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This index covers all technical items—papers, correspondence, reviews, etc.—that appeared in this periodical during 2020, and items from previous years that were commented upon or corrected in 2020. Departments and other items may also be covered if they have been judged to have archival value.

The Author Index contains the primary entry for each item, listed under the first author's name. The primary entry includes the coauthors' names, the title of the paper or other item, and its location, specified by the publication abbreviation, year, month, and inclusive pagination. The Subject Index contains entries describing the item under all appropriate subject headings, plus the first author's name, the publication abbreviation, month, and year, and inclusive pages. Note that the item title is found only under the primary entry in the Author Index.

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- A Hybrid Compact Neural Architecture for Visual Place Recognition. *Chancan, M., +, LRA April 2020 993-1000*
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- Braking**
Wide Area Exploration System Using Passive-Follower Robots Towed by Multiple Winches. *Luces, J.V.S., +, LRA Oct. 2020 6459-6466*
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- Cables (mechanical)**
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- Intrinsic Calibration of an Eye-In-Hand 2D LiDAR Sensor in Unstructured Environments Using ICP. *Peters, A., +, LRA April 2020 929-936*
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- Investigation of a Hybrid Kinematic Calibration Method for the “Sina” Surgical Robot. *Alamdar, A., +, LRA Oct. 2020 5276-5282*
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- Ultra-Thin Joint Torque Sensor With Enhanced Sensitivity for Robotic Application. *Seok, D., +, LRA Oct. 2020 5873-5880*
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- An Experimental Comparison Towards Autonomous Camera Navigation to Optimize Training in Robot Assisted Surgery. *Mariani, A., +, LRA April 2020 1461-1467*
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- Model-Based Robotic Cell Aspiration: Tackling Nonlinear Dynamics and Varying Cell Sizes. *Shan, G., +, LRA Jan. 2020 173-178*
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- Centralized control**
- Scalable Cooperative Transport of Cable-Suspended Loads With UAVs Using Distributed Trajectory Optimization. *Jackson, B.E., +, LRA April 2020 3368-3374*
- Chains**
- Strategy for Roller Chain Assembly With Parallel Jaw Gripper. *Tatemura, K., +, LRA April 2020 2435-2442*
- Channel flow**
- Soft Inductive Tactile Sensor Using Flow-Channel Enclosing Liquid Metal. *Hamaguchi, S., +, LRA July 2020 4028-4034*
- Chaos**
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- Chirality**
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- Climbing robots**
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- Closed loop systems**
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- Lyapunov-Stable Orientation Estimator for Humanoid Robots. *benallegue, M., +, LRA Oct. 2020 6371-6378*
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Image annotation

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Addressing the Sim2Real Gap in Robotic 3-D Object Classification. *Weibel, J., +, LRA April 2020 407-413*

AMAE: Adaptive Motion-Agnostic Encoder for Event-Based Object Classification. *Deng, Y., +, LRA July 2020 4596-4603*

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CNN Based Road User Detection Using the 3D Radar Cube. *Palfy, A., +, LRA April 2020 1263-1270*

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Image sensors

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