# 2019 Index IEEE Transactions on Systems, Man, and Cybernetics: Systems Vol. 49

This index covers all technical items—papers, correspondence, reviews, etc.—that appeared in this periodical during 2019, and items from previous years that were commented upon or corrected in 2019. Departments and other items may also be covered if they have been judged to have archival value.

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- Automated Model Construction for Combined Sewer Overflow Prediction Based on Efficient LASSO Algorithm. *Zhao, W.*, +, *TSMC June 2019* 1254-1269
- The MR-CA Models for Analysis of Pollution Sources and Prediction of PM<sub>2.5</sub>. *Deng, F.*, +, *TSMC April 2019 814-820*

### Air pollution control

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- Reliable Tracking Control for Under-Actuated Quadrotors With Wind Disturbances. Xu, J., +, TSMC Oct. 2019 2059-2070

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- Adaptive Neural Backstepping Control Design for A Class of Nonsmooth Nonlinear Systems. *Zhao, X.*, +, *TSMC Sept. 2019 1820-1831*
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#### Artificial bee colony algorithm

Two-Level Master–Slave RFID Networks Planning via Hybrid Multiobjective Artificial Bee Colony Optimizer. *Ma*, *L.*, +, *TSMC May 2019 861-880* Artificial neural networks

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## Attitude control

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## Authentication

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Output Feedback Stabilization for an Axially Moving System. Zhao, Z., +, TSMC Dec. 2019 2374-2383

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## **Battery powered vehicles**

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## Bending

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Cancer detection

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## Cognitive systems

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## Μ

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## **Pneumatic actuators**

Trajectory Tracking Control of a One Degree of Freedom Manipulator Based on a Switched Sliding Mode Controller With a Novel Extended State Observer Framework. Zhao, L., +, TSMC June 2019 1110-1118

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#### Power distribution economics

Planning and Operation of Parking Lots Considering System, Traffic, and Drivers Behavioral Model. Rahmani-Andebili, M., +, TSMC Sept. 2019 1879-1892

## Power distribution planning

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# Power markets

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#### **Production management**

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#### Semiconductor industry

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Stability

- A Dynamic Neural Network Approach for Efficient Control of Manipulators. Li, S., +, TSMC May 2019 932-941
- A Paradigm for Path Following Control of a Ribbon-Fin Propelled Biomimetic Underwater Vehicle. Wang, R., +, TSMC March 2019 482-493
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