - Swing-Reducing Flight Control System for an Underactuated Indoor Miniature Autonomous Blimp. Tao, Q., +, TMECH Aug. 2021 1895-1904
 - Terrain Identification for Humanoid Robots Applying Convolutional Neural Networks. *Venancio, M.M.*, +, *TMECH June 2021 1433-1444*

Robot kinematics

- Biomimetic Realization of a Robotic Penguin Wing: Design and Thrust Characteristics. Shen, Y., +, TMECH Oct. 2021 2350-2361
- Coordinated Dynamic Control in the Task Space for Redundantly Actuated Cable-Driven Parallel Robots. Zhang, B., +, TMECH Oct. 2021 2396-2407
- Efficient Motion Planning Based on Kinodynamic Model for Quadruped Robots Following Persons in Confined Spaces. *Zhang, Z.*, +, *TMECH Aug.* 2021 1997-2006

- Evaluation of Locomotion Performances for a Mecanum-Wheeled Hybrid Hexapod Robot. Orozco-Magdaleno, E.C., +, TMECH June 2021 1657-1667
- Focused Section on the Second Edition of TMECH/AIM Emerging Topics. *Chen, X.*, +, *TMECH Aug. 2021 1705-1707*
- Fully Actuated Autonomous Flight of Thruster-Tilting Multirotor. Lee, S.J., +, TMECH April 2021 765-776
- Guest Editorial Focused Section on Mechatronics in Unmanned Systems. He, W., +, TMECH April 2021 595-599
- Investigation of Micromotion Kinematics of Continuum Robots for Volumetric OCT and OCT-Guided Visual Servoing. *Giudice, G.D.*, +, *TMECH Oct.* 2021 2604-2615
- Kinematic Modeling and Control of Variable Curvature Soft Continuum Robots. *Huang, X.*, +, *TMECH Dec. 2021 3175-3185*
- Kinematic Modeling, Analysis, and Verification of an Essboard-Like Robot. Guan, Y., +, TMECH April 2021 864-875
- Modified Configuration Control With Potential Field for Inverse Kinematic Solution of Redundant Manipulator. *Kim, J.*, +, *TMECH Aug. 2021 1782-1790*
- Sensing and Reconstruction of 3-D Deformation on Pneumatic Soft Robots. Scharff, R.B.N., +, TMECH Aug. 2021 1877-1885

Robot learning

A Constrained DMPs Framework for Robot Skills Learning and Generalization From Human Demonstrations. *Lu*, *Z*., +, *TMECH Dec. 2021 3265-3275*

Robot motion

 A Circadian Rhythms Neural Network for Solving the Redundant Robot Manipulators Tracking Problem Perturbed by Periodic Noise. *Zhang, Z.*,
+, *TMECH Dec. 2021 3232-3242*

Robot sensing systems

- A Hermaphrodite Electromechanical Connector for Self-Reconfigurable Robot Modules. *Tian, X.*, +, *TMECH Dec. 2021 3276-3281*
- Focused Section on the Second Edition of TMECH/AIM Emerging Topics. Chen, X., +, TMECH Aug. 2021 1705-1707
- Guest Editorial Introduction to the Focused Section on Mechatronics and Automation for Constructions. *Cheah, C.C.*, +, *TMECH Dec. 2021 2819-2825*
- Modified Stiffness-Based Soft Optical Waveguide Integrated Pneumatic Artificial Muscle (PAM) Actuators for Contraction and Force Sensing. *Jamil, B., +, TMECH Dec. 2021 3243-3253*
- Robot-Assisted Object Detection for Construction Automation: Data and Information-Driven Approach. *Muhammad, 1., +, TMECH Dec. 2021* 2845-2856

Robot vision

- An Active Sense and Avoid System for Flying Robots in Dynamic Environments. Chen, G., +, TMECH April 2021 668-678
- Autonomous Vision-Guided Object Collection From Water Surfaces With a Customized Multirotor. *Mishra, S.*, +, *TMECH Aug, 2021 1914-1922*
- Collaborative Semantic Understanding and Mapping Framework for Autonomous Systems. Yue, Y., +, TMECH April 2021 978-989
- Compliant Bistable Grippers Enable Passive Perching for Micro Aerial Vehicles. Zhang, H., +, TMECH Oct. 2021 2316-2326
- Globally Optimal Symbolic Hand-Eye Calibration. *Wu, J.*, +, *TMECH June* 2021 1369-1379
- Loop-Closure Detection With a Multiresolution Point Cloud Histogram Mode in Lidar Odometry and Mapping for Intelligent Vehicles. *Meng, Q.*, +, *TMECH June 2021 1307-1317*
- Nontarget-Based Measurement of 6-DOF Structural Displacement Using Combined RGB Color and Depth Information. *Lee, S.*, +, *TMECH June* 2021 1358-1368
- Robust Nonlinear Model Predictive Control Based Visual Servoing of Quadrotor UAVs. *Zhang, K.*, +, *TMECH April 2021 700-708*
- Self-Balancing Two-Wheeled Robot Featuring Intelligent End-to-End Deep Visual-Steering. Li, C.G., +, TMECH Oct. 2021 2263-2273

Vision-Based Cutting Control of Deformable Objects With Surface Tracking. Han, L., +, TMECH Aug. 2021 2016-2026

Robot vision systems

Development of a Soft Robot Based Photodynamic Therapy for Pancreatic Cancer. Li, Y, +, TMECH Dec. 2021 2977-2985

Robotic assembly

A New Position Detection and Status Monitoring System for Joint of SCARA. Lu, W., +, TMECH June 2021 1613-1623

Robots

- A Hermaphrodite Electromechanical Connector for Self-Reconfigurable Robot Modules. *Tian, X.*, +, *TMECH Dec. 2021 3276-3281*
- A Mechanism-Image Fusion Approach to Calibration of an Ultrasound-Guided Dual-Arm Robotic Brachytherapy System. *Xiong, J.*, +, *TMECH Dec. 2021 3211-3220*
- A Novel Wolfrom-Based Gearbox for Robotic Actuators. Crispel, S., +, TMECH Aug. 2021 1980-1988
- Artificial-Delay Adaptive Control for Underactuated Euler–Lagrange Robotics. Roy, S., +, TMECH Dec. 2021 3064-3075
- Basic Input–Output Gain Tuning System Based on Control Input Histogram Leveling for Human-Operated Machines. *Kamezaki, M.*, +, *TMECH Dec.* 2021 2857-2869
- Design and Validation of a Novel Fuzzy-Logic-Based Static Feedback Controller for Tendon-Driven Continuum Robots. *Ba, W.*, +, *TMECH Dec.* 2021 3010-3021
- Development of a Soft Robot Based Photodynamic Therapy for Pancreatic Cancer. Li, Y., +, TMECH Dec. 2021 2977-2985
- Diversified and Untethered Motion Generation Via Crease Patterning from Magnetically Actuated Caterpillar-Inspired Origami Robot. Cai, C.J., +, TMECH June 2021 1678-1688
- Edge-Dependent Efficient Grasp Rectangle Search in Robotic Grasp Detection. Chen, L., +, TMECH Dec. 2021 2922-2931
- Focused Section on the Second Edition of TMECH/AIM Emerging Topics. Chen, X., +, TMECH Aug. 2021 1705-1707
- Investigation on a New Approach for Designing Articulated Soft Robots With Discrete Variable Stiffness. *Zhong, Y.*, +, *TMECH Dec. 2021 2998-3009*
- Longitudinal Motion Modeling and Experimental Verification of a Microrobot Subject to Liquid Laminar Flow. *Demircali, A.A.*, +, *TMECH Dec.* 2021 2956-2966
- Optimized Interaction Control for Robot Manipulator Interacting With Flexible Environment. *Liu*, *X*., +, *TMECH Dec. 2021 2888-2898*
- Plate-Springed Parallel Elastic Actuator for Efficient Snake Robot Movement. Kakogawa, A., +, TMECH Dec. 2021 3051-3063
- Similitude Analysis Method of the Dynamics of a Hybrid Spray-Painting Robot Considering Electromechanical Coupling Effect. *Song, Y.*, +, *TMECH Dec. 2021 2986-2997*

Slider-Tendon Linear Actuator With Under-Actuation and Fast-Connection for Soft Wearable Robots. *Kim, B., +, TMECH Dec. 2021 2932-2943*

Robust control

- A Novel Rotational Actuator With Variable Stiffness Using S-Shaped Springs. Xu, Y, +, TMECH Aug. 2021 2249-2260
- A Phase-Shaping Approach to the Control of Parametric Systems and Its Application. *Shimonomura, S.,* +, *TMECH Aug. 2021 2163-2173*
- A Tilting-Rotor Unmanned Aerial Vehicle for Enhanced Aerial Locomotion and Manipulation Capabilities: Design, Control, and Applications. *Ding, C.*, +, *TMECH Aug. 2021 2237-2248*
- Adaptive Output Feedback Control of Steer-by-Wire Systems With Event-Triggered Communication. *Ma*, *B*., +, *TMECH Aug. 2021 1968-1979*
- Adaptive Robust Finite-Time Nonlinear Control of a Typical Autonomous Underwater Vehicle With Saturated Inputs and Uncertainties. *Sedghi, F*, +, *TMECH Oct. 2021 2517-2527*
- An Output Feedback Based Robust Saturated Controller Design for Pavement Sweeping Self-Reconfigurable Robot. Rayguru, M.M., +, TMECH June 2021 1236-1247
- Analytical Design and Experimental Verification of Geofencing Control for Aerial Applications. *Ghaffari, A., TMECH April 2021 1106-1117*
- Asymptotic Tracking Control of Mechanical Servosystems With Mismatched Uncertainties. *Deng, W.*, +, *TMECH Aug. 2021 2204-2214*

- Computationally Improved State-Dependent Riccati Equation Scheme for Nonlinear Benchmark System. *Lin, L., TMECH April 2021 1064-1075*
- Coordinated Dynamic Control in the Task Space for Redundantly Actuated Cable-Driven Parallel Robots. Zhang, B., +, TMECH Oct. 2021 2396-2407
- Distributed Formation Control Using Fuzzy Self-Tuning of Strictly Negative Imaginary Consensus Controllers in Aerial Robotics. *Tran, V.P.*, +, *TMECH Oct. 2021 2306-2315*
- Efficient Cooperative Structured Control for a Multijoint Biomimetic Robotic Fish. Yan, S., +, TMECH Oct. 2021 2506-2516
- Fractional-Order Control for Uncertain Teleoperated Cyber-Physical System With Actuator Fault. Ma, Z., +, TMECH Oct. 2021 2472-2482
- Fully Actuated Autonomous Flight of Thruster-Tilting Multirotor. Lee, S.J., +, TMECH April 2021 765-776
- Intelligent Vibration Control for Semiactive Suspension Systems Without Prior Knowledge of Dynamical Nonlinear Damper Behaviors Based on Improved Extreme Learning Machine. *Huang, W.*, +, *TMECH Aug. 2021* 2071-2079
- Markovian Robust Filtering and Control Applied to Rehabilitation Robotics. Escalante, F.M., +, TMECH Feb. 2021 491-502
- Modeling and Motion Control of Industrial Tractor–Trailers Vehicles Using Force Compensation. Zhao, H., +, TMECH April 2021 645-656
- Path Following of Wheeled Mobile Robots Using Online-Optimization-Based Guidance Vector Field. *Chen, J.*, +, *TMECH Aug. 2021 1737-1744*
- Proportional-Integral Approximation-Free Control of Robotic Systems With Unknown Dynamics. *Zhang, C.*, +, *TMECH Aug. 2021 2226-2236*
- Quasi-Synchronization Control of Multiple Electrohydraulic Actuators With Load Disturbance and Uncertain Parameters. Guo, Q., +, TMECH Aug. 2021 2048-2058
- Robust Adaptive Tracking Control of Underwater Vehicles: Design, Stability Analysis, and Experiments. *Tijjani, A.S.*, +, *TMECH April 2021 897-907*
- Robust Concurrent Design of a 2-DOF Collaborative Robot (Cobot). Mendoza-Trejo, O., +, TMECH Feb. 2021 347-357
- Robust Nonlinear Model Predictive Control Based Visual Servoing of Quadrotor UAVs. *Zhang, K.,* +, *TMECH April 2021 700-708*
- Robust Tracking Control of a Quadrotor Unmanned Aerial Vehicle-Suspended Payload System. Xian, B., +, TMECH Oct. 2021 2653-2663
- Rotor Position Tracking Control for Low Speed Operation of Direct-Drive PMSM Servo System. Bu, F., +, TMECH April 2021 1129-1139
- Sliding-Mode-Disturbance-Observer-Based Robust Tracking Control for Omnidirectional Mobile Robots With Kinematic and Dynamic Uncertainties. Jeong, S., +, TMECH April 2021 741-752
- Stability and Robustness of the Disturbance Observer-Based Motion Control Systems in Discrete-Time Domain. *Sariyildiz, E., +, TMECH Aug. 2021* 2139-2150
- Unified Motion/Force/Impedance Control for Manipulators in Unknown Contact Environments Based on Robust Model-Reaching Approach. *Lin*, *Y*, +, *TMECH Aug. 2021 1905-1913*

Rolling bearings

Weighted Entropy Minimization Based Deep Conditional Adversarial Diagnosis Approach Under Variable Working Conditions. She, D., +, TMECH Oct. 2021 2440-2450

Ropes

- Position-Tracking Control of Dual-Rope Winch Robot With Rope Slip Compensation. *Yoo, S.,* +, *TMECH Aug. 2021 1754-1762*
- Vibration Reduction of Flexible Rope-Driven Mobile Robot for Safe Façade Operation. Seo, M., +, TMECH Aug. 2021 1812-1819

Rotors

- A Computational-Effective Field-Oriented Control Strategy for Accurate and Efficient Electric Propulsion of Unmanned Aerial Vehicles. *Bosso, A.*, +, *TMECH June 2021 1501-1511*
- A Piezoelectric Microultrasonic Motor With High Q and Good Mode Match. Zhou, W., +, TMECH Aug. 2021 1773-1781
- A Position Sensorless Torque Control Strategy for Switched Reluctance Machines With Fewer Current Sensors. *Gan, C.*, +, *TMECH April 2021* 1118-1128

- A Tilting-Rotor Unmanned Aerial Vehicle for Enhanced Aerial Locomotion and Manipulation Capabilities: Design, Control, and Applications. *Ding, C.*, +, *TMECH Aug. 2021 2237-2248*
- Design and Experimental Validation of a Novel High-Speed Omnidirectional Underwater Propulsion Mechanism. *Njaka, T., +, TMECH Oct. 2021* 2339-2349
- Design Principles for Compact, Backdrivable Actuation in Partial-Assist Powered Knee Orthoses. Zhu, H., +, TMECH Dec. 2021 3104-3115
- Design Process and Verification of SPMSM for a Wearable Robot Considering Thermal Characteristics Through LPTN. Hwang, S., +, TMECH April 2021 1033-1042
- Multimodal Dynamics Analysis and Control for Amphibious Fly-Drive Vehicle. *Tan, Q.*, +, *TMECH April 2021 621-632*
- Online Compensation of Mechanical Load Defects With Composite Control in PMSM Drives. *Kommuri, S.K.*, +, *TMECH June 2021 1392-1400*
- Rotor Balancing for Magnetically Levitated TMPs Integrated With Vibration Self-Sensing of Magnetic Bearings. *Zheng, S.*, +, *TMECH Dec. 2021* 3031-3039
- Rotor Position Tracking Control for Low Speed Operation of Direct-Drive PMSM Servo System. *Bu*, *F*, +, *TMECH April 2021 1129-1139*
- Static Position Sensor Bias Fault Diagnosis in Permanent Magnet Synchronous Machines via Current Estimation. Kuruppu, S.S., +, TMECH April 2021 888-896

Runge-Kutta methods

Computationally Efficient Practical Method for Solving the Dynamics of Fluid Power Circuits in the Presence of Singularities. *Malysheva*, J., +, *TMECH Oct. 2021 2385-2395*

S

- A Constrained DMPs Framework for Robot Skills Learning and Generalization From Human Demonstrations. *Lu*, *Z*., +, *TMECH Dec. 2021 3265-3275*
- An Efficient Design Solution for a Low-Cost High-G Centrifuge System. Mohajer, N., +, TMECH Feb. 2021 134-145
- Guest Editorial: Focused Section on Mechatronics in Road Mobility Systems. Ivanov, V., +, TMECH June 2021 1195-1200

Sampling methods

Safety

Actuation Frequency Modeling and Prediction for Shape Memory Alloy Actuators. *Liu, X., +, TMECH June 2021 1536-1546*

Saturation magnetization

Rotor Balancing for Magnetically Levitated TMPs Integrated With Vibration Self-Sensing of Magnetic Bearings. *Zheng, S.*, +, *TMECH Dec. 2021* 3031-3039

Scheduling

- Cyber–Physical Codesign of Field-Level Reconfigurations in Networked Motion Controllers. *Zhou*, *N*., +, *TMECH Aug. 2021 2092-2103*
- Multiobjective Scheduling Strategy With Genetic Algorithm and Time-Enhanced A* Planning for Autonomous Parking Robotics in High-Density Unmanned Parking Lots. *Chen, G.,* +, *TMECH June 2021 1547-1557*

Search problems

A Novel Clustering-Based Algorithm for Solving Spatially Constrained Robotic Task Sequencing Problems. *Wong, C.*, +, *TMECH Oct. 2021 2294-2305*

Edge-Dependent Efficient Grasp Rectangle Search in Robotic Grasp Detection. Chen, L., +, TMECH Dec. 2021 2922-2931

Seats

Semiactively Controllable Vehicle Seat Suspension System With Negative Stiffness Magnetic Spring. *Tu, L., +, TMECH Feb. 2021 156-167*

Secondary cells

- General Discharge Voltage Information Enabled Health Evaluation for Lithium-Ion Batteries. Deng, Z., +, TMECH June 2021 1295-1306
- Global Parameter Sensitivity Analysis of Electrochemical Model for Lithium-Ion Batteries Considering Aging. *Gao, Y.*, +, *TMECH June 2021 1283-1294*

Security of data

- Covert Attacks Through Adversarial Learning: Study of Lane Keeping Attacks on the Safety of Autonomous Vehicles. *Farivar, F., +, TMECH June 2021 1350-1357*
- Self-adjusting systems
 - Development of Embedded Sensor System for 5-DOF Finger-Wearable Tactile Interface. *Lim, B., +, TMECH Aug. 2021 1728-1736*
 - Distributed Formation Control Using Fuzzy Self-Tuning of Strictly Negative Imaginary Consensus Controllers in Aerial Robotics. *Tran, V.P.*, +, *TMECH Oct. 2021 2306-2315*

Sensitivity analysis

- Actuation Frequency Modeling and Prediction for Shape Memory Alloy Actuators. *Liu*, X., +, *TMECH June 2021 1536-1546*
- Global Parameter Sensitivity Analysis of Electrochemical Model for Lithium-Ion Batteries Considering Aging. *Gao, Y.*, +, *TMECH June 2021 1283-1294*

Sensor fusion

- An Active Sense and Avoid System for Flying Robots in Dynamic Environments. Chen, G., +, TMECH April 2021 668-678
- Real-Time Avoidance Strategy of Dynamic Obstacles via Half Model-Free Detection and Tracking With 2D Lidar for Mobile Robots. *Dong, H.*, +, *TMECH Aug. 2021 2215-2225*

Sensing and Reconstruction of 3-D Deformation on Pneumatic Soft Robots. Scharff, R.B.N., +, TMECH Aug. 2021 1877-1885

Sensorless machine control

A Position Sensorless Torque Control Strategy for Switched Reluctance Machines With Fewer Current Sensors. *Gan, C.*, +, *TMECH April 2021* 1118-1128

Efficiency Optimization Strategy for Switched Reluctance Generator System With Position Sensorless Control. *Chen, H., +, TMECH Feb. 2021* 469-479

Sensors

- A Laser-Guided Solution to Manipulate Mobile Robot Arm Terminals Within a Large Workspace. *Li*, *F*, +, *TMECH Oct. 2021 2676-2687*
- Design and Control of Soft Unmanned Aerial Vehicle "S-CLOUD". Song, S.H., +, TMECH Feb. 2021 267-275
- Dynamic State Estimation and Control of a Heavy Tractor–Trailers Vehicle. Zhou, S., +, TMECH June 2021 1467-1478
- MEMS-Enabled Retrofitting of Automobile Wheel Balancer for Automatic Unbalance Detection. *Pozzato, G.,* +, *TMECH April 2021 830-840*
- Modified Stiffness-Based Soft Optical Waveguide Integrated Pneumatic Artificial Muscle (PAM) Actuators for Contraction and Force Sensing. *Jamil, B.*, +, *TMECH Dec. 2021 3243-3253*
- On-Body RF Sensor Toward Tremor Detection in Parkinson's Disease. Abirami B, S., +, TMECH Oct. 2021 2814-2817
- Radial Coverage Strength for Optimization of Monocular Multicamera Deployment. Lei, Z., +, TMECH Dec. 2021 3221-3231
- Robot-Assisted Object Detection for Construction Automation: Data and Information-Driven Approach. *Muhammad, 1.*, +, *TMECH Dec. 2021* 2845-2856
- Sensorless Unbalance Diagnosis of Affiliated Rotating Chamber Based on Driving Current of Permanent Magnet Synchronous Motor. *Huo, X.*, +, *TMECH Dec. 2021 2899-2909*
- Static Position Sensor Bias Fault Diagnosis in Permanent Magnet Synchronous Machines via Current Estimation. Kuruppu, S.S., +, TMECH April 2021 888-896
- Tendon-Inspired Piezoelectric Sensor for Biometric Application. Kim, H., +, TMECH Oct. 2021 2538-2547
- Testing of a Strained Silicon Based 3-D Stress Sensor for Out-of-Plane Stress Measurements. *Balbola, A.A.*, +, *TMECH April 2021 1076-1083*

Servers

Development of a Concrete Floating and Delamination Detection System Using Infrared Thermography. *Chun, P.,* +, *TMECH Dec. 2021 2835-2844* Service robots

A Circadian Rhythms Neural Network for Solving the Redundant Robot Manipulators Tracking Problem Perturbed by Periodic Noise. *Zhang, Z.*, +, *TMECH Dec. 2021 3232-3242*

- Façade Cleaning Robot With Manipulating and Sensing Devices Equipped on a Gondola. Chae, H., +, TMECH Aug. 2021 1719-1727
- Guest Editorial Focused Section on Mechatronics in Unmanned Systems. He, W., +, TMECH April 2021 595-599
- Guest Editorial Introduction to the Focused Section on Mechatronics and Automation for Constructions. *Cheah, C.C.*, +, *TMECH Dec. 2021 2819-2825*
- OrthographicNet: A Deep Transfer Learning Approach for 3-D Object Recognition in Open-Ended Domains. *Kasaei, S.H., TMECH Dec. 2021 2910-2921*
- Similitude Analysis Method of the Dynamics of a Hybrid Spray-Painting Robot Considering Electromechanical Coupling Effect. *Song, Y.*, +, *TMECH Dec. 2021 2986-2997*

Servomechanisms

- Asymptotic Tracking Control of Mechanical Servosystems With Mismatched Uncertainties. *Deng, W.*, +, *TMECH Aug. 2021 2204-2214*
- Design and Experimental Validation of a Novel High-Speed Omnidirectional Underwater Propulsion Mechanism. *Njaka, T.*, +, *TMECH Oct. 2021* 2339-2349
- Fully Actuated Autonomous Flight of Thruster-Tilting Multirotor. Lee, S.J., +, TMECH April 2021 765-776
- Integral Design and Manufacturing Methodology of a Reduced-Scale Servo Press. Olaizola, J., +, TMECH Oct. 2021 2418-2428
- Rotor Position Tracking Control for Low Speed Operation of Direct-Drive PMSM Servo System. *Bu*, *F*., +, *TMECH April 2021 1129-1139*
- Stability and Robustness of the Disturbance Observer-Based Motion Control Systems in Discrete-Time Domain. *Sariyildiz, E., +, TMECH Aug. 2021* 2139-2150

Servomotors

A Tilting-Rotor Unmanned Aerial Vehicle for Enhanced Aerial Locomotion and Manipulation Capabilities: Design, Control, and Applications. *Ding*, *C.*, +, *TMECH Aug*. 2021 2237-2248

Tracking Accuracy Improvement Based on Adaptive Nonlinear Sliding Mode Control. *Tsai*, W., +, *TMECH Feb. 2021 179-190*

Shafts

- A Hermaphrodite Electromechanical Connector for Self-Reconfigurable Robot Modules. *Tian, X.*, +, *TMECH Dec. 2021 3276-3281*
- Overcoming the Torque/Stiffness Range Tradeoff in Antagonistic Variable Stiffness Actuators. *Mengacci, R., +, TMECH Dec. 2021 3186-3197*
- Sensorless Unbalance Diagnosis of Affiliated Rotating Chamber Based on Driving Current of Permanent Magnet Synchronous Motor. *Huo, X.*, +, *TMECH Dec. 2021 2899-2909*
- Steady-State Characteristics Study of a Power Split Hydraulic Transmission. Wang, F., +, TMECH Feb. 2021 78-89

Shape measurement

Investigation on a New Approach for Designing Articulated Soft Robots With Discrete Variable Stiffness. *Zhong, Y.*, +, *TMECH Dec. 2021 2998*-*3009*

Shape memory effects

- Actuation Frequency Modeling and Prediction for Shape Memory Alloy Actuators. *Liu, X.*, +, *TMECH June 2021 1536-1546*
- Development of Embedded Sensor System for 5-DOF Finger-Wearable Tactile Interface. *Lim, B., +, TMECH Aug. 2021 1728-1736*
- Magnetically Levitated Linear Drive Using an Active Gravity Compensation Based on Hybrid Shape Memory Actuators. *Raab, M.*, +, *TMECH June* 2021 1380-1391

Shock absorbers

- Global Optimization of the Hydraulic-Electromagnetic Energy-Harvesting Shock Absorber for Road Vehicles With Human-Knowledge-Integrated Particle Swarm Optimization Scheme. *Zhou, Q., +, TMECH June 2021 1225-1235*
- Intelligent Vibration Control for Semiactive Suspension Systems Without Prior Knowledge of Dynamical Nonlinear Damper Behaviors Based on Improved Extreme Learning Machine. *Huang, W.*, +, *TMECH Aug. 2021* 2071-2079
- Mechanism and Controller Design of a Transfemoral Prosthesis With Electrohydraulic Knee and Motor-Driven Ankle. *Gao, S.*, +, *TMECH Oct. 2021* 2429-2439

Semiactively Controllable Vehicle Seat Suspension System With Negative Stiffness Magnetic Spring. *Tu, L.*, +, *TMECH Feb. 2021 156-167*

Shock waves

A Lightweight Wireless Overpressure Node Based Efficient Monitoring for Shock Waves. *Gao*, S., +, *TMECH Feb. 2021 448-457*

Silicon

- Testing of a Strained Silicon Based 3-D Stress Sensor for Out-of-Plane Stress Measurements. *Balbola, A.A.*, +, *TMECH April 2021 1076-1083* Silicones
 - Automated Retinal Vein Cannulation on Silicone Phantoms Using Optical-Coherence-Tomography-Guided Robotic Manipulations. *Gerber, M.J.*, +, *TMECH Oct. 2021 2758-2769*

Silver

Robotic Prototyping of Paper-Based Field-Effect Transistors With Rolled-Up Semiconductor Microtubes. *Dong, X.*, +, *TMECH Feb. 2021 427-436*

Singular value decomposition

- Modified Configuration Control With Potential Field for Inverse Kinematic Solution of Redundant Manipulator. *Kim, J.*, +, *TMECH Aug. 2021 1782-1790*
- Regularized Hierarchical Quadratic Program for Real-Time Whole-Body Motion Generation. *Hong*, S., +, *TMECH Aug. 2021 2115-2126*

SLAM (robots)

- Collaborative Semantic Understanding and Mapping Framework for Autonomous Systems. Yue, Y., +, TMECH April 2021 978-989
- Efficient Bathymetric SLAM With Invalid Loop Closure Identification. Teng, M., +, TMECH Oct. 2021 2570-2580
- Loop-Closure Detection With a Multiresolution Point Cloud Histogram Mode in Lidar Odometry and Mapping for Intelligent Vehicles. *Meng, Q.*, +, *TMECH June 2021 1307-1317*

Smart phones

Amaran:An Unmanned Robotic Coconut Tree Climber and Harvester. Megalingam, R.K., +, TMECH Feb. 2021 288-299

Smoothing methods

- A Smoothed Raster Scanning Trajectory Based on Acceleration-Continuous B-Spline Transition for High-Speed Atomic Force Microscopy. *Li*, *L.*, +, *TMECH Feb. 2021 24-32*
- Erratum to "A Smoothed Raster Scanning Trajectory Based on Acceleration-Continuous B-Spline Transition for High-Speed Atomic Force Microscopy" [Feb 21 24-32]. *Li*, *L.*, +, *TMECH June 2021 1700*

Snake robots

Plate-Springed Parallel Elastic Actuator for Efficient Snake Robot Movement. Kakogawa, A., +, TMECH Dec. 2021 3051-3063

Socio-economic effects

Integral Design and Manufacturing Methodology of a Reduced-Scale Servo Press. Olaizola, J., +, TMECH Oct. 2021 2418-2428

Soft robotics

- Development of a Soft Robot Based Photodynamic Therapy for Pancreatic Cancer. Li, Y., +, TMECH Dec. 2021 2977-2985
- Focused Section on the Second Edition of TMECH/AIM Emerging Topics. Chen, X., +, TMECH Aug. 2021 1705-1707
- Investigation on a New Approach for Designing Articulated Soft Robots With Discrete Variable Stiffness. *Zhong, Y., +, TMECH Dec. 2021 2998-3009*
- Kinematic Modeling and Control of Variable Curvature Soft Continuum Robots. *Huang, X.*, +, *TMECH Dec. 2021 3175-3185*
- On the Mechanical Power Output Comparisons of Cone Dielectric Elastomer Actuators. Cao, C., +, TMECH Dec. 2021 3151-3162
- On the Mechanical Power Output Comparisons of Cone Dielectric Elastomer Actuators. Cao, C., +, TMECH Dec. 2021 3151-3162
- Overcoming the Torque/Stiffness Range Tradeoff in Antagonistic Variable Stiffness Actuators. *Mengacci, R., +, TMECH Dec. 2021 3186-3197*

Soil measurements

Automatic Construction of Three-Dimensional Ground Model by Data Processing. *Takeyama*, *T.*, +, *TMECH Dec.* 2021 2881-2887

Solenoids

A Method for Mass Flow and Displacement Estimation in a Pneumatic Actuation System Using Valve-Based Pressure Sensing. Vailati, L.G., +, TMECH Feb. 2021 235-245 Ferrofluidic Manipulator: Automatic Manipulation of Nonmagnetic Microparticles at the Air–Ferrofluid Interface. Cenev, Z., +, TMECH Aug. 2021 1932-1940

Integral Sliding-Mode Tracking Control for Heavy Vehicle Electrohydraulic Power Steering System. *Du*, *H.*, +, *TMECH June 2021 1455-1466*

Solid modeling

- Automatic Construction of Three-Dimensional Ground Model by Data Processing. *Takeyama*, *T.*, +, *TMECH Dec.* 2021 2881-2887
- Kernel Principal Components Analysis of Lateral Force Data for Quantitative Evaluation of 3D Features Rendering Fidelity. *Liu, G.*, +, *TMECH June 2021 1602-1612*
- Radial Coverage Strength for Optimization of Monocular Multicamera Deployment. Lei, Z., +, TMECH Dec. 2021 3221-3231

Space missions

Estimation of the Electrostatic Effects in the LISA-Pathfinder Critical Test Mass Dynamics via the Method of Moments. *Zanoni, C.*, +, *TMECH Dec.* 2021 3022-3030

Spatiotemporal phenomena

Time/Space-Separation-Based Gaussian Process Modeling for the Cross-Coupling Effect of a 2-DOF Nanopositioning Stage. *Tao, Y*, +, *TMECH Aug. 2021 2186-2194*

Special issues and sections

- Focused Section on the Second Edition of TMECH/AIM Emerging Topics. Chen, X., +, TMECH Aug. 2021 1705-1707
- Guest Editorial Focused Section on Mechatronics in Unmanned Systems. *He*, *W*., +, *TMECH April 2021 595-599*
- Guest Editorial Introduction to the Focused Section on Mechatronics and Automation for Constructions. *Cheah, C.C.*, +, *TMECH Dec. 2021 2819-2825*
- Guest Editorial: Focused Section on Mechatronics in Road Mobility Systems. *Ivanov, V.*, +, *TMECH June 2021 1195-1200*

Splines (mathematics)

- A Smoothed Raster Scanning Trajectory Based on Acceleration-Continuous B-Spline Transition for High-Speed Atomic Force Microscopy. *Li*, *L*., +, *TMECH Feb. 2021 24-32*
- Erratum to "A Smoothed Raster Scanning Trajectory Based on Acceleration-Continuous B-Spline Transition for High-Speed Atomic Force Microscopy" [Feb 21 24-32]. *Li*, *L.*, +, *TMECH June 2021 1700*
- Tracking Accuracy Improvement Based on Adaptive Nonlinear Sliding Mode Control. *Tsai, W.*, +, *TMECH Feb. 2021 179-190*

Spot welding

Electrical Parameter Identification of Medium-Frequency DC Resistance Spot Welding System Using Intelligent Algorithm. *Wang, X.*, +, *TMECH Aug. 2021 1791-1802*

Spraying

Control Parameters Design Based on Dynamic Characteristics of a Hybrid Robot With Parallelogram Structures. *Liu, Z.*, +, *TMECH April 2021 1140-1150*

Springs

Overcoming the Torque/Stiffness Range Tradeoff in Antagonistic Variable Stiffness Actuators. *Mengacci, R.*, +, *TMECH Dec. 2021 3186-3197*

Plate-Springed Parallel Elastic Actuator for Efficient Snake Robot Movement. Kakogawa, A., +, TMECH Dec. 2021 3051-3063

Springs (mechanical)

- A Novel Rotational Actuator With Variable Stiffness Using S-Shaped Springs. Xu, Y, +, TMECH Aug. 2021 2249-2260
- Semiactively Controllable Vehicle Seat Suspension System With Negative Stiffness Magnetic Spring. *Tu, L., +, TMECH Feb. 2021 156-167*
- Shock Isolation Capability of an Electromagnetic Variable Stiffness Isolator With Bidirectional Stiffness Regulation. Zhao, J., +, TMECH Aug. 2021 2038-2047
- Thermal Modeling and Characterization of Twisted Coiled Actuators for Upper Limb Wearable Devices. *Edmonds, B.P.R.*, +, *TMECH April 2021* 966-977

Stability

A Binary Tree Based Coordination Scheme for Target Enclosing With Micro Aerial Vehicles. *Duan, H.,*+, *TMECH Feb. 2021 458-468*

- A Computational-Effective Field-Oriented Control Strategy for Accurate and Efficient Electric Propulsion of Unmanned Aerial Vehicles. *Bosso, A.*, +, *TMECH June 2021 1501-1511*
- A Visual Servo-Based Predictive Control With Echo State Gaussian Process for Soft Bending Actuator. Cao, Y., +, TMECH Feb. 2021 574-585
- Adaptive Finite-Time Control for Half-Vehicle Active Suspension Systems With Uncertain Dynamics. *Liu, Y.*, +, *TMECH Feb. 2021 168-178*
- Adaptive Robust Finite-Time Nonlinear Control of a Typical Autonomous Underwater Vehicle With Saturated Inputs and Uncertainties. *Sedghi, F*, +, *TMECH Oct. 2021 2517-2527*
- Analytical Design and Experimental Verification of Geofencing Control for Aerial Applications. *Ghaffari, A., TMECH April 2021 1106-1117*
- Asymptotic Tracking Control of Mechanical Servosystems With Mismatched Uncertainties. *Deng, W.*, +, *TMECH Aug. 2021 2204-2214*
- Closed-Loop Range-Based Control of Dual-Stage Nanopositioning Systems. *Mitrovic, A., +, TMECH June 2021 1412-1421*
- Development and Performance Enhancement of an Overactuated Autonomous Ground Vehicle. *Huang, Y.*, +, *TMECH Feb. 2021 33-44*
- Distributed Formation Control Using Fuzzy Self-Tuning of Strictly Negative Imaginary Consensus Controllers in Aerial Robotics. *Tran, V.P.*, +, *TMECH Oct. 2021 2306-2315*
- Event-Triggered-Based Discrete-Time Neural Control for a Quadrotor UAV Using Disturbance Observer. Shao, S., +, TMECH April 2021 689-699
- Finite-Time Synchronization Control for Bilateral Teleoperation Systems With Asymmetric Time-Varying Delay and Input Dead Zone. *Bao, J.*, +, *TMECH June 2021 1570-1580*
- Fractional-Order Control for Uncertain Teleoperated Cyber-Physical System With Actuator Fault. *Ma*, *Z*., +, *TMECH Oct. 2021 2472-2482*
- Human-in-the-Loop Control of a Wearable Lower Limb Exoskeleton for Stable Dynamic Walking. *Li*, *Z*., +, *TMECH Oct. 2021 2700-2711*
- Low Impedance-Guaranteed Gain-Scheduled GESO for Torque-Controlled VSA With Application of Exoskeleton-Assisted Sit-to-Stand. *Liu, L.*, +, *TMECH Aug. 2021 2080-2091*
- Model-Free Control of Flexible Manipulator Based on Intrinsic Design. Jiang, N., +, TMECH Oct. 2021 2641-2652
- Modeling and Motion Control of Industrial Tractor–Trailers Vehicles Using Force Compensation. Zhao, H., +, TMECH April 2021 645-656
- Multimodal Dynamics Analysis and Control for Amphibious Fly-Drive Vehicle. *Tan, Q., +, TMECH April 2021 621-632*
- Nonlinear Model Predictive Control for Integrated Energy-Efficient Torque-Vectoring and Anti-Roll Moment Distribution. *Dalboni, M.*, +, *TMECH June 2021 1212-1224*
- Nonprehensile Manipulation:A Trajectory-Planning Perspective. Acharya, P., +, TMECH Feb. 2021 527-538
- Novel Joint-Drift-Free Scheme at Acceleration Level for Robotic Redundancy Resolution With Tracking Error Theoretically Eliminated. *Jin, L.*, +, *TMECH Feb. 2021 90-101*
- Online Delayed Reference Generation for a Humanoid Imitating Human Walking Motion. *Oh, J.*, +, *TMECH Feb. 2021 102-112*
- Optimized Power Modulation in Wave-Based Bilateral Teleoperation. *Ferraguti, F., +, TMECH Feb. 2021 276-287*
- Parallel Compliance Design for Increasing Robustness and Efficiency in Legged Locomotion–Theoretical Background and Applications. Sharbafi, M.A., +, TMECH Feb. 2021 335-346
- Passivity-Based Nonlinear Control Approach for Tracking Task of an Underactuated CMG. *Toriumi, F.Y.*, +, *TMECH Oct. 2021 2285-2293*
- Phase-Relaxed-Passive Full State Feedback Gain Limits for Series Elastic Actuators. *Thomas, G.C.,* +, *TMECH Feb. 2021 586-591*
- Point Stabilization of Nonholonomic Mobile Robot by Bézier Smooth Subline Constraint Nonlinear Model Predictive Control. *Zhang, Y.*, +, *TMECH April 2021 990-1001*
- Practical Terminal Sliding Mode Control of Nonlinear Uncertain Active Suspension Systems With Adaptive Disturbance Observer. *Wang, G., +, TMECH April 2021 789-797*
- Proportional-Integral Approximation-Free Control of Robotic Systems With Unknown Dynamics. Zhang, C., +, TMECH Aug. 2021 2226-2236

- Quasi-LPV Interconnected Observer Design for Full Vehicle Dynamics Estimation With Hardware Experiments. *Fouka, M.*, +, *TMECH Aug. 2021* 1763-1772
- Semiactively Controllable Vehicle Seat Suspension System With Negative Stiffness Magnetic Spring. *Tu, L.*, +, *TMECH Feb. 2021 156-167*
- Sliding Mode Control With Model-Based Switching Functions Applied on a 7-DOF Exoskeleton Arm. *Fallaha*, C., +, *TMECH Feb. 2021 539-550*
- Sliding-Mode-Disturbance-Observer-Based Robust Tracking Control for Omnidirectional Mobile Robots With Kinematic and Dynamic Uncertainties. *Jeong, S.*, +, *TMECH April 2021 741-752*
- Swing-Reducing Flight Control System for an Underactuated Indoor Miniature Autonomous Blimp. *Tao*, Q., +, *TMECH Aug. 2021 1895-1904*
- Takagi–Sugeno Fuzzy Unknown Input Observers to Estimate Nonlinear Dynamics of Autonomous Ground Vehicles: Theory and Real-Time Verification. *Nguyen, A., +, TMECH June 2021 1328-1338*
- Tracking Accuracy Improvement Based on Adaptive Nonlinear Sliding Mode Control. *Tsai, W.*, +, *TMECH Feb. 2021 179-190*
- Stability analysis
 - Integral Sliding-Mode Tracking Control for Heavy Vehicle Electrohydraulic Power Steering System. Du, H., +, TMECH June 2021 1455-1466
 - Longitudinal Motion Modeling and Experimental Verification of a Microrobot Subject to Liquid Laminar Flow. *Demircali, A.A.*, +, *TMECH Dec.* 2021 2956-2966

State estimation

An Adaptive Fault-Tolerant EKF for Vehicle State Estimation With Partial Missing Measurements. *Wang, Y.*, +, *TMECH June 2021 1318-1327* State feedback

- Phase-Relaxed-Passive Full State Feedback Gain Limits for Series Elastic Actuators. *Thomas*, G.C., +, *TMECH Feb. 2021 586-591*
- State-space methods

Computationally Improved State-Dependent Riccati Equation Scheme for Nonlinear Benchmark System. *Lin, L., TMECH April 2021 1064-1075*

Statistical analysis

- A Delaunay Triangulation-Based Matching Area Selection Algorithm for Underwater Gravity-Aided Inertial Navigation. Wang, C., +, TMECH April 2021 908-917
- An Integrated Terrain Identification Framework for Mobile Robots: System Development, Analysis, and Verification. Zeng, R., +, TMECH June 2021 1581-1590
- Generative Adversarial Network for Prediction of Workpiece Surface Topography in Machining Stage. *Cao, L.*, +, *TMECH Feb. 2021 480-490* Stator windings

Design Principles for Compact, Backdrivable Actuation in Partial-Assist Powered Knee Orthoses. *Zhu, H.,* +, *TMECH Dec. 2021 3104-3115*

Stators

- A Piezoelectric Microultrasonic Motor With High *Q* and Good Mode Match. *Zhou, W.*, +, *TMECH Aug. 2021 1773-1781*
- Design Process and Verification of SPMSM for a Wearable Robot Considering Thermal Characteristics Through LPTN. *Hwang, S.*, +, *TMECH April* 2021 1033-1042
- Development of FW and MTPV Control for SynRM via Feedforward Voltage Angle Control. *Chen, S.*, +, *TMECH Dec. 2021 3254-3264*

Steering systems

- Development and Performance Enhancement of an Overactuated Autonomous Ground Vehicle. *Huang, Y., +, TMECH Feb. 2021 33-44*
- Individual Auxiliary and Fault-Tolerant Control of Steer-by-Wire System Considering Different Drivers Steering Characteristics. *Zhao, W.*, +, *TMECH June 2021 1558-1569*
- Integral Sliding-Mode Tracking Control for Heavy Vehicle Electrohydraulic Power Steering System. *Du*, *H*., +, *TMECH June 2021 1455-1466*
- Nonlinear Model Predictive Control for Integrated Energy-Efficient Torque-Vectoring and Anti-Roll Moment Distribution. *Dalboni*, *M.*, +, *TMECH June 2021 1212-1224*
- Quasi-LPV Interconnected Observer Design for Full Vehicle Dynamics Estimation With Hardware Experiments. *Fouka, M.*, +, *TMECH Aug. 2021* 1763-1772

Takagi–Sugeno Fuzzy-Based Robust *H*∞ Integrated Lane-Keeping and Direct Yaw Moment Controller of Unmanned Electric Vehicles. *Guo*, *J*., +, *TMECH Aug. 2021 2151-2162*

Step response

- Development of a Small and Lightweight Missile Fin Control Actuation System Driven by Novel Dielectric Elastomer Actuators. Jung, H.S., +, TMECH April 2021 1002-1012
- Self-Sensing and Control of Soft Electrothermal Actuator. Cao, Y., +, TMECH April 2021 854-863

Stereo image processing

- Camera Orientation Optimization in Stereo Vision Systems for Low Measurement Error. Liu, X., +, TMECH April 2021 1178-1182
- Geometrical-Based Displacement Measurement With Pseudostereo Monocular Camera on Bidirectional Cascaded Linear Actuator. *Lee, D.*, +, *TMECH Aug. 2021 1923-1931*

Strain

- Energy-Based Modeling of Ionic Polymer–Metal Composite Actuators Dedicated to the Control of Flexible Structures. *Liu*, *N.*, +, *TMECH Dec. 2021* 3139-3150
- Kinematic Modeling and Control of Variable Curvature Soft Continuum Robots. *Huang, X.*, +, *TMECH Dec. 2021 3175-3185*
- Modified Stiffness-Based Soft Optical Waveguide Integrated Pneumatic Artificial Muscle (PAM) Actuators for Contraction and Force Sensing. *Jamil, B.*, +, *TMECH Dec. 2021 3243-3253*

Strain gauges

- A Monolithic Force Sensing Integrated Flexure Bonder Dedicated to Flip-Chip Active Soft-Landing Interconnection. *Tang, H.*, +, *TMECH Feb.* 2021 323-334
- Design and Testing of a New Force-Sensing Cell Microinjector Based on Small-Stiffness Compliant Mechanism. *Wei, Y.*, +, *TMECH April 2021* 818-829

Strain sensors

- Design and Testing of a New Force-Sensing Cell Microinjector Based on Small-Stiffness Compliant Mechanism. *Wei, Y.*, +, *TMECH April 2021* 818-829
- Dynamic Modeling and State Estimation of Cable-Conduit Actuation During Interaction With Nonpassive Environments. *Buchanan, S.*, +, *TMECH Oct.* 2021 2462-2471

Stress

On the Mechanical Power Output Comparisons of Cone Dielectric Elastomer Actuators. Cao, C., +, TMECH Dec. 2021 3151-3162

Stress analysis

- A Monolithic Force Sensing Integrated Flexure Bonder Dedicated to Flip-Chip Active Soft-Landing Interconnection. *Tang, H.*, +, *TMECH Feb.* 2021 323-334
- Analytical Harmonic Method for Modeling High-Frequency Oscillation With Applications to Aircraft Piston Pump Vibration Analysis. *Li*, *L.*, +, *TMECH April 2021 918-929*

Stress measurement

Testing of a Strained Silicon Based 3-D Stress Sensor for Out-of-Plane Stress Measurements. *Balbola, A.A.*, +, *TMECH April 2021 1076-1083*

Stress-strain relations

Actuation Frequency Modeling and Prediction for Shape Memory Alloy Actuators. *Liu*, *X.*, +, *TMECH June 2021 1536-1546*

Structural engineering

Nontarget-Based Measurement of 6-DOF Structural Displacement Using Combined RGB Color and Depth Information. *Lee, S.*, +, *TMECH June* 2021 1358-1368

Support vector machines

- Brain–Machine Interface Using Functional Electrical Stimulation and Motion-Related Cortical Potentials Identified by a Support Vector Machine. *Miura*, S., +, *TMECH April 2021 1013-1021*
- General Discharge Voltage Information Enabled Health Evaluation for Lithium-Ion Batteries. *Deng, Z., +, TMECH June 2021 1295-1306*

Supports

A Piezoelectric Microultrasonic Motor With High Q and Good Mode Match. Zhou, W., +, TMECH Aug. 2021 1773-1781

Surface cracks

A DC-Biased Scanning Induction Thermographic System for Characterizing Surface Cracks in Ferromagnetic Components. *Wu, J.*, +, *TMECH Oct.* 2021 2782-2790

Surface impedance

Optimized Interaction Control for Robot Manipulator Interacting With Flexible Environment. *Liu*, X., +, *TMECH Dec. 2021 2888-2898*

Surface topography

Generative Adversarial Network for Prediction of Workpiece Surface Topography in Machining Stage. *Cao, L.*, +, *TMECH Feb. 2021 480-490* Surgery

- A Fully Actuated Robotic Assistant for MRI-Guided Precision Conformal Ablation of Brain Tumors. *Li*, *G.*, +, *TMECH Feb. 2021 255-266*
- A Surgical Robotic System for Treatment of Pelvic Osteolysis Using an FBG-Equipped Continuum Manipulator and Flexible Instruments. *Sefati, S.*, +, *TMECH Feb.* 2021 369-380
- Automated Retinal Vein Cannulation on Silicone Phantoms Using Optical-Coherence-Tomography-Guided Robotic Manipulations. *Gerber, M.J.*, +, *TMECH Oct. 2021 2758-2769*
- Construction of Controller Model of Notch Continuum Manipulator for Laryngeal Surgery Based on Hybrid Method. *Wang, H.*, +, *TMECH April* 2021 1022-1032
- Design and Experimental Validation of a Miniaturized Robotic Tendon-Driven Articulated Surgical Drill for Enhancing Distal Dexterity in Minimally Invasive Spine Fusion. *Wang, Y.*, +, *TMECH Aug. 2021 1858-1866*
- Needle Deflection Modeling and Preoperative Trajectory Planning During Insertion Into Multilayered Tissues. *Zhao, B., +, TMECH April 2021 943-954*
- Robotized Catheter With Enhanced Distal Targeting for Peripheral Pulmonary Biopsy. Kato, T., +, TMECH Oct. 2021 2451-2461
- Stochastic Force-Based Insertion Depth and Tip Position Estimations of Flexible FBG-Equipped Instruments in Robotic Retinal Surgery. *Ebrahimi, A.*, +, *TMECH June 2021 1512-1523*
- The MUSHA Hand II:A Multifunctional Hand for Robot-Assisted Laparoscopic Surgery. Liu, H., +, TMECH Feb. 2021 393-404
- Vision-Based Cutting Control of Deformable Objects With Surface Tracking. Han, L., +, TMECH Aug. 2021 2016-2026

Suspensions (mechanical components)

- Adaptive Finite-Time Control for Half-Vehicle Active Suspension Systems With Uncertain Dynamics. *Liu*, *Y*, +, *TMECH Feb. 2021 168-178*
- Multimodal Dynamics Analysis and Control for Amphibious Fly-Drive Vehicle. *Tan, Q.*, +, *TMECH April 2021 621-632*
- Nonlinear Model Predictive Control for Integrated Energy-Efficient Torque-Vectoring and Anti-Roll Moment Distribution. *Dalboni, M.*, +, *TMECH June 2021 1212-1224*
- Practical Terminal Sliding Mode Control of Nonlinear Uncertain Active Suspension Systems With Adaptive Disturbance Observer. *Wang, G.*, +, *TMECH April 2021 789-797*
- Semiactively Controllable Vehicle Seat Suspension System With Negative Stiffness Magnetic Spring. *Tu, L., +, TMECH Feb. 2021 156-167*

Swarm intelligence

Design and Real-Time Optimization for a Magnetic Actuation System With Enhanced Flexibility. *Du*, *X.*, +, *TMECH June 2021 1524-1535*

Synchronization

- Finite-Time Synchronization Control for Bilateral Teleoperation Systems With Asymmetric Time-Varying Delay and Input Dead Zone. *Bao, J.*, +, *TMECH June 2021 1570-1580*
- Precise Linear-Motor Synchronization Control via Cross-Coupled Second-Order Discrete-Time Fractional-Order Sliding Mode. Kuang, Z., +, TMECH Feb. 2021 358-368
- Quasi-Synchronization Control of Multiple Electrohydraulic Actuators With Load Disturbance and Uncertain Parameters. *Guo, Q.*, +, *TMECH Aug.* 2021 2048-2058

Synchronous machines

Static Position Sensor Bias Fault Diagnosis in Permanent Magnet Synchronous Machines via Current Estimation. Kuruppu, S.S., +, TMECH April 2021 888-896

Synchronous motor drives

- Online Compensation of Mechanical Load Defects With Composite Control in PMSM Drives. *Kommuri, S.K.*, +, *TMECH June 2021 1392-1400*
- Rotor Position Tracking Control for Low Speed Operation of Direct-Drive PMSM Servo System. *Bu*, *F*., +, *TMECH April 2021 1129-1139*
- Static Position Sensor Bias Fault Diagnosis in Permanent Magnet Synchronous Machines via Current Estimation. Kuruppu, S.S., +, TMECH April 2021 888-896

Synchronous motors

Design Process and Verification of SPMSM for a Wearable Robot Considering Thermal Characteristics Through LPTN. Hwang, S., +, TMECH April 2021 1033-1042

- Online Compensation of Mechanical Load Defects With Composite Control in PMSM Drives. *Kommuri, S.K.*, +, *TMECH June 2021 1392-1400*
- Rotor Position Tracking Control for Low Speed Operation of Direct-Drive PMSM Servo System. *Bu*, *F*., +, *TMECH April 2021 1129-1139*
- Study on a Double-Sided Permanent-Magnet Linear Synchronous Motor With Reversed Slots. Zhao, J., +, TMECH Feb. 2021 3-12

System dynamics

Artificial-Delay Adaptive Control for Underactuated Euler–Lagrange Robotics. *Roy, S.*, +, *TMECH Dec. 2021 3064-3075*

Coordinated Trajectory-Tracking Control of a Marine Aerial-Surface Heterogeneous System. Wang, N., +, TMECH Dec. 2021 3198-3210

Т

Table lookup

Development of FW and MTPV Control for SynRM via Feedforward Voltage Angle Control. Chen, S., +, TMECH Dec. 2021 3254-3264

Tactile sensors

- Design, Modeling, and Control of a 3D Printed Monolithic Soft Robotic Finger With Embedded Pneumatic Sensing Chambers. *Tawk, C.*, +, *TMECH April 2021 876-887*
- Development of Embedded Sensor System for 5-DOF Finger-Wearable Tactile Interface. *Lim, B., +, TMECH Aug. 2021 1728-1736*
- Haptic Display Responsive to Touch Driven by Soft Actuator and Soft Sensor. *Phung, H., +, TMECH Oct. 2021 2495-2505*
- Soft Robotic Palm With Tunable Stiffness Using Dual-Layered Particle Jamming Mechanism. *Lee*, *J.*, +, *TMECH Aug. 2021 1820-1827*

Target tracking

A Novel Wireless 5-D Electromagnetic Tracking System Based on Nine-Channel Sinusoidal Signals. *Yang, W.*, +, *TMECH Feb. 2021 246-254* Task analysis

- A Circadian Rhythms Neural Network for Solving the Redundant Robot Manipulators Tracking Problem Perturbed by Periodic Noise. *Zhang, Z.*, +, *TMECH Dec. 2021 3232-3242*
- Basic Input–Output Gain Tuning System Based on Control Input Histogram Leveling for Human-Operated Machines. Kamezaki, M., +, TMECH Dec. 2021 2857-2869
- MPC-Based Haptic Shared Steering System: A Driver Modeling Approach for Symbiotic Driving. *Lazcano, A.M.*, +, *TMECH June 2021 1201-1211*
- Optimized Interaction Control for Robot Manipulator Interacting With Flexible Environment. *Liu*, *X*., +, *TMECH Dec. 2021 2888-2898*
- Radial Coverage Strength for Optimization of Monocular Multicamera Deployment. Lei, Z., +, TMECH Dec. 2021 3221-3231

Telemedicine

An Efficient Design Solution for a Low-Cost High-G Centrifuge System. Mohajer, N., +, TMECH Feb. 2021 134-145

Telerobotics

- Finite-Time Synchronization Control for Bilateral Teleoperation Systems With Asymmetric Time-Varying Delay and Input Dead Zone. *Bao, J.*, +, *TMECH June 2021 1570-1580*
- Online Delayed Reference Generation for a Humanoid Imitating Human Walking Motion. *Oh, J.*, +, *TMECH Feb. 2021 102-112*
- Optimized Power Modulation in Wave-Based Bilateral Teleoperation. *Ferraguti*, *F*, +, *TMECH Feb. 2021 276-287*

The MUSHA Hand II:A Multifunctional Hand for Robot-Assisted Laparoscopic Surgery. *Liu*, *H.*, +, *TMECH Feb. 2021 393-404*

Temperature measurement

Development of a Concrete Floating and Delamination Detection System Using Infrared Thermography. *Chun, P.,* +, *TMECH Dec. 2021 2835-2844* **Tendons**

Development of a Soft Robot Based Photodynamic Therapy for Pancreatic Cancer. *Li*, *Y*, +, *TMECH Dec. 2021 2977-2985*

Slider-Tendon Linear Actuator With Under-Actuation and Fast-Connection for Soft Wearable Robots. *Kim, B., +, TMECH Dec. 2021 2932-2943*

Tensile strength

Localized Property Design and Gradient Processing of a Hydraulic Valve Body Using Selective Laser Melting. *Zhu, Y.*, +, *TMECH April 2021 1151-1160*

Tensile testing

Tendon-Inspired Piezoelectric Sensor for Biometric Application. Kim, H., +, TMECH Oct. 2021 2538-2547

Testing

Integrated Predictive Powertrain Control for a Multimode Plug-in Hybrid Electric Vehicle. Oncken, J., +, TMECH June 2021 1248-1259

Thermal analysis

Design Process and Verification of SPMSM for a Wearable Robot Considering Thermal Characteristics Through LPTN. Hwang, S., +, TMECH April 2021 1033-1042

Thermal expansion

Four-Point Method in the Measurement and Separation of Spindle Rotation Error. *Liu*, *F*, +, *TMECH Feb. 2021 113-123*

Modeling of One-Ply and Two-Ply Twisted and Coiled Polymer Artificial Muscles. *Karami, F.*, +, *TMECH Feb. 2021 300-310*

Thermal management (packaging)

Real-Time Integrated Power and Thermal Management of Connected HEVs Based on Hierarchical Model Predictive Control. *Gong, X.*, +, *TMECH June 2021 1271-1282*

Three-dimensional displays

OrthographicNet: A Deep Transfer Learning Approach for 3-D Object Recognition in Open-Ended Domains. Kasaei, S.H., TMECH Dec. 2021 2910-2921

Three-dimensional printing

- An Integrated Design and Fabrication Strategy for Planar Soft Dielectric Elastomer Actuators. *Chen, F,* +, *TMECH Oct. 2021 2629-2640*
- Automated In Situ Placing of Metal Components Into 3-D Printed FFF Objects. Ahlers, D., +, TMECH Aug. 2021 1886-1894
- Design, Modeling, and Control of a 3D Printed Monolithic Soft Robotic Finger With Embedded Pneumatic Sensing Chambers. Tawk, C., +, TMECH April 2021 876-887

Three-term control

- Active Disturbance Rejection Control for a Fluid-Driven Hand Rehabilitation Device. Li, H., +, TMECH April 2021 841-853
- An Observer-Based Neural Adaptive\$PID^2\$ Controller for Robot Manipulators Including Motor Dynamics With a Prescribed Performance. *Shojaei*, *K.*, +, *TMECH June 2021 1689-1699*
- Development and Test of a Two-Dimensional Stacked Terfenol-D Actuator With High Bandwidth and Large Stroke. *Chen, L.*, +, *TMECH Aug. 2021* 1951-1959
- Development of Embedded Sensor System for 5-DOF Finger-Wearable Tactile Interface. *Lim, B., +, TMECH Aug. 2021 1728-1736*
- Distributed Formation Control Using Fuzzy Self-Tuning of Strictly Negative Imaginary Consensus Controllers in Aerial Robotics. *Tran, V.P.*, +, *TMECH Oct. 2021 2306-2315*
- Dynamic Control of Multisection Three-Dimensional Continuum Manipulators Based on Virtual Discrete-Jointed Robot Models. *Wang, C.*, +, *TMECH April 2021* 777-788
- Efficient Cooperative Structured Control for a Multijoint Biomimetic Robotic Fish. Yan, S., +, TMECH Oct. 2021 2506-2516
- Self-Sensing and Control of Soft Electrothermal Actuator. Cao, Y., +, TMECH April 2021 854-863

Time-frequency analysis

An Integrated Terrain Identification Framework for Mobile Robots: System Development, Analysis, and Verification. Zeng, R., +, TMECH June 2021 1581-1590

Time-varying systems

- Adaptive Output Feedback Control of Steer-by-Wire Systems With Event-Triggered Communication. *Ma*, *B*., +, *TMECH Aug. 2021 1968-1979*
- Asymptotic Tracking Control of Mechanical Servosystems With Mismatched Uncertainties. *Deng, W.*, +, *TMECH Aug. 2021 2204-2214*
- Finite-Time Synchronization Control for Bilateral Teleoperation Systems With Asymmetric Time-Varying Delay and Input Dead Zone. *Bao, J.*, +, *TMECH June 2021 1570-1580*
- Low Impedance-Guaranteed Gain-Scheduled GESO for Torque-Controlled VSA With Application of Exoskeleton-Assisted Sit-to-Stand. *Liu, L.*, +, *TMECH Aug. 2021 2080-2091*
- Sliding Mode Control With Model-Based Switching Functions Applied on a 7-DOF Exoskeleton Arm. *Fallaha*, C., +, *TMECH Feb. 2021 539-550*
- Takagi–Sugeno Fuzzy-Based Robust *H*∞ Integrated Lane-Keeping and Direct Yaw Moment Controller of Unmanned Electric Vehicles. *Guo*, *J*., +, *TMECH Aug. 2021 2151-2162*

Tires

- Integral Sliding-Mode Tracking Control for Heavy Vehicle Electrohydraulic Power Steering System. *Du*, *H.*, +, *TMECH June 2021 1455-1466*
- MEMS-Enabled Retrofitting of Automobile Wheel Balancer for Automatic Unbalance Detection. *Pozzato, G.,* +, *TMECH April 2021 830-840*
- Multimodal Dynamics Analysis and Control for Amphibious Fly-Drive Vehicle. *Tan, Q.*, +, *TMECH April 2021 621-632*
- Nonlinear Model Predictive Control for Integrated Energy-Efficient Torque-Vectoring and Anti-Roll Moment Distribution. *Dalboni, M.*, +, *TMECH June 2021 1212-1224*
- Quasi-LPV Interconnected Observer Design for Full Vehicle Dynamics Estimation With Hardware Experiments. *Fouka*, M., +, *TMECH Aug. 2021* 1763-1772
- Simultaneous State Estimation and Tire Model Learning for Autonomous Vehicle Applications. Jeon, W., +, TMECH Aug. 2021 1941-1950

Topology

Topology Optimization for Design of a 3D-Printed Constant-Force Compliant Finger. *Liu*, *C.*, +, *TMECH Aug. 2021 1828-1836*

Topology Optimization of Skeleton-Reinforced Soft Pneumatic Actuators for Desired Motions. *Chen, S.*, +, *TMECH Aug. 2021 1745-1753*

Torque

- A Compact Ankle Exoskeleton With a Multiaxis Parallel Linkage Mechanism. Lee, M., +, TMECH Feb. 2021 191-202
- A Piezoelectric Microultrasonic Motor With High Q and Good Mode Match. Zhou, W., +, TMECH Aug. 2021 1773-1781
- Adaptive Harmonic and Disturbance Estimators for Rotary Machines With Applications to Engines. Vadamalu, R.S., +, TMECH Feb. 2021 381-392
- Biomimetic Realization of a Robotic Penguin Wing: Design and Thrust Characteristics. Shen, Y., +, TMECH Oct. 2021 2350-2361
- Design and Experimental Validation of a Novel High-Speed Omnidirectional Underwater Propulsion Mechanism. *Njaka, T., +, TMECH Oct. 2021* 2339-2349
- Design Principles for Compact, Backdrivable Actuation in Partial-Assist Powered Knee Orthoses. Zhu, H., +, TMECH Dec. 2021 3104-3115
- Design Process and Verification of SPMSM for a Wearable Robot Considering Thermal Characteristics Through LPTN. Hwang, S., +, TMECH April 2021 1033-1042
- Development of FW and MTPV Control for SynRM via Feedforward Voltage Angle Control. *Chen, S.*, +, *TMECH Dec. 2021 3254-3264*
- Edge-Dependent Efficient Grasp Rectangle Search in Robotic Grasp Detection. Chen, L., +, TMECH Dec. 2021 2922-2931
- MPC-Based Haptic Shared Steering System: A Driver Modeling Approach for Symbiotic Driving. Lazcano, A.M., +, TMECH June 2021 1201-1211
- Overcoming the Torque/Stiffness Range Tradeoff in Antagonistic Variable Stiffness Actuators. *Mengacci, R.*, +, *TMECH Dec. 2021 3186-3197*
- Rotor Position Tracking Control for Low Speed Operation of Direct-Drive PMSM Servo System. Bu, F., +, TMECH April 2021 1129-1139

Steady-State Characteristics Study of a Power Split Hydraulic Transmission. Wang, F., +, TMECH Feb. 2021 78-89

Torque control

- A Novel Wolfrom-Based Gearbox for Robotic Actuators. Crispel, S., +, TMECH Aug. 2021 1980-1988
- A Position Sensorless Torque Control Strategy for Switched Reluctance Machines With Fewer Current Sensors. *Gan, C.*, +, *TMECH April 2021* 1118-1128
- Development of a Small and Lightweight Missile Fin Control Actuation System Driven by Novel Dielectric Elastomer Actuators. *Jung, H.S.*, +, *TMECH April 2021 1002-1012*
- Dual Fast Marching Tree Algorithm for Human-Like Motion Planning of Anthropomorphic Arms With Task Constraints. *Xia, J.*, +, *TMECH Oct.* 2021 2803-2813
- Dynamic Control of Multisection Three-Dimensional Continuum Manipulators Based on Virtual Discrete-Jointed Robot Models. *Wang, C.*, +, *TMECH April 2021* 777-788
- Low Impedance-Guaranteed Gain-Scheduled GESO for Torque-Controlled VSA With Application of Exoskeleton-Assisted Sit-to-Stand. *Liu, L.*, +, *TMECH Aug. 2021 2080-2091*
- Nonlinear Model Predictive Control for Integrated Energy-Efficient Torque-Vectoring and Anti-Roll Moment Distribution. *Dalboni, M.*, +, *TMECH June 2021 1212-1224*
- Online Compensation of Mechanical Load Defects With Composite Control in PMSM Drives. *Kommuri, S.K.*, +, *TMECH June 2021 1392-1400*
- Sliding Mode Control With Model-Based Switching Functions Applied on a 7-DOF Exoskeleton Arm. *Fallaha*, C., +, *TMECH Feb. 2021 539-550*
- Static Position Sensor Bias Fault Diagnosis in Permanent Magnet Synchronous Machines via Current Estimation. Kuruppu, S.S., +, TMECH April 2021 888-896

Torque motors

Practical Fixed-Time Position Tracking Control of Permanent Magnet DC Torque Motor Systems. *Wu, Y., +, TMECH Feb. 2021 563-573*

Tracking

- Accurate Motion Control of a Direct-Drive Hydraulic System With an Adaptive Nonlinear Pump Flow Compensation. *Helian, B.*, +, *TMECH Oct.* 2021 2593-2603
- An Observer-Based Neural Adaptive\$PID^2\$ Controller for Robot Manipulators Including Motor Dynamics With a Prescribed Performance. *Shojaei*, *K.*, +, *TMECH June 2021 1689-1699*
- Asymptotic Tracking Control of Mechanical Servosystems With Mismatched Uncertainties. *Deng, W.*, +, *TMECH Aug. 2021 2204-2214*
- Event-Triggered-Based Discrete-Time Neural Control for a Quadrotor UAV Using Disturbance Observer. Shao, S., +, TMECH April 2021 689-699
- Modeling and Adaptive Fault Compensation for Two Physically Linked 2WD Mobile Robots. *Ma*, *Y*, +, *TMECH April 2021 1161-1171*
- Modeling and Motion Control of Industrial Tractor–Trailers Vehicles Using Force Compensation. Zhao, H., +, TMECH April 2021 645-656
- Point Stabilization of Nonholonomic Mobile Robot by Bézier Smooth Subline Constraint Nonlinear Model Predictive Control. *Zhang, Y.*, +, *TMECH April 2021 990-1001*
- Prediction-Model-Based Contouring Error Iterative Precompensation Scheme for Precision Multiaxis Motion Systems. *Wang, Z.*, +, *TMECH Oct.* 2021 2274-2284
- Proportional-Integral Approximation-Free Control of Robotic Systems With Unknown Dynamics. *Zhang, C., +, TMECH Aug. 2021 2226-2236*
- Quasi-Synchronization Control of Multiple Electrohydraulic Actuators With Load Disturbance and Uncertain Parameters. *Guo, Q.*, +, *TMECH Aug.* 2021 2048-2058
- Sliding-Mode-Disturbance-Observer-Based Robust Tracking Control for Omnidirectional Mobile Robots With Kinematic and Dynamic Uncertainties. Jeong, S., +, TMECH April 2021 741-752
- Vision-Based Cutting Control of Deformable Objects With Surface Tracking. Han, L., +, TMECH Aug. 2021 2016-2026
- Whole-Body Control of an Autonomous Mobile Manipulator Using Series Elastic Actuators. *Liu*, *Y*., +, *TMECH April 2021 657-667*

Traction motors

Design Method for Reducing AC Resistance of Traction Motor Using High Fill Factor Coil to Improve the Fuel Economy of eBus. *Cha, K.*, +, *TMECH June 2021 1260-1270*

Traffic engineering computing

- Global Optimization of the Hydraulic-Electromagnetic Energy-Harvesting Shock Absorber for Road Vehicles With Human-Knowledge-Integrated Particle Swarm Optimization Scheme. *Zhou, Q., +, TMECH June 2021 1225-1235*
- Toward Safe and Personalized Autonomous Driving: Decision-Making and Motion Control With DPF and CDT Techniques. *Huang, C.*, +, *TMECH April 2021 611-620*
- Unmanned System Safety Decision-Making Support: Analysis and Assessment of Road Traffic Accidents. *Xie, G., +, TMECH April 2021 633-644*

Training

An Efficient Design Solution for a Low-Cost High-G Centrifuge System. Mohajer, N., +, TMECH Feb. 2021 134-145

Training data

- Human–Robot Cooperation Control Based on Trajectory Deformation Algorithm for a Lower Limb Rehabilitation Robot. *Zhou, J.*, +, *TMECH Dec.* 2021 3128-3138
- OrthographicNet: A Deep Transfer Learning Approach for 3-D Object Recognition in Open-Ended Domains. *Kasaei, S.H., TMECH Dec. 2021 2910-2921*
- Weakly Supervised Acoustic Defect Detection in Concrete Structures Using Clustering-Based Augmentation. *Kasahara, J.Y.L.*, +, *TMECH Dec. 2021* 2826-2834

Trajectory

- A Constrained DMPs Framework for Robot Skills Learning and Generalization From Human Demonstrations. *Lu*, *Z.*, +, *TMECH Dec. 2021 3265-3275*
- Data-Driven Iterative Trajectory Shaping for Precision Control of Flexible Feed Drives. *Dumanli, A.*, +, *TMECH Oct. 2021 2735-2746*
- Human–Robot Cooperation Control Based on Trajectory Deformation Algorithm for a Lower Limb Rehabilitation Robot. *Zhou, J.*, +, *TMECH Dec.* 2021 3128-3138
- Optimized Interaction Control for Robot Manipulator Interacting With Flexible Environment. *Liu*, X., +, *TMECH Dec. 2021 2888-2898*
- Prediction-Model-Based Contouring Error Iterative Precompensation Scheme for Precision Multiaxis Motion Systems. *Wang, Z.*, +, *TMECH Oct.* 2021 2274-2284
- Reconstructing Walking Dynamics From Two Shank-Mounted Inertial Measurement Units. Li, T., +, TMECH Dec. 2021 3040-3050

Trajectory control

- Distributed Control Algorithm for Leader–Follower Formation Tracking of Multiple Quadrotors: Theory and Experiment. Wang, Z., +, TMECH April 2021 1095-1105
- Dynamic Control of Multisection Three-Dimensional Continuum Manipulators Based on Virtual Discrete-Jointed Robot Models. Wang, C., +, TMECH April 2021 777-788
- Efficient Motion Planning Based on Kinodynamic Model for Quadruped Robots Following Persons in Confined Spaces. *Zhang, Z.*, +, *TMECH Aug.* 2021 1997-2006
- Formation Reconstruction and Trajectory Replanning for Multi-UAV Patrol. Wang, Y., +, TMECH April 2021 719-729
- Modeling and Motion Control of Industrial Tractor-Trailers Vehicles Using Force Compensation. Zhao, H., +, TMECH April 2021 645-656
- Nonprehensile Manipulation: A Trajectory-Planning Perspective. Acharya, P., +, TMECH Feb. 2021 527-538
- Optimization of Generalized S-Curve Trajectories for Residual Vibration Suppression and Compliance With Kinematic Bounds. *Biagiotti, L.*, +, *TMECH Oct. 2021 2724-2734*
- Robust Adaptive Tracking Control of Underwater Vehicles: Design, Stability Analysis, and Experiments. *Tijjani, A.S.*, +, *TMECH April 2021 897-907*
- Unified Motion/Force/Impedance Control for Manipulators in Unknown Contact Environments Based on Robust Model-Reaching Approach. *Lin, Y*, +, *TMECH Aug. 2021 1905-1913*

Whole-Body Control of an Autonomous Mobile Manipulator Using Series Elastic Actuators. *Liu*, *Y*, +, *TMECH April 2021 657-667*

Trajectory tracking

- An Adaptive Fuzzy Trajectory Tracking Control via Improved Cerebellar Model Articulation Controller for Electro-Hydraulic Shovel. *Fan, R.*, +, *TMECH Dec. 2021 2870-2880*
- Coordinated Trajectory-Tracking Control of a Marine Aerial-Surface Heterogeneous System. Wang, N., +, TMECH Dec. 2021 3198-3210

Transceivers

A Lightweight Wireless Overpressure Node Based Efficient Monitoring for Shock Waves. *Gao*, *S.*, +, *TMECH Feb. 2021 448-457*

Transducers

Design, Modeling, and Experiments of Electromagnetic Energy Harvester Embedded in Smart Watch and Wristband as Power Source. *Cai, M.*, +, *TMECH Aug. 2021 2104-2114*

Transient analysis

Development of FW and MTPV Control for SynRM via Feedforward Voltage Angle Control. *Chen, S.,* +, *TMECH Dec. 2021 3254-3264*

Trees (mathematics)

- A Binary Tree Based Coordination Scheme for Target Enclosing With Micro Aerial Vehicles. *Duan, H.*, +, *TMECH Feb. 2021 458-468*
- Dual Fast Marching Tree Algorithm for Human-Like Motion Planning of Anthropomorphic Arms With Task Constraints. *Xia, J.*, +, *TMECH Oct.* 2021 2803-2813

Triboelectricity

Characterization of a Packaged Triboelectric Harvester Under Simulated Gait Loading for Total Knee Replacement. *Hossain, N.A.*, +, *TMECH Dec.* 2021 2967-2976

Tumors

- A Fully Actuated Robotic Assistant for MRI-Guided Precision Conformal Ablation of Brain Tumors. *Li*, *G.*, +, *TMECH Feb. 2021 255-266*
- A Piezoelectric Robotic System for MRI Targeting Assessments of Therapeutics During Dipole Field Navigation. *Shi*, Y, +, *TMECH Feb. 2021* 214-225

A Tubular Dual-Roller Bending Mechanism Toward Robotic Transurethral Prostate Biopsy. *Xiao*, *X*., +, *TMECH Oct. 2021 2483-2494*

Tuning

Basic Input–Output Gain Tuning System Based on Control Input Histogram Leveling for Human-Operated Machines. *Kamezaki, M.*, +, *TMECH Dec.* 2021 2857-2869

Turbomachinery

Unsupervised Cross-Domain Fault Diagnosis Using Feature Representation Alignment Networks for Rotating Machinery. *Chen, J.*, +, *TMECH Oct.* 2021 2770-2781

Two-dimensional displays

Energy-Based Modeling of Ionic Polymer–Metal Composite Actuators Dedicated to the Control of Flexible Structures. *Liu*, N., +, *TMECH Dec. 2021* 3139-3150

U

Ultrasonic imaging

A Mechanism-Image Fusion Approach to Calibration of an Ultrasound-Guided Dual-Arm Robotic Brachytherapy System. *Xiong, J.*, +, *TMECH Dec. 2021 3211-3220*

Ultrasonic motors

A Piezoelectric Microultrasonic Motor With High *Q* and Good Mode Match. *Zhou, W.*, +, *TMECH Aug. 2021 1773-1781*

Ultraviolet sources

Ultraviolet Beam Lithography System for Digital Fabrication of Roller Molds. Yang, S., +, TMECH Feb. 2021 226-234

Uncertain systems

- A Novel Rotational Actuator With Variable Stiffness Using S-Shaped Springs. Xu, Y, +, TMECH Aug. 2021 2249-2260
- A Phase-Shaping Approach to the Control of Parametric Systems and Its Application. *Shimonomura, S.,* +, *TMECH Aug. 2021 2163-2173*
- A Tilting-Rotor Unmanned Aerial Vehicle for Enhanced Aerial Locomotion and Manipulation Capabilities: Design, Control, and Applications. *Ding*, *C.*, +, *TMECH Aug. 2021 2237-2248*

Adaptive Finite-Time Control for Half-Vehicle Active Suspension Systems With Uncertain Dynamics. *Liu*, Y, +, *TMECH Feb.* 2021 168-178

- Adaptive Output Feedback Control of Steer-by-Wire Systems With Event-Triggered Communication. *Ma*, *B*., +, *TMECH Aug. 2021 1968-1979*
- Adaptive Robust Finite-Time Nonlinear Control of a Typical Autonomous Underwater Vehicle With Saturated Inputs and Uncertainties. Sedghi, F, +, TMECH Oct. 2021 2517-2527
- An Output Feedback Based Robust Saturated Controller Design for Pavement Sweeping Self-Reconfigurable Robot. Rayguru, M.M., +, TMECH June 2021 1236-1247
- Asymptotic Tracking Control of Mechanical Servosystems With Mismatched Uncertainties. *Deng, W.*, +, *TMECH Aug. 2021 2204-2214*
- Finite-Time Synchronization Control for Bilateral Teleoperation Systems With Asymmetric Time-Varying Delay and Input Dead Zone. *Bao, J.*, +, *TMECH June 2021 1570-1580*
- Fractional-Order Control for Uncertain Teleoperated Cyber-Physical System With Actuator Fault. *Ma*, *Z*., +, *TMECH Oct.* 2021 2472-2482
- Practical Terminal Sliding Mode Control of Nonlinear Uncertain Active Suspension Systems With Adaptive Disturbance Observer. *Wang, G.*, +, *TMECH April 2021* 789-797
- Proportional-Integral Approximation-Free Control of Robotic Systems With Unknown Dynamics. Zhang, C., +, TMECH Aug. 2021 2226-2236
- Quasi-Synchronization Control of Multiple Electrohydraulic Actuators With Load Disturbance and Uncertain Parameters. *Guo, Q.*, +, *TMECH Aug.* 2021 2048-2058
- Robust Adaptive Tracking Control of Underwater Vehicles: Design, Stability Analysis, and Experiments. *Tijjani, A.S.*, +, *TMECH April 2021 897-907*
- Sliding-Mode-Disturbance-Observer-Based Robust Tracking Control for Omnidirectional Mobile Robots With Kinematic and Dynamic Uncertainties. Jeong, S., +, TMECH April 2021 741-752
- Takagi–Sugeno Fuzzy-Based Robust $H\infty$ Integrated Lane-Keeping and Direct Yaw Moment Controller of Unmanned Electric Vehicles. *Guo*, *J.*, +, *TMECH Aug. 2021 2151-2162*
- Whole-Body Control of an Autonomous Mobile Manipulator Using Series Elastic Actuators. *Liu*, *Y*., +, *TMECH April 2021 657-667*

Uncertainty

- An Adaptive Fuzzy Trajectory Tracking Control via Improved Cerebellar Model Articulation Controller for Electro-Hydraulic Shovel. *Fan, R.*, +, *TMECH Dec. 2021 2870-2880*
- Artificial-Delay Adaptive Control for Underactuated Euler–Lagrange Robotics. Roy, S., +, TMECH Dec. 2021 3064-3075
- Constrained Surrogate-Based Engine Calibration Using Lower Confidence Bound. Pal, A., +, TMECH Dec. 2021 3116-3127

Unmanned aerial vehicles

- Coordinated Trajectory-Tracking Control of a Marine Aerial-Surface Heterogeneous System. Wang, N., +, TMECH Dec. 2021 3198-3210
- Guest Editorial Focused Section on Mechatronics in Unmanned Systems. He, W., +, TMECH April 2021 595-599

Unsupervised learning

- A Two-Stage Transfer Adversarial Network for Intelligent Fault Diagnosis of Rotating Machinery With Multiple New Faults. *Li*, *J.*, +, *TMECH June* 2021 1591-1601
- Intelligent Fault Diagnosis of a Reciprocating Compressor Using Mode Isolation Convolutional Deep Belief Networks. *Zhang, Y.*, +, *TMECH June* 2021 1668-1677
- Unsupervised Cross-Domain Fault Diagnosis Using Feature Representation Alignment Networks for Rotating Machinery. *Chen, J.*, +, *TMECH Oct.* 2021 2770-2781

Upper bound

Artificial-Delay Adaptive Control for Underactuated Euler–Lagrange Robotics. *Roy, S.*, +, *TMECH Dec. 2021 3064-3075*

Valves

A Method for Mass Flow and Displacement Estimation in a Pneumatic Actuation System Using Valve-Based Pressure Sensing. Vailati, L.G., +, TMECH Feb. 2021 235-245

V

- Integral Sliding-Mode Tracking Control for Heavy Vehicle Electrohydraulic Power Steering System. *Du*, *H*., +, *TMECH June 2021 1455-1466*
- Localized Property Design and Gradient Processing of a Hydraulic Valve Body Using Selective Laser Melting. *Zhu, Y.*, +, *TMECH April 2021 1151-1160*
- Novel Structure for Waveform Control of Twin Rotary Flowrate Valve Controlled Vibration Exciter. *Wang, T.*, +, *TMECH April 2021 1183-1188*

Variable structure systems

- A Novel Rotational Actuator With Variable Stiffness Using S-Shaped Springs. Xu, Y, +, TMECH Aug. 2021 2249-2260
- Adaptive Output Feedback Control of Steer-by-Wire Systems With Event-Triggered Communication. *Ma*, *B*., +, *TMECH Aug. 2021 1968-1979*
- Adaptive Robust Finite-Time Nonlinear Control of a Typical Autonomous Underwater Vehicle With Saturated Inputs and Uncertainties. *Sedghi, F.,* +, *TMECH Oct. 2021 2517-2527*
- Analytical Design and Experimental Verification of Geofencing Control for Aerial Applications. *Ghaffari*, A., *TMECH April 2021 1106-1117*
- Autonomous Vision-Guided Object Collection From Water Surfaces With a Customized Multirotor. *Mishra*, S., +, *TMECH Aug*. 2021 1914-1922
- Efficient Cooperative Structured Control for a Multijoint Biomimetic Robotic Fish. Yan, S., +, TMECH Oct. 2021 2506-2516
- Fractional-Order Control for Uncertain Teleoperated Cyber-Physical System With Actuator Fault. *Ma*, *Z*., +, *TMECH Oct. 2021 2472-2482*
- Practical Terminal Sliding Mode Control of Nonlinear Uncertain Active Suspension Systems With Adaptive Disturbance Observer. *Wang, G.*, +, *TMECH April 2021 789-797*
- Precise Linear-Motor Synchronization Control via Cross-Coupled Second-Order Discrete-Time Fractional-Order Sliding Mode. *Kuang*, Z., +, *TMECH Feb. 2021 358-368*
- Quasi-Synchronization Control of Multiple Electrohydraulic Actuators With Load Disturbance and Uncertain Parameters. *Guo, Q.*, +, *TMECH Aug.* 2021 2048-2058
- Robust Adaptive Tracking Control of Underwater Vehicles: Design, Stability Analysis, and Experiments. *Tijjani, A.S.*, +, *TMECH April 2021 897-907*
- Sliding Mode Control With Model-Based Switching Functions Applied on a 7-DOF Exoskeleton Arm. *Fallaha*, C., +, *TMECH Feb. 2021 539-550*
- Sliding-Mode-Disturbance-Observer-Based Robust Tracking Control for Omnidirectional Mobile Robots With Kinematic and Dynamic Uncertainties. *Jeong, S.*, +, *TMECH April 2021 741-752*
- Tracking Accuracy Improvement Based on Adaptive Nonlinear Sliding Mode Control. *Tsai*, W., +, *TMECH Feb. 2021 179-190*

Vehicle dynamics

- A Tilting-Rotor Unmanned Aerial Vehicle for Enhanced Aerial Locomotion and Manipulation Capabilities: Design, Control, and Applications. *Ding, C.*, +, *TMECH Aug. 2021 2237-2248*
- Adaptive Finite-Time Control for Half-Vehicle Active Suspension Systems With Uncertain Dynamics. *Liu, Y., +, TMECH Feb. 2021 168-178*
- Adaptive Output Feedback Control of Steer-by-Wire Systems With Event-Triggered Communication. *Ma*, *B*., +, *TMECH Aug. 2021 1968-1979*
- Artificial-Delay Adaptive Control for Underactuated Euler–Lagrange Robotics. Roy, S., +, TMECH Dec. 2021 3064-3075
- Coordinated Trajectory-Tracking Control of a Marine Aerial-Surface Heterogeneous System. Wang, N., +, TMECH Dec. 2021 3198-3210
- Design and Control of Soft Unmanned Aerial Vehicle "S-CLOUD". Song, S.H., +, TMECH Feb. 2021 267-275
- Development and Performance Enhancement of an Overactuated Autonomous Ground Vehicle. *Huang, Y., +, TMECH Feb. 2021 33-44*
- Dimensionless Model-Based System Tracking Via Augmented Kalman Filter for Multiscale Unmanned Ground Vehicles. *Sun, C.*, +, *TMECH April* 2021 600-610

- Dynamic State Estimation and Control of a Heavy Tractor–Trailers Vehicle. *Zhou, S.,* +, *TMECH June 2021 1467-1478*
- Guest Editorial Focused Section on Mechatronics in Unmanned Systems. *He, W.*, +, *TMECH April 2021 595-599*
- Individual Auxiliary and Fault-Tolerant Control of Steer-by-Wire System Considering Different Drivers Steering Characteristics. *Zhao, W.*, +, *TMECH June 2021 1558-1569*
- Modeling and Motion Control of Industrial Tractor–Trailers Vehicles Using Force Compensation. Zhao, H., +, TMECH April 2021 645-656
- MPC-Based Haptic Shared Steering System: A Driver Modeling Approach for Symbiotic Driving. *Lazcano*, A.M., +, *TMECH June 2021 1201-1211*
- Multimodal Dynamics Analysis and Control for Amphibious Fly-Drive Vehicle. *Tan, Q.*, +, *TMECH April 2021 621-632*
- Nonlinear Model Predictive Control for Integrated Energy-Efficient Torque-Vectoring and Anti-Roll Moment Distribution. *Dalboni, M.*, +, *TMECH June 2021 1212-1224*
- Quasi-LPV Interconnected Observer Design for Full Vehicle Dynamics Estimation With Hardware Experiments. *Fouka*, M., +, *TMECH Aug. 2021* 1763-1772
- Semiactively Controllable Vehicle Seat Suspension System With Negative Stiffness Magnetic Spring. *Tu, L.*, +, *TMECH Feb. 2021 156-167*
- Simultaneous State Estimation and Tire Model Learning for Autonomous Vehicle Applications. Jeon, W., +, TMECH Aug. 2021 1941-1950
- Takagi–Sugeno Fuzzy Unknown Input Observers to Estimate Nonlinear Dynamics of Autonomous Ground Vehicles: Theory and Real-Time Verification. Nguyen, A., +, TMECH June 2021 1328-1338

Vehicles

MPC-Based Haptic Shared Steering System: A Driver Modeling Approach for Symbiotic Driving. Lazcano, A.M., +, TMECH June 2021 1201-1211

Velocity control

- Experimental Investigation on Control of an Infinitely Variable Transmission System for Tidal Current Energy Converters. Li, G., +, TMECH Aug. 2021 1960-1967
- Online Compensation of Mechanical Load Defects With Composite Control in PMSM Drives. *Kommuri, S.K.*, +, *TMECH June 2021 1392-1400*

Swing-Reducing Flight Control System for an Underactuated Indoor Miniature Autonomous Blimp. *Tao*, Q., +, *TMECH Aug. 2021 1895-1904*

Vibration control

- Mechanism and Controller Design of a Transfemoral Prosthesis With Electrohydraulic Knee and Motor-Driven Ankle. *Gao, S.*, +, *TMECH Oct. 2021* 2429-2439
- Model-Free Control of Flexible Manipulator Based on Intrinsic Design. Jiang, N., +, TMECH Oct. 2021 2641-2652
- Nontarget-Based Measurement of 6-DOF Structural Displacement Using Combined RGB Color and Depth Information. *Lee, S.*, +, *TMECH June* 2021 1358-1368
- Novel Structure for Waveform Control of Twin Rotary Flowrate Valve Controlled Vibration Exciter. *Wang, T., +, TMECH April 2021 1183-1188*
- Optimization of Generalized S-Curve Trajectories for Residual Vibration Suppression and Compliance With Kinematic Bounds. *Biagiotti, L.*, +, *TMECH Oct. 2021 2724-2734*
- Semiactively Controllable Vehicle Seat Suspension System With Negative Stiffness Magnetic Spring. *Tu, L.*, +, *TMECH Feb. 2021 156-167*
- Vibration Reduction of Flexible Rope-Driven Mobile Robot for Safe Façade Operation. Seo, M., +, TMECH Aug. 2021 1812-1819

Vibration isolation

- Semiactively Controllable Vehicle Seat Suspension System With Negative Stiffness Magnetic Spring. *Tu, L.*, +, *TMECH Feb. 2021 156-167*
- Shock Isolation Capability of an Electromagnetic Variable Stiffness Isolator With Bidirectional Stiffness Regulation. *Zhao, J.*, +, *TMECH Aug. 2021* 2038-2047

Vibrations

An Investigation Into Fault Diagnosis of Planetary Gearboxes Using A Bispectrum Convolutional Neural Network. *Pang, X.*, +, *TMECH Aug.* 2021 2027-2037

Data-Driven Iterative Trajectory Shaping for Precision Control of Flexible Feed Drives. *Dumanli, A.*, +, *TMECH Oct. 2021 2735-2746*

- Design and Experimental Validation of a Novel High-Speed Omnidirectional Underwater Propulsion Mechanism. *Njaka, T., +, TMECH Oct. 2021* 2339-2349
- Generative Adversarial Network for Prediction of Workpiece Surface Topography in Machining Stage. Cao, L., +, TMECH Feb. 2021 480-490
- Intelligent Fault Diagnosis of a Reciprocating Compressor Using Mode Isolation Convolutional Deep Belief Networks. *Zhang, Y.*, +, *TMECH June* 2021 1668-1677
- MEMS-Enabled Retrofitting of Automobile Wheel Balancer for Automatic Unbalance Detection. *Pozzato, G.,* +, *TMECH April 2021 830-840*
- Model-Free Control of Flexible Manipulator Based on Intrinsic Design. Jiang, N., +, TMECH Oct. 2021 2641-2652
- Multimodal Dynamics Analysis and Control for Amphibious Fly-Drive Vehicle. *Tan, Q.*, +, *TMECH April 2021 621-632*
- Novel Structure for Waveform Control of Twin Rotary Flowrate Valve Controlled Vibration Exciter. *Wang*, *T.*, +, *TMECH April 2021 1183-1188*
- Pulling Illusion Based on the Phase Difference of the Frequency Components of Asymmetric Vibrations. *Tanabe, T.*, +, *TMECH Feb. 2021 203-213*
- Rotor Balancing for Magnetically Levitated TMPs Integrated With Vibration Self-Sensing of Magnetic Bearings. *Zheng, S.*, +, *TMECH Dec. 2021* 3031-3039
- Shock Isolation Capability of an Electromagnetic Variable Stiffness Isolator With Bidirectional Stiffness Regulation. *Zhao, J.*, +, *TMECH Aug. 2021* 2038-2047
- Stability and Sommerfeld Effect of a Vibrating System With Two Vibrators Driven Separately by Induction Motors. *Zhang, X.*, +, *TMECH April 2021* 807-817
- Structural Failure Detection Using Wireless Transmission Rate From Piezoelectric Energy Harvesters. Jung, H.J., +, TMECH Aug. 2021 1708-1718
- Vibration Reduction of Flexible Rope-Driven Mobile Robot for Safe Façade Operation. Seo, M., +, TMECH Aug. 2021 1812-1819
- Weighted Entropy Minimization Based Deep Conditional Adversarial Diagnosis Approach Under Variable Working Conditions. She, D., +, TMECH Oct. 2021 2440-2450

Video signal processing

- Efficient Anomaly Detection in a Laser-Surface Heat-Treatment Process via Laser-Spot Tracking. *Atienza*, D., +, *TMECH Feb. 2021 405-415*
- Iterative Learning Control for Video-Rate Atomic Force Microscopy. Nikooienejad, N., +, TMECH Aug. 2021 2127-2138

Virtual prototyping

Kinematic Modeling, Analysis, and Verification of an Essboard-Like Robot. *Guan, Y.*, +, *TMECH April 2021 864-875*

Virtual reality

- Design and Rapid Construction of a Cost-Effective Virtual Haptic Device. Wang, F, +, TMECH Feb. 2021 66-77
- Pulling Illusion Based on the Phase Difference of the Frequency Components of Asymmetric Vibrations. *Tanabe, T., +, TMECH Feb. 2021 203-213*

Viscoelasticity

- Design and Characterization of a Bellows-Driven Soft Pneumatic Actuator. *Hashem, R.*, +, *TMECH Oct. 2021 2327-2338*
- Identification of a Nonlinear Dielectric Elastomer Actuator Based on the Harmonic Balance Method. *Bernat, J.*, +, *TMECH Oct. 2021 2664-2675*

Vision

Automated Retinal Vein Cannulation on Silicone Phantoms Using Optical-Coherence-Tomography-Guided Robotic Manipulations. *Gerber, M.J.*, +, *TMECH Oct. 2021 2758-2769*

Visual perception

Pulling Illusion Based on the Phase Difference of the Frequency Components of Asymmetric Vibrations. *Tanabe, T.*, +, *TMECH Feb. 2021 203-213*

Visual servoing

- A Visual Servo-Based Predictive Control With Echo State Gaussian Process for Soft Bending Actuator. *Cao, Y.*, +, *TMECH Feb. 2021 574-585*
- Autonomous Navigation of Magnetic Microrobots in a Large Workspace Using Mobile-Coil System. Yang, Z., +, TMECH Dec. 2021 3163-3174

Globally Optimal Symbolic Hand-Eye Calibration. *Wu, J.*, +, *TMECH June* 2021 1369-1379

Robust Nonlinear Model Predictive Control Based Visual Servoing of Quadrotor UAVs. *Zhang, K., +, TMECH April 2021 700-708*

Visualization

OrthographicNet: A Deep Transfer Learning Approach for 3-D Object Recognition in Open-Ended Domains. *Kasaei, S.H., TMECH Dec. 2021 2910-2921*

Radial Coverage Strength for Optimization of Monocular Multicamera Deployment. Lei, Z., +, TMECH Dec. 2021 3221-3231

Voltage control

Development of FW and MTPV Control for SynRM via Feedforward Voltage Angle Control. *Chen, S.*, +, *TMECH Dec. 2021 3254-3264*

W

Wearable computers

Design, Modeling, and Experiments of Electromagnetic Energy Harvester Embedded in Smart Watch and Wristband as Power Source. *Cai, M.*, +, *TMECH Aug. 2021 2104-2114*

Wearable robots

- Dynamic Modeling and State Estimation of Cable-Conduit Actuation During Interaction With Nonpassive Environments. *Buchanan, S.*, +, *TMECH Oct.* 2021 2462-2471
- Low Impedance-Guaranteed Gain-Scheduled GESO for Torque-Controlled VSA With Application of Exoskeleton-Assisted Sit-to-Stand. *Liu, L.*, +, *TMECH Aug. 2021 2080-2091*
- Otariidae-Inspired Soft-Robotic Supernumerary Flippers by Fabric Kirigami and Origami. *Liu, S.*, +, *TMECH Oct. 2021 2747-2757*
- Slider-Tendon Linear Actuator With Under-Actuation and Fast-Connection for Soft Wearable Robots. *Kim, B.,* +, *TMECH Dec. 2021 2932-2943*

Thermal Modeling and Characterization of Twisted Coiled Actuators for Upper Limb Wearable Devices. *Edmonds, B.P.R.*, +, *TMECH April 2021* 966-977

Wearable sensors

Characterization of a Packaged Triboelectric Harvester Under Simulated Gait Loading for Total Knee Replacement. *Hossain, N.A.*, +, *TMECH Dec.* 2021 2967-2976

Wheelchairs

Wheels

- Development and Performance Enhancement of an Overactuated Autonomous Ground Vehicle. *Huang, Y., +, TMECH Feb. 2021 33-44*
- Evaluation of Locomotion Performances for a Mecanum-Wheeled Hybrid Hexapod Robot. Orozco-Magdaleno, E.C., +, TMECH June 2021 1657-1667
- Façade Cleaning Robot With Manipulating and Sensing Devices Equipped on a Gondola. Chae, H., +, TMECH Aug. 2021 1719-1727
- Kinematic Modeling, Analysis, and Verification of an Essboard-Like Robot. *Guan, Y., +, TMECH April 2021 864-875*
- MEMS-Enabled Retrofitting of Automobile Wheel Balancer for Automatic Unbalance Detection. *Pozzato, G.*, +, *TMECH April 2021 830-840*
- MPC-Based Haptic Shared Steering System: A Driver Modeling Approach for Symbiotic Driving. *Lazcano*, A.M., +, *TMECH June 2021 1201-1211*
- Nonlinear Model Predictive Control for Integrated Energy-Efficient Torque-Vectoring and Anti-Roll Moment Distribution. *Dalboni, M.*, +, *TMECH June 2021 1212-1224*
- Roller-Skating of Mammalian Quadrupedal Robot With Passive Wheels Inspired by Human. Chen, J., +, TMECH June 2021 1624-1634
- Takagi–Sugeno Fuzzy-Based Robust $H\infty$ Integrated Lane-Keeping and Direct Yaw Moment Controller of Unmanned Electric Vehicles. *Guo*, *J.*, +, *TMECH Aug. 2021 2151-2162*

Wide band gap semiconductors

Winches

Position-Tracking Control of Dual-Rope Winch Robot With Rope Slip Compensation. *Yoo, S.*, +, *TMECH Aug. 2021 1754-1762*

Wind power plants

Efficiency Optimization Strategy for Switched Reluctance Generator System With Position Sensorless Control. *Chen, H.*, +, *TMECH Feb. 2021* 469-479

Wind tunnels

Modeling Quadrotor Dynamics in a Wind Field. Jeon, H., +, TMECH June 2021 1401-1411

Wireless sensor networks

A Lightweight Wireless Overpressure Node Based Efficient Monitoring for Shock Waves. *Gao*, S., +, *TMECH Feb*. 2021 448-457

Structural Failure Detection Using Wireless Transmission Rate From Piezoelectric Energy Harvesters. Jung, H.J., +, TMECH Aug. 2021 1708-1718

Workability

Basic Input–Output Gain Tuning System Based on Control Input Histogram Leveling for Human-Operated Machines. *Kamezaki, M.*, +, *TMECH Dec.* 2021 2857-2869

Х

XML

Automatic Construction of Three-Dimensional Ground Model by Data Processing. Takeyama, T., +, TMECH Dec. 2021 2881-2887

Y

Yield strength

Localized Property Design and Gradient Processing of a Hydraulic Valve Body Using Selective Laser Melting. *Zhu, Y.*, +, *TMECH April 2021 1151-1160*

Ζ

Zero voltage switching

Reconstructing Walking Dynamics From Two Shank-Mounted Inertial Mea-

surement Units. Li, T., +, TMECH Dec. 2021 3040-3050

Zinc compounds

Robotic Prototyping of Paper-Based Field-Effect Transistors With Rolled-Up

Semiconductor Microtubes. Dong, X., +, TMECH Feb. 2021 427-436

Zoology

Curvature-Induced Buckling for Flapping-Wing Vehicles. Sharifzadeh, M.,

+, TMECH Feb. 2021 503-514

Virtual Landmark-Based Control of Docking Support for Assistive Mobility Devices. Chen, Y, +, TMECH Aug. 2021 2007-2015

Robotic Prototyping of Paper-Based Field-Effect Transistors With Rolled-Up Semiconductor Microtubes. *Dong, X.*, +, *TMECH Feb. 2021 427-436*